

## PREFACE

This effort was conducted by The University of Kentucky under the sponsorship of the Rome Air Development Center Post-Doctoral Program for RADC's Compatibility Branch. Mr. Jim Brodock of RADC was the task project engineer and provided overall technical direction and guidance.

The RADC Post-Doctoral Program is a cooperative venture between RADC and some sixty-five universities eligible to participate in the program. Syracuse University (Department of Electrical Engineering), Purdue University (School of Electrical Engineering), Georgia Institute of Technology (School of Electrical Engineering), and State University of New York at Buffalo (Department of Electrical Engineering) act as prime contractor schools with other schools participating via sub-contracts with the prime schools. The U.S. Air Force Academy (Department of Electrical Engineering), Air Force Institute of Technology (Department of Electrical Engineering), and the Naval Post Graduate School (Department of Electrical Engineering) also participate in the program.

The Post-Doctoral Program provides an opportunity for faculty at participating universities to spend up to one year full time on exploratory development and problem-solving efforts with the post-doctorals splitting their time between the customer location and their educational institutions. The program is totally customer-funded with current projects being undertaken for Rome Air Development Center (RADC), Space and Missile Systems Organization (SAMSO), Aeronautical Systems Division (ASD), Electronics Systems Division (ESD), Air Force Avionics Laboratory (AFAL), Foreign Technology Division (FTD), Air Force Weapons Laboratory (AFWL), Armament Development and Test Center (ADTC), Air Force Communications Service (AFCS), Aerospace Defense

Command (ADC), Hq USAF, Defense Communications Agency (DCA), Navy, Army, Aerospace Medical Division (AMD), and Federal Aviation Administration (FAA).

Further information about the RADC Post-Doctoral Program can be obtained from Mr. Jacob Scherer, RADC/RBC, Griffiss AFB, NY, 13441, telephone Autovon 587-2543, commercial (315) 330-2543.

The author of this report is Clayton R. Paul. He received the BSEE degree from The Citadel (1963), the MSEE degree from Georgia Institute of Technology (1964), and the Ph.D. degree from Purdue University (1970). He is currently an Associate Professor with the Department of Electrical Engineering, University of Kentucky, Lexington, Kentucky 40506.

The author wishes to acknowledge the capable efforts of Ms. Donna Toon in typing this manuscript.

## TABLE OF CONTENTS

	<u>Page</u>
I. INTRODUCTION -----	1
II. FORMULATION OF THE MULTICONDUCTOR TRANSMISSION LINE EQUATIONS -----	3
2.1 The Multiconductor Transmission Line Model -----	3
2.2 The Equations to be Programmed -----	14
2.3 Formulation of the Terminal Network Equations -----	22
2.4 Common Impedance Coupling and the Calculation of Conductor Self Impedances -----	28
2.5 Computation of the Per-Unit-Length Inductance and Capacitance Matrices -----	36
2.5.1 Transmission Lines Consisting of Perfect Conductors in a Lossless, Homogeneous Medium, XTALK -----	36
2.5.2 Transmission Lines Consisting of Imperfect (Lossy) Conductors in a Lossless, Homogeneous Medium, XTALK2 -----	41
2.5.3 Transmission Lines Consisting of Perfect Conductors in a Lossless, Inhomogeneous Medium, FLATPAK -----	42
2.5.4 Transmission Lines Consisting of Imperfect (Lossy) Conductors in a Lossless, Inhomogeneous Medium, FLATPAK2 -----	44
III. PROGRAM CODE DESCRIPTIONS -----	46
3.1 Program XTALK -----	46
3.2 Program XTALK2 -----	50
3.3 Program FLATPAK -----	53
3.4 Program FLATPAK2 -----	56
3.5 Required Subroutines -----	59
3.5.1 Subroutine LEQT1C -----	59
3.5.2 Subroutine EIGCC -----	61

	3.5.3 Subroutines NROOT and EIGEN -----	62
IV.	USER'S MANUAL -----	65
	4.1 The Frequency Cards, Group III -----	65
	4.2 The Termination Network Characterization Cards, Group II -----	68
	4.3 Program XTALK -----	73
	4.4 Program XTALK2 -----	77
	4.5 Program FLATPAK -----	79
	4.6 Program FLATPAK2 -----	83
	4.7 Examples of Program Useage -----	83
	4.7.1 Examples of the XTALK Program -----	85
	4.7.2 Examples of the XTALK2 Program -----	85
	4.7.3 Examples of the FLATPAK Program -----	86
	4.7.4 Examples of the FLATPAK2 Program -----	86
V.	SUMMARY -----	119
	REFERENCES -----	120
	APPENDIX A -----	123
	APPENDIX B -----	133
	APPENDIX C -----	145
	APPENDIX D -----	152
	APPENDIX E -----	163
	APPENDIX F -----	167

LIST OF ILLUSTRATIONS

<u>FIGURE</u>		<u>PAGE</u>
2-1	An (n+1) conductor, uniform transmission line.	
	Sheet 1 of 2 -----	5
	Sheet 2 of 2 -----	6
2-2	The per-unit-length equivalent circuit. -----	7
2-3	The termination networks. -----	11
2-4	Example termination networks. -----	23
2-5	Example termination networks. -----	26
2-6	Illustration of common impedance coupling. -----	30
2-7	Conductor dimensions for calculating common impedance. -----	33
2-8	Lines in a homogeneous medium. -----	37
2-9	An (n+1) wire ribbon (flatpack) cable. -----	43
4-1	Type 1 structure. -----	74
4-2	Type 2 structure. -----	75
4-3	Type 3 structure. -----	76
4-4	Wire numbering for ribbon (flatpack) cables. -----	81
4-5	Input Cards, XTALK, Example 1. -----	87
4-6	Input Cards, XTALK, Example 2. -----	88
4-7	Input Cards, XTALK, Example 3. -----	89
4-8	Input Cards, XTALK, Example 4. -----	90
4-9	Output Listing, XTALK, Example 1. -----	91
4-10	Output Listing, XTALK, Example 2. -----	92
4-11	Output Listing, XTALK, Example 3. -----	93
4-12	Output Listing, XTALK, Example 4. -----	94
4-13	Input Cards, XTALK2, Example 1. -----	95

4-14	Input Cards, XTALK2, Example 2.-----	96
4-15	Input Cards, XTALK2, Example 3.-----	97
4-16	Input Cards, XTALK2, Example 4.-----	98
4-17	Output Listing, XTALK2, Example 1.-----	99
4-18	Output Listing, XTALK2, Example 2.-----	100
4-19	Output Listing, XTALK2, Example 3.-----	101
4-20	Output Listing, XTALK2, Example 4.-----	102
4-21	Input Cards, FLATPAK, Example 1.-----	103
4-22	Input Cards, FLATPAK, Example 2.-----	104
4-23	Input Cards, FLATPAK, Example 3.-----	105
4-24	Input Cards, FLATPAK, Example 4.-----	106
4-25	Output Listing, FLATPAK, Example 1.-----	107
4-26	Output Listing, FLATPAK, Example 2.-----	108
4-27	Output Listing, FLATPAK, Example 3.-----	109
4-28	Output Listing, FLATPAK, Example 4.-----	110
4-29	Input Cards, FLATPAK2,Example 1.-----	111
4-30	Input Cards, FLATPAK2,Example 2.-----	112
4-31	Input Cards, FLATPAK2,Example 3.-----	113
4-32	Input Cards, FLATPAK2,Example 4.-----	114
4-33	Output Listing, FLATPAK2, Example 1.-----	115
4-34	Output Listing, FLATPAK2, Example 2.-----	116
4-35	Output Listing, FLATPAK2, Example 3.-----	117
4-36	Output Listing, FLATPAK2, Example 4.-----	118

## I. INTRODUCTION

This report is the seventh in a seven volume series documenting the Application of Multiconductor Transmission Line Theory to the Prediction of Cable Coupling. The purpose of this report is to implement the analytical techniques described in Volume I of this series [1] in the form of digital computer programs.

Crosstalk or electromagnetic coupling between wires (cylindrical conductors) in densely packed cable bundles can be a serious contributor to the degradation in performance of modern electronic systems. A recently developed digital computer program, IEMCAP, provides a general analysis capability for determining overall electromagnetic compatibility of aircraft, ground and spacecraft systems [3]. The computer programs described in this report are intended to provide a supplement to the analysis capabilities of IEMCAP by providing a more fine-grained analysis of wire-coupled interference.

IEMCAP is intended to be used to model all recognizable coupling paths on aircraft, ground and spacecraft systems. By virtue of the large size and complexity of many of these systems, detailed modeling of the coupling paths is not feasible in a program such as IEMCAP. To avoid excessive computer run times, the models of the various coupling paths used in IEMCAP are generally quite simple and represent bounds on the coupling. Consequently, the predictions of IEMCAP are generally somewhat conservative. However, once a potential wire-coupled interference problem is pinpointed by IEMCAP, the computer programs described in this report can, in many cases, be used to determine if an actual interference situation exists and the precise level of the interference.

Four programs are described: XTALK, XTALK2, FLATPAK, and FLATPAK2.

XTALK analyzes three configurations of transmission lines: (1)  $(n+1)$  bare wires, (2)  $n$  bare wires above an infinite ground plane, and (3)  $n$  wires within a cylindrical shield which is filled with a homogeneous dielectric. All conductors are considered to be perfect conductors. XTALK2 analyzes the same three structural configurations as XTALK except that the conductors are considered to be imperfect conductors. FLATPAK analyzes  $(n+1)$  wire ribbon cables. All wires are assumed to be perfect conductors. FLATPAK2 analyzes the same configuration as FLATPAK except that the wires are considered to be imperfect conductors. In all of the above programs, the medium (media) surrounding the conductors is assumed to be lossless. Sinusoidal, steady-state excitation of the line is considered, i.e., the transient solution is not directly obtained. Comparison of predicted to experimental results are obtained using these programs in Volume III and Volume IV of this series [4,5].

All programs are written in FORTRAN IV Language and are double precision. Changes in the programs to convert them to single precision arithmetic will be indicated. All programs have been implemented on an IBM 370/165 computer at The University of Kentucky using the Fortran IV, G level compiler and should be easily implemented on other computers.

It is, of course, difficult if not impossible to write a general computer program which will address all types of transmission line structures which the user may wish to investigate. The four programs included in this report form an initial library of analysis capabilities for wire-coupled interference problems. Other programs which address more specific structures and structures not considered by these four programs will be documented in other volumes of this series as well as in future RADC publications as they are developed.



## II. FORMULATION OF THE MULTICONDUCTOR

### TRANSMISSION LINE (MTL) EQUATIONS

In this chapter, the distributed parameter, multiconductor transmission line (MTL) model will be described and the programmed equations will be derived. This model is exact in the sense that interactions between all conductors in the transmission line are considered, and the distributed parameter representation (assuming the TEM mode or "quasi-TEM" mode of propagation on the line) is used. The line is assumed to be uniform in the sense that all conductors are parallel to each other and there is no variation in the cross sections of the conductors or the surrounding media along the line.

#### 2.1 The Multiconductor Transmission Line (MTL) Model

The MTL model is described in detail in Volume I of this series [1] and in reference [2]. In this section, a brief review of the MTL model will be given and the reader should consult Volume I [1] or reference [2] for further details.

If the line is immersed in a homogeneous medium, e.g., bare wires in free space, the fundamental mode of propagation is the TEM (Transverse Electro-Magnetic) mode. If the line is immersed in an inhomogeneous medium, e.g., wires with cylindrical dielectric insulations surrounded by free space, the fundamental mode of propagation is taken to be the "quasi-TEM" mode. The essential difference in these two cases is as follows. For lines in a homogeneous medium the TEM mode assumption is legitimate. For lines in an inhomogeneous medium, the TEM mode cannot exist except in the limiting case of zero frequency (DC). However, for the inhomogeneous medium case, the assumption is made that the electric and magnetic fields are almost trans-

verse to the direction of propagation, i.e., the mode of propagation is almost TEM or "quasi-TEM".

With the assumption of the TEM mode or "quasi-TEM" mode of propagation, line voltages and currents may be defined. Consider a general  $(n + 1)$  conductor, uniform transmission line shown in Figure 2-1. The  $(n + 1)$ st or zero-th conductor is the reference conductor for the line voltages. For sinusoidal, steady-state excitation of the line, the line voltages,  $V_i(x, t)$ , (with respect to the reference, the zero-th, conductor) and line currents,  $I_i(x, t)$  are

$$V_i(x, t) = V_i(x) e^{j\omega t} \quad (2-1a)$$

$$I_i(x, t) = I_i(x) e^{j\omega t} \quad (2-1b)$$

for  $i = 1, \dots, n$  where  $V_i(x)$  and  $I_i(x)$  are the complex, phasor line voltages and currents and  $\omega$  is the radian frequency of excitation of the line,  $\omega = 2\pi f$ . The current in the reference conductor satisfies

$$I_0(x, t) = -\sum_{i=1}^n I_i(x, t) \quad (2-2a)$$

$$I_0(x) = -\sum_{i=1}^n I_i(x) \quad (2-2b)$$

The MTL equations can be derived from the per-unit-length equivalent circuit in Figure 2-2 and are a set of  $2n$ , complex-valued, first order, ordinary differential equations

$$\frac{d}{dx} \begin{bmatrix} \underline{V}(x) \\ \underline{I}(x) \end{bmatrix} = - \begin{bmatrix} 0 & \underline{Z} \\ \underline{Y} & 0 \end{bmatrix} \begin{bmatrix} \underline{V}(x) \\ \underline{I}(x) \end{bmatrix} + \begin{bmatrix} \underline{V}_s(x) \\ \underline{I}_s(x) \end{bmatrix} \quad (2-3)$$

A matrix  $\underline{M}$  with  $m$  rows and  $p$  columns is said to be  $m \times p$  and the element in the  $i$ -th row and  $j$ -th column is designated by  $[\underline{M}]_{ij}$  with  $i = 1, \dots, m$

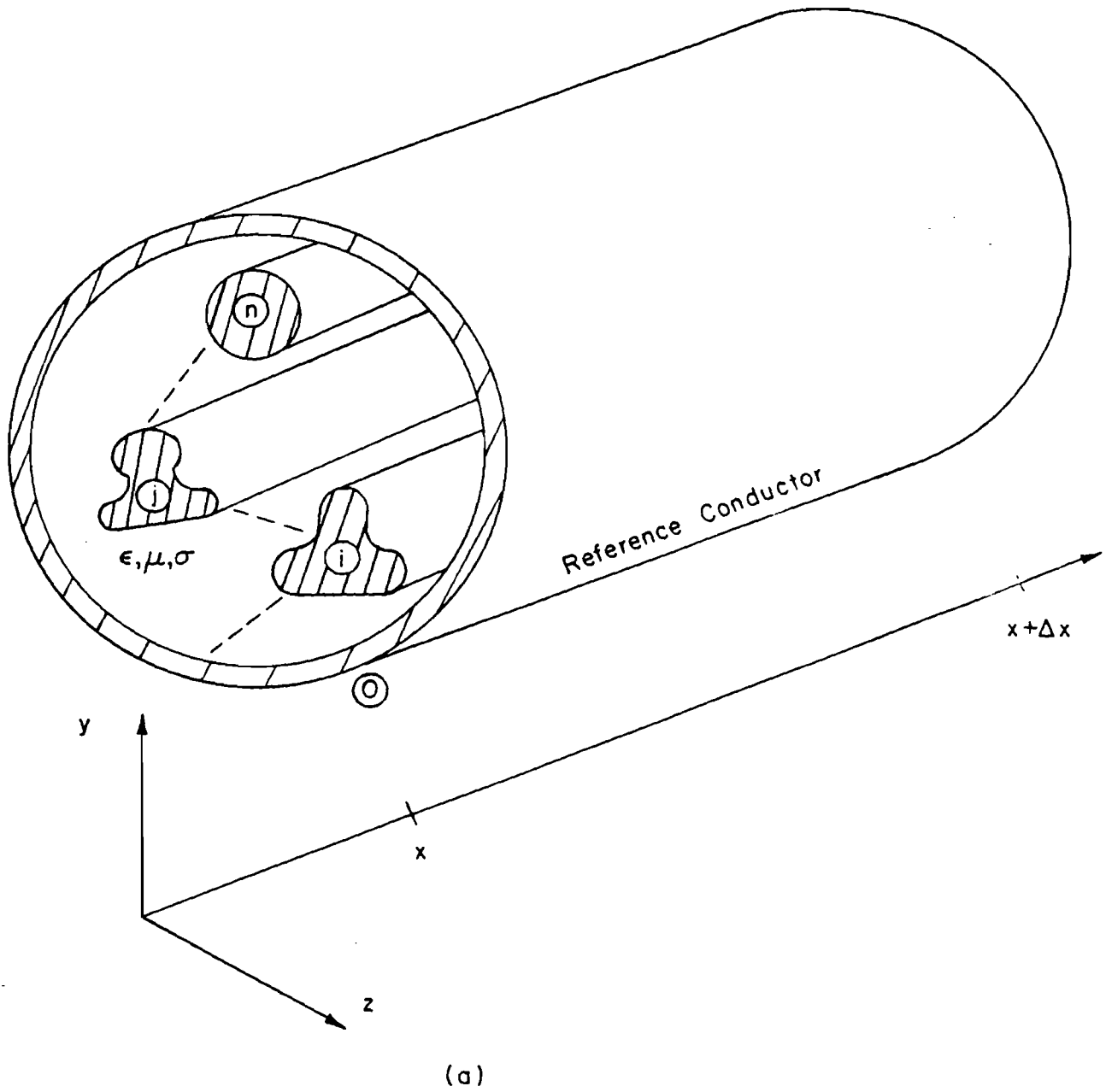
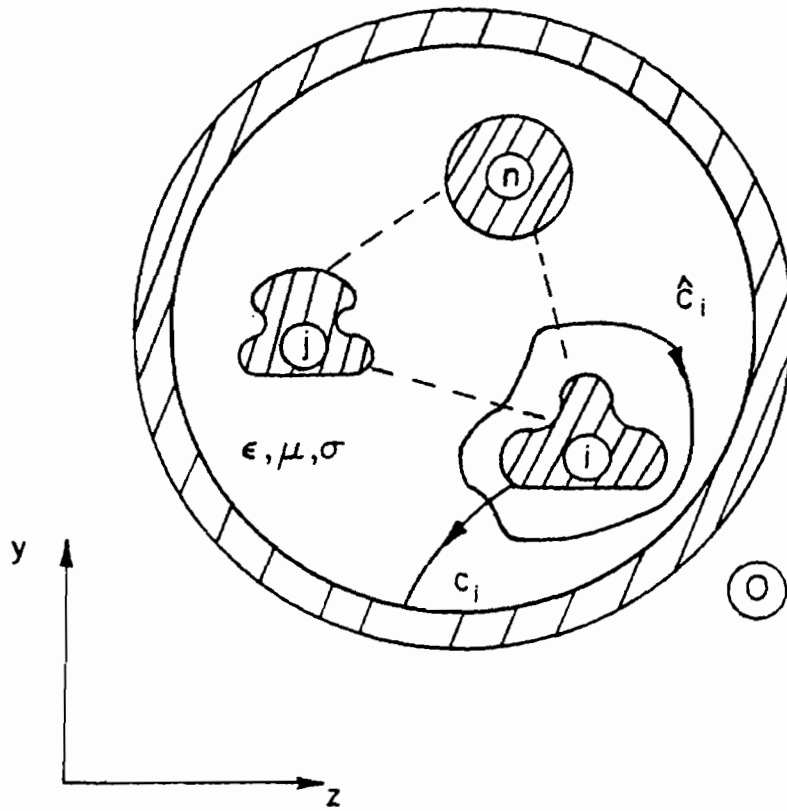
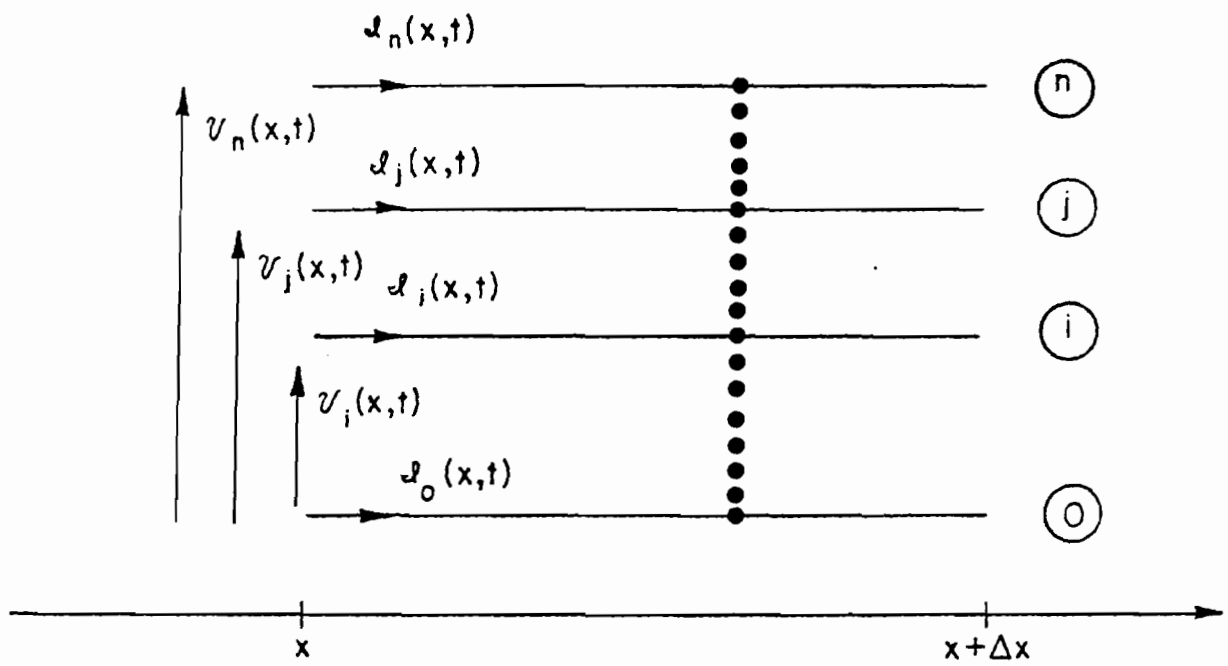


Fig. 2-1(cont.). An  $(n+1)$  conductor, uniform transmission line.



(b)



(c)

Fig. 2-1. An  $(n+1)$  conductor, uniform transmission line.

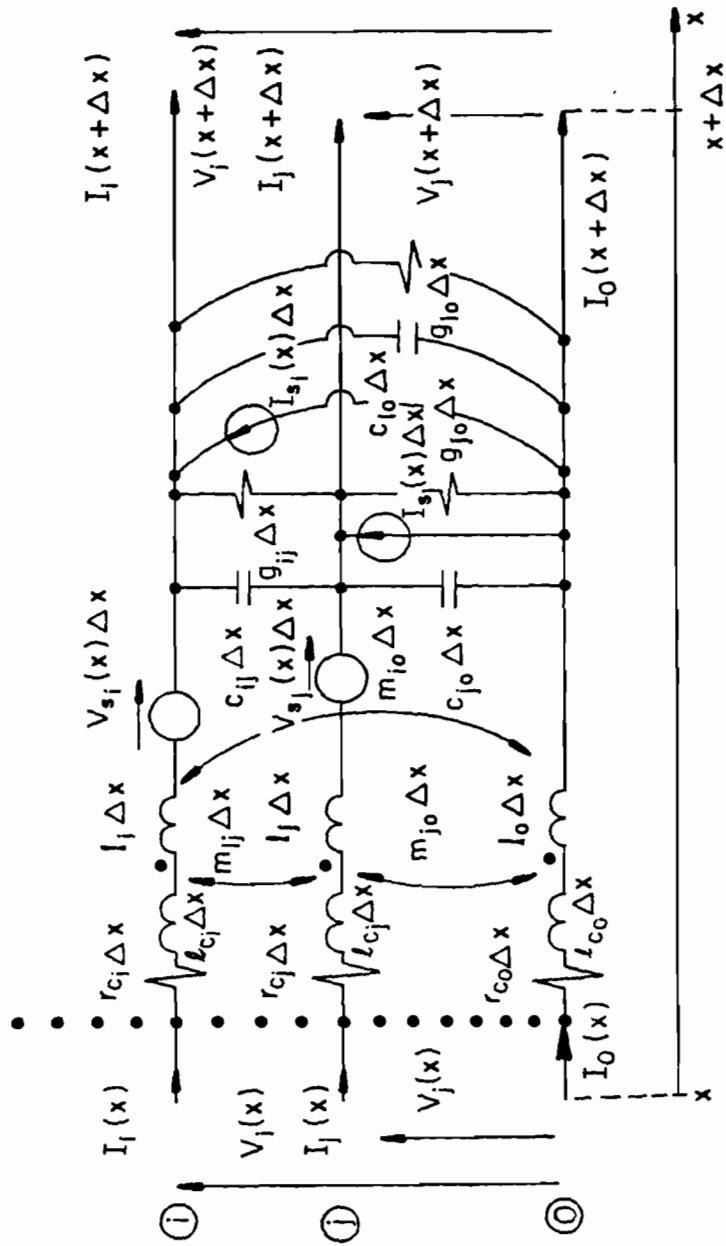


Fig. 2-2. The per-unit-length equivalent circuit.

and  $j = 1, \dots, p$ . An  $n \times 1$  vector is denoted with a bar, e.g.,  $\underline{V}$ , with the entry in the  $i$ -th row denoted by  $[\underline{V}]_i = V_i$ . The matrix  $\underline{0}_{m \times p}$  is the  $m \times p$  zero matrix with zeros in every position, i.e.,  $[\underline{0}]_{ij} = 0$  for  $i = 1, \dots, m$  and  $j = 1, \dots, p$ . The complex-valued phasor line voltages with respect to the reference conductor (the zero-th conductor),  $V_i(x)$ , and line currents,  $I_i(x)$ , are given by  $[\underline{V}(x)]_i = V_i(x)$  and  $[\underline{I}(x)]_i = I_i(x)$ .

The  $n \times n$  complex-valued, symmetric matrices,  $\underline{Z}$  and  $\underline{Y}$ , are the per-unit-length impedance and admittance matrices of the line, respectively. Since the line is assumed to be uniform, these matrices are independent of  $x$ . These per-unit-length matrices are separable as

$$\underline{Z} = \underline{R}_{\sim c} + j\omega \underline{L}_{\sim c} + j\omega \underline{L}_{\sim} \quad (2-4a)$$

$$\underline{Y} = \underline{G}_{\sim} + j\omega \underline{C}_{\sim} \quad (2-4b)$$

where the  $n \times n$  real, symmetric matrices  $\underline{R}_{\sim c}$ ,  $\underline{L}_{\sim c}$ ,  $\underline{L}_{\sim}$ ,  $\underline{G}_{\sim}$ ,  $\underline{C}_{\sim}$  are the per-unit-length conductor resistance, conductor internal inductance, external inductance, conductance and capacitance matrices, respectively. The entries in these matrices may be straightforwardly obtained in terms of the elements of the per-unit-length equivalent circuit in Figure 2-2 as

$$[\underline{R}_{\sim c}]_{ii} = r_{c_i} + r_{c_0}, \quad [\underline{R}_{\sim c}]_{ij} = r_{c_0} \quad (2-5a)$$

$$[\underline{L}_{\sim c}]_{ii} = l_{c_i} + l_{c_0}, \quad [\underline{L}_{\sim c}]_{ij} = l_{c_0} \quad (2-5b)$$

$$[\underline{L}_{\sim}]_{ii} = l_i + l_0 - 2m_{i0}, \quad [\underline{L}_{\sim}]_{ij} = l_0 + m_{ij} - m_{i0} - m_{j0} \quad (2-5c)$$

$$[\underline{G}_{\sim}]_{ii} = g_{i0} + \sum_{\substack{j=1 \\ i \neq j}}^n g_{ij}, \quad [\underline{G}_{\sim}]_{ij} = -g_{ij} \quad (2-5d)$$

$$[\tilde{C}]_{ii} = c_{i0} + \sum_{\substack{j=1 \\ i \neq j}}^n c_{ij}, \quad [\tilde{C}]_{ij} = -c_{ij}. \quad (2-5e)$$

The  $n \times 1$  column vectors,  $\underline{V}_s(x)$  and  $\underline{I}_s(x)$  contain per-unit-length equivalent voltage and current sources,  $[\underline{V}_s(x)]_i = V_{s_i}(x)$  and  $[\underline{I}_s(x)]_i = I_{s_i}(x)$ , which are included to represent the effects of the spectral components of incident electromagnetic field sources which illuminate the line. These entries are complex-valued functions of frequency and position,  $x$ , along the line. In this report, no external incident fields are considered and these sources are set equal to zero, i.e.,  $\underline{V}_s(x) = \underline{0}$  and  $\underline{I}_s(x) = \underline{0}$ .

The solution to (2-3) is

$$\begin{aligned} \begin{bmatrix} \underline{V}(x) \\ \underline{I}(x) \end{bmatrix} &= \tilde{\Phi}(x, x_0) \begin{bmatrix} \underline{V}(x_0) \\ \underline{I}(x_0) \end{bmatrix} + \int_{x_0}^x \tilde{\Phi}(x, \hat{x}) \begin{bmatrix} \underline{V}_s(\hat{x}) \\ \underline{I}_s(\hat{x}) \end{bmatrix} d\hat{x} \\ &= \tilde{\Phi}(x, x_0) \begin{bmatrix} \underline{V}(x_0) \\ \underline{I}(x_0) \end{bmatrix} + \begin{bmatrix} \hat{\underline{V}}_s(x) \\ \hat{\underline{I}}_s(x) \end{bmatrix} \end{aligned} \quad (2-6)$$

where  $\tilde{\Phi}(x, x_0)$  is the  $2n \times 2n$  chain parameter matrix (or state transition matrix) and  $x_0$  is some arbitrary position along the line  $x \geq x_0$ . The chain parameter matrix can be partitioned as

$$\tilde{\Phi}(x, x_0) = \begin{bmatrix} \tilde{\Phi}_{11}(x, x_0) & \tilde{\Phi}_{12}(x, x_0) \\ \tilde{\Phi}_{21}(x, x_0) & \tilde{\Phi}_{22}(x, x_0) \end{bmatrix} \quad (2-7)$$

where  $\tilde{\Phi}_{ij}(x, x_0)$  are  $n \times n$  for  $i, j=1, 2$ . Thus (2-6) can be written as

$$\underline{V}(x) = \tilde{\Phi}_{11}(x, x_0) \underline{V}(x_0) + \tilde{\Phi}_{12}(x, x_0) \underline{I}(x_0) + \hat{\underline{V}}_s(x) \quad (2-8a)$$

$$\underline{I}(x) = \tilde{\Phi}_{21}(x, x_0) \underline{V}(x_0) + \tilde{\Phi}_{22}(x, x_0) \underline{I}(x_0) + \hat{\underline{I}}_s(x) \quad (2-8b)$$

The entries  $\tilde{\Phi}_{ij}(x, x_0)$  are given by

$$\underline{\Phi}_{11}(x, x_0) = 1/2 \underline{Y}^{-1} \underline{T} (e^{\underline{Y}(x-x_0)} + e^{-\underline{Y}(x-x_0)}) \underline{T}^{-1} \underline{Y} \quad (2-9a)$$

$$\underline{\Phi}_{12}(x, x_0) = -1/2 \underline{Y}^{-1} \underline{T} \underline{Y} (e^{\underline{Y}(x-x_0)} - e^{-\underline{Y}(x-x_0)}) \underline{T}^{-1} \quad (2-9b)$$

$$\underline{\Phi}_{21}(x, x_0) = -1/2 \underline{T} (e^{\underline{Y}(x-x_0)} - e^{-\underline{Y}(x-x_0)}) \underline{Y}^{-1} \underline{T}^{-1} \underline{Y} \quad (2-9c)$$

$$\underline{\Phi}_{22}(x, x_0) = 1/2 \underline{T} (e^{\underline{Y}(x-x_0)} + e^{-\underline{Y}(x-x_0)}) \underline{T}^{-1} \quad (2-9d)$$

where  $e^{\underline{Y}(x-x_0)}$  is an  $n \times n$  diagonal matrix with  $[e^{\underline{Y}(x-x_0)}]_{ii} = e^{\gamma_i(x-x_0)}$  and  $[e^{\underline{Y}(x-x_0)}]_{ij} = 0$  for  $i, j=1, \dots, n$  and  $i \neq j$ . The matrix  $\underline{T}$  is an  $n \times n$ , complex-valued matrix which diagonalizes the matrix product  $\underline{Y}\underline{Z}$  as

$$\underline{T}^{-1} \underline{Y} \underline{Z} \underline{T} = \underline{Y}^2 \quad (2-10)$$

where  $\underline{Y}^2$  is an  $n \times n$  diagonal matrix with  $[\underline{Y}^2]_{ii} = \gamma_i^2$  and  $[\underline{Y}^2]_{ij} = 0$  for  $i, j=1, \dots, n$  and  $i \neq j$ . The  $n \times n$  characteristic impedance matrix,  $\underline{Z}_C$ , is given by

$$\underline{Z}_C = \underline{Y}^{-1} \underline{T} \underline{Y} \underline{T}^{-1} = \underline{Z} \underline{T} \underline{Y}^{-1} \underline{T}^{-1} \quad (2-11)$$

The transmission line is of length  $\mathcal{L}$  with termination networks at  $x = 0$  and at  $x = \mathcal{L}$  as shown in Fig. 2-3. For generality, the termination networks are considered to be in the form of linear n-ports and are characterizable by "Generalized Thevenin Equivalents" as

$$\underline{V}(0) = \underline{V}_0 - \underline{Z}_0 \underline{I}(0) \quad (2-12a)$$

$$\underline{V}(\mathcal{L}) = \underline{V}_{\mathcal{L}} + \underline{Z}_{\mathcal{L}} \underline{I}(\mathcal{L}) \quad (2-12b)$$

where  $\underline{V}_0$  and  $\underline{V}_{\mathcal{L}}$  are  $n \times 1$  complex-valued vectors of equivalent, open-circuit, port excitation voltages (with respect to the reference conductor) and  $\underline{Z}_0$



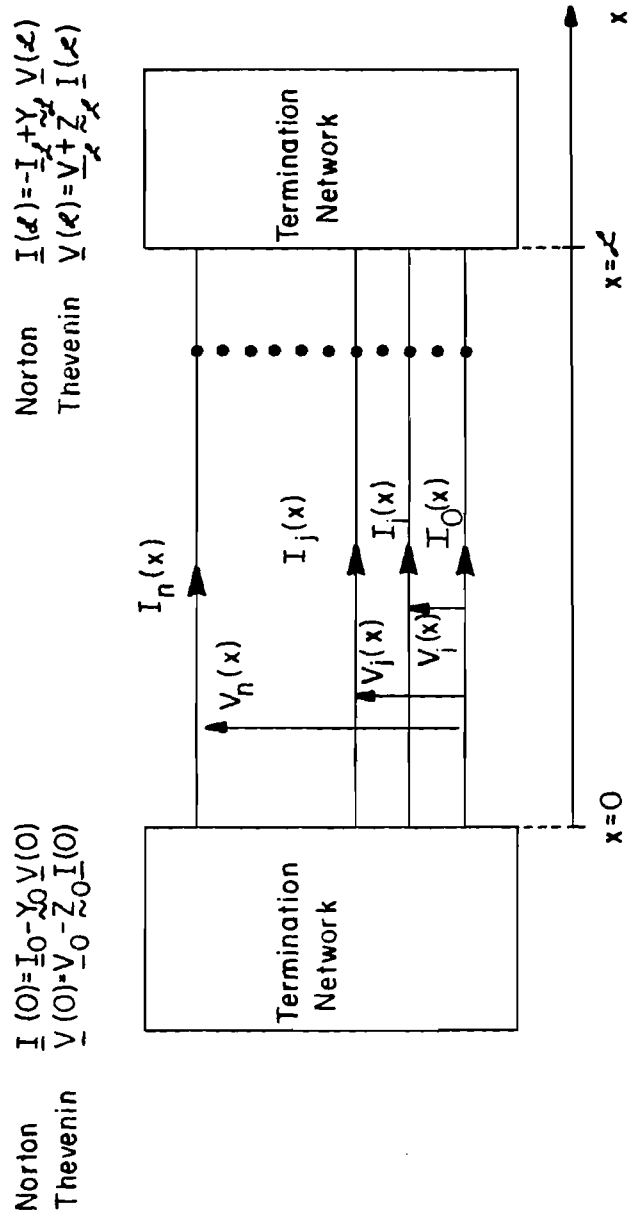


Fig. 2-3. The termination networks.

and  $\underline{Z}_x$  are  $n \times n$  symmetric, complex-valued port impedance matrices.

As an alternate characterization, (2-12) may be written as "Generalized Norton Equivalents" by multiplying (2-12a) on the left by  $\underline{Z}_0^{-1}$  and (2-12b) on the left by  $\underline{Z}_L^{-1}$  and rearranging as

$$\underline{I}(0) = \underline{I}_0 - \underline{Y}_0 \underline{V}(0) \quad (2-13a)$$

$$\underline{I}(L) = -\underline{I}_L + \underline{Y}_L \underline{V}(L) \quad (2-13b)$$

where  $\underline{I}_0$  and  $\underline{I}_L$  are equivalent, short-circuit, port excitation current sources. The  $n \times n$  port admittance matrices  $\underline{Y}_0$  and  $\underline{Y}_L$  are given by  $\underline{Y}_0 = \underline{Z}_0^{-1}$  and  $\underline{Y}_L = \underline{Z}_L^{-1}$  where the inverse of an  $n \times n$  matrix  $\underline{M}$  is denoted by  $\underline{M}^{-1}$  and  $\underline{I}_0 = \underline{Y}_0 \underline{V}_0$ ,  $\underline{I}_L = \underline{Y}_L \underline{V}_L$ . These port admittance matrices can be found by treating the line currents  $\underline{I}(0)$  or  $\underline{I}(L)$  as independent sources and writing the node voltage equations for the termination networks. The transmission line voltages,  $\underline{V}(0)$  or  $\underline{V}(L)$ , will comprise subsets of the node voltages of the termination networks. The additional node voltages can be eliminated from the node voltage equations describing the networks to yield (2-13). If the termination networks at  $x = 0$  and  $x = L$  consist only of admittances between the  $i$ -th and  $j$ -th wires,  $Y_{0_{ij}}$  and  $Y_{L_{ij}}$ , respectively, and between the  $i$ -th wire and the reference conductor,  $Y_{0_{in}}$  and  $Y_{L_{in}}$ , respectively, then the entries in  $\underline{Y}_0$  and  $\underline{Y}_L$  become  $[\underline{Y}_0]_{ii} = Y_{0_{ii}} + \sum_{j=1}^n Y_{0_{ij}}$ ,  $[\underline{Y}_0]_{ij} = -Y_{0_{ij}}$ ,  $[\underline{Y}_L]_{ii} = Y_{L_{ii}} + \sum_{j=1}^n Y_{L_{ij}}$ ,  $[\underline{Y}_L]_{ij} = -Y_{L_{ij}}$  for  $i, j=1, \dots, n$  and  $i \neq j$ .

With  $x = L$  and  $x_0 = 0$  in (2-8), one can straightforwardly obtain using the "Generalized Thevenin Equivalent" characterization of the termination networks given in (2-12)<sup>2</sup>

<sup>2</sup>In (2-8a) with  $x=L, x_0=0$  substitute (2-12a) for  $\underline{V}(0)$  and (2-12b) for  $\underline{V}(L)$ . Then substitute  $\underline{I}(L)$  from (2-8b) with  $x=L, x_0=0$  into the result and rearrange into the form in (2-14a). Substitute  $\underline{V}(0)$  from (2-12a) into (2-8b) and rearrange to yield (2-14b).

$$[Z_{\sim 1} \phi_{\sim 22}(\underline{x}) - Z_{\sim 1} \phi_{\sim 21}(\underline{x}) Z_0 - \phi_{\sim 12}(\underline{x}) + \phi_{\sim 11}(\underline{x}) Z_0] \underline{I}(0) = \quad (2-14a)$$

$$[\phi_{\sim 11}(\underline{x}) - Z_{\sim 1} \phi_{\sim 21}(\underline{x})] \underline{V}_0 - \underline{V}_{\sim 1} + \hat{\underline{V}}_{\sim s}(\underline{x}) - Z_{\sim 1} \hat{\underline{I}}_{\sim s}(\underline{x})$$

$$\underline{I}(\underline{x}) = \phi_{\sim 21}(\underline{x}) \underline{V}_0 + [\phi_{\sim 22}(\underline{x}) - \phi_{\sim 21}(\underline{x}) Z_0] \underline{I}(0) + \hat{\underline{I}}_{\sim s}(\underline{x}) \quad (2-14b)$$

where  $\phi_{\sim i}(\underline{x}, 0) \triangleq \phi_{\sim i}(\underline{x})$ .  $\underline{V}(\underline{x})$  and  $\underline{I}(\underline{x})$  can be obtained for any  $\underline{x}$ ,  $0 \leq \underline{x} \leq \underline{L}$ , from (2-8) with  $\underline{I}(0)$  from the solution of (2-14a) and  $\underline{V}(0)$  determined from (2-12a). Generally, we are only interested in the terminal voltages and currents,  $\underline{V}(0)$ ,  $\underline{V}(\underline{x})$ ,  $\underline{I}(0)$ ,  $\underline{I}(\underline{x})$ . The terminal currents,  $\underline{I}(0)$  and  $\underline{I}(\underline{x})$ , can be obtained from (2-14) and the terminal voltages,  $\underline{V}(0)$  and  $\underline{V}(\underline{x})$ , can be obtained from (2-12). Here one only needs to solve  $n$  equations in  $n$  unknowns (equation 2-14a).

The  $\phi_{\sim ij}$  submatrices of the chain parameter matrix in (2-7) satisfy certain fundamental identities, [1,2]. These identities can be used to formulate (2-14a) in an alternate form [1,2]:

$$[\{\phi_{\sim 21}(\underline{x}) Z_{\sim x} - \phi_{\sim 22}(\underline{x})\} \{\phi_{\sim 21}(\underline{x}) Z_0 - \phi_{\sim 22}(\underline{x})\} - \underline{1}_{\sim n}] \underline{I}(0) =$$

$$\phi_{\sim 21}(\underline{x}) \underline{V}_{\sim x} + \{\phi_{\sim 21}(\underline{x}) Z_{\sim x} - \phi_{\sim 22}(\underline{x})\} \phi_{\sim 21}(\underline{x}) \underline{V}_0 - \phi_{\sim 21}(\underline{x}) \cdot$$

$$[\hat{\underline{V}}_{\sim s}(\underline{x}) - Z_{\sim x} \hat{\underline{I}}_{\sim s}(\underline{x})] \quad (2-15)$$

where  $\underline{1}_{\sim n}$  is the  $n \times n$  identity matrix with  $[\underline{1}_{\sim n}]_{ii} = 1$  and  $[\underline{1}_{\sim n}]_{ij} = 0$  for  $i, j=1, \dots, n$  and  $i \neq j$ . Note that the formulations in (2-15) and (2-14b) require computation of only two of the four chain parameter submatrices,  $\phi_{\sim 21}(\underline{x})$  and  $\phi_{\sim 22}(\underline{x})$ .

As an alternate formulation, the above equations can be written in terms

of the "Generalized Norton Equivalent" representation of the termination networks given in (2-13). Rather than rederiving the above equations it is much simpler to note the direct similarity of the Norton equivalent representation in (2-13) and the Thevenin equivalent representation in (2-12). By noting the analogous variables in (2-13) and (2-12) and observing the form of (2-8), we may simply make certain substitutions of these analogous variables in (2-14) and (2-15) as shown in Table 1. The result is

$$[\underline{Y}_{\sim z} \underline{\phi}_{\sim 11}(z) - \underline{Y}_{\sim z} \underline{\phi}_{\sim 12}(z) \underline{Y}_{\sim 0} - \underline{\phi}_{\sim 21}(z) + \underline{\phi}_{\sim 22}(z) \underline{Y}_{\sim 0}] \underline{V}(0) = \quad (2-16a)$$

$$[\underline{\phi}_{\sim 22}(z) - \underline{Y}_{\sim z} \underline{\phi}_{\sim 12}(z)] \underline{I}_{\sim 0} + \underline{I}_{\sim z} + \hat{\underline{I}}_{\sim s}(z) - \underline{Y}_{\sim z} \hat{\underline{V}}_{\sim s}(z)$$

$$\underline{V}(z) = \underline{\phi}_{\sim 12}(z) \underline{I}_{\sim 0} + [\underline{\phi}_{\sim 11}(z) - \underline{\phi}_{\sim 12}(z) \underline{Y}_{\sim 0}] \underline{V}(0) + \hat{\underline{V}}_{\sim s}(z) \quad (2-16b)$$

$$\begin{aligned} & [ \{ \underline{\phi}_{\sim 12}(z) \underline{Y}_{\sim z} - \underline{\phi}_{\sim 11}(z) \} \{ \underline{\phi}_{\sim 12}(z) \underline{Y}_{\sim 0} - \underline{\phi}_{\sim 11}(z) \} - \underline{1}_{\sim n} ] \underline{V}(0) = \\ & - \underline{\phi}_{\sim 12}(z) \underline{I}_{\sim z} + [ \underline{\phi}_{\sim 12}(z) \underline{Y}_{\sim z} - \underline{\phi}_{\sim 11}(z) ] \underline{\phi}_{\sim 12}(z) \underline{I}_{\sim 0} \quad (2-16c) \\ & - \underline{\phi}_{\sim 12}(z) [ \hat{\underline{I}}_{\sim s}(z) - \underline{Y}_{\sim z} \hat{\underline{V}}_{\sim s}(z) ] \end{aligned}$$

## 2.2 The Equations to Be Programmed

The equations for  $\underline{I}(z)$  and  $\underline{V}(z)$  are given in (2-14b) and (2-16b), respectively. Either (2-14a) or (2-15) could be used for determining  $\underline{I}(0)$  and either (2-16a) or (2-16c) could be used for determining  $\underline{V}(0)$ . However, (2-14a) and (2-16a) will be selected for determining  $\underline{I}(0)$  and  $\underline{V}(0)$ , respectively. Since no external incident fields are considered,  $\hat{\underline{V}}_{\sim s}(z)$  and  $\hat{\underline{I}}_{\sim s}(z)$  in (2-14), (2-15) and (2-16) will be zero, i.e.,  $\hat{\underline{V}}_{\sim s}(z) = \hat{\underline{I}}_{\sim s}(z) = \underline{0}_{n-1}$ .

Certain modifications to these equations will be made to produce the final equations. The matrix chain parameters given in (2-9) for a line of

TABLE 1

Analogous variables in the Generalized Thevenin Equivalent (2-12) and Generalized Norton Equivalent (2-13) representation of the termination networks. The analogous variables are substituted in equations (2-14) and (2-15) to obtain equations (2-16).

Generalized Thevenin Equivalent (2-12)	Generalized Norton Equivalent (2-13)
$\underline{I}(0)$	$\underline{V}(0)$
$\underline{I}(z)$	$\underline{V}(z)$
$\underline{Z}_0$	$\underline{Y}_0$
$\underline{Z}_z$	$\underline{Y}_z$
$\underline{V}(0)$	$\underline{I}(0)$
$\underline{V}(z)$	$-\underline{I}(z)$
$\underline{\phi}_{11}(z)$	$\underline{\phi}_{22}(z)$
$\underline{\phi}_{12}(z)$	$\underline{\phi}_{21}(z)$
$\underline{\phi}_{21}(z)$	$\underline{\phi}_{12}(z)$
$\underline{\phi}_{22}(z)$	$\underline{\phi}_{11}(z)$
$\hat{\underline{V}}_{-s}(z)$	$\hat{\underline{I}}_{-s}(z)$
$\hat{\underline{I}}_{-s}(z)$	$\hat{\underline{V}}_{-s}(z)$

total length  $\mathcal{L}(x_0 = 0, x = \mathcal{L})$  become

$$\tilde{\Phi}_{11}(\mathcal{L}) = \tilde{Y}^{-1} \tilde{T} \tilde{E}^+ \tilde{T}^{-1} \tilde{Y} \quad (2-17a)$$

$$\tilde{\Phi}_{12}(\mathcal{L}) = -\tilde{Y}^{-1} \tilde{T} \tilde{Y} \tilde{E}^- \tilde{T}^{-1} \quad (2-17b)$$

$$\tilde{\Phi}_{21}(\mathcal{L}) = -\tilde{T} \tilde{E}^- \tilde{Y}^{-1} \tilde{T}^{-1} \tilde{Y} \quad (2-17c)$$

$$\tilde{\Phi}_{22}(\mathcal{L}) = \tilde{T} \tilde{E}^+ \tilde{T}^{-1} \quad (2-17d)$$

where the  $n \times n$  diagonal matrices  $\tilde{E}^+$  and  $\tilde{E}^-$  are given by

$$\tilde{E}^+ = \frac{1}{2} (\tilde{e}^{\tilde{Y}\mathcal{L}} + \tilde{e}^{-\tilde{Y}\mathcal{L}}) \quad (2-18a)$$

$$\tilde{E}^- = \frac{1}{2} (\tilde{e}^{\tilde{Y}\mathcal{L}} - \tilde{e}^{-\tilde{Y}\mathcal{L}}) \quad (2-18b)$$

Substituting (2-17) into (2-14a) and (2-14b) yields, for the Thevenin Equivalent representation of the termination networks

$$\begin{aligned} & [\tilde{Z} \tilde{Y} \tilde{T} \tilde{E}^+ \tilde{T}^{-1} + \tilde{Z} \tilde{Y} \tilde{T} \tilde{E}^- \tilde{Y}^{-1} \tilde{T}^{-1} \tilde{Y} \tilde{Z}_0] \tilde{I}(0) \\ & + \tilde{Y}^{-1} \tilde{T} \tilde{Y} \tilde{E}^- \tilde{T}^{-1} + \tilde{Y}^{-1} \tilde{T} \tilde{E}^+ \tilde{T}^{-1} \tilde{Y} \tilde{Z}_0] \tilde{I}(0) \\ & = [\tilde{Y}^{-1} \tilde{T} \tilde{E}^+ \tilde{T}^{-1} \tilde{Y} + \tilde{Z} \tilde{Y} \tilde{T} \tilde{E}^- \tilde{Y}^{-1} \tilde{T}^{-1} \tilde{Y}] \tilde{V}_0 - \tilde{V} \mathcal{L} \end{aligned} \quad (2-19a)$$

$$\begin{aligned} \tilde{I}(\mathcal{L}) & = -\tilde{T} \tilde{E}^- \tilde{Y}^{-1} \tilde{T}^{-1} \tilde{Y} \tilde{V}_0 \\ & + [\tilde{T} \tilde{E}^+ \tilde{T}^{-1} + \tilde{T} \tilde{E}^- \tilde{Y}^{-1} \tilde{T}^{-1} \tilde{Y} \tilde{Z}_0] \tilde{I}(0) \end{aligned} \quad (2-19b)$$

Similarly, substituting (2-17) into (2-16a) and (2-16b) yields, for the Norton Equivalent representation of the termination networks,

$$\begin{aligned} & [\tilde{Y} \tilde{Z} \tilde{Y}^{-1} \tilde{T} \tilde{E}^+ \tilde{T}^{-1} \tilde{Y} + \tilde{Y} \tilde{Z} \tilde{Y}^{-1} \tilde{T} \tilde{Y} \tilde{E}^- \tilde{T}^{-1} \tilde{Y}_0] \tilde{V}(0) \\ & + \tilde{T} \tilde{E}^- \tilde{Y}^{-1} \tilde{T}^{-1} \tilde{Y} + \tilde{T} \tilde{E}^+ \tilde{T}^{-1} \tilde{Y}_0] \tilde{V}(0) \\ & = [\tilde{T} \tilde{E}^+ \tilde{T}^{-1} + \tilde{Y} \tilde{Z} \tilde{Y}^{-1} \tilde{T} \tilde{Y} \tilde{E}^- \tilde{T}^{-1}] \tilde{I}_0 + \tilde{I} \mathcal{L} \end{aligned} \quad (2-20a)$$

$$\tilde{V}(\mathcal{L}) = -\tilde{Y}^{-1} \tilde{T} \tilde{Y} \tilde{E}^- \tilde{T}^{-1} \tilde{I}_0 + [\tilde{Y}^{-1} \tilde{T} \tilde{E}^+ \tilde{T}^{-1} \tilde{Y} + \tilde{Y}^{-1} \tilde{T} \tilde{Y} \tilde{E}^- \tilde{T}^{-1} \tilde{Y}_0] \tilde{V}(0) \quad (2-20b)$$

The medium surrounding all conductors is assumed throughout this report to be lossless. Therefore the per-unit-length conductance matrix,  $\underline{G}$ , which represents these losses in (2-4b) is zero, i.e.,  $\underline{G} = \underline{0}_{n \times n}$ . Therefore the per-unit-length admittance matrix becomes

$$\underline{Y} = j \omega \underline{C} \quad (2-21)$$

The per-unit-length impedance matrix is

$$\underline{Z} = \underline{R}_c + j \omega \underline{L}_c + j \omega \underline{L} \quad (2-22)$$

where  $\underline{R}_c$  and  $\underline{L}_c$  are zero matrices, i.e.,  $\underline{0}_{n \times n}$ , when perfect conductors are assumed.

To reduce the number of matrix multiplications, the above equations will be placed in an alternate form. For the Norton Equivalent representation in (2-20), define

$$\underline{Y}_z^* = \underline{T}^{-1} \underline{Y}_z \underline{C}^{-1} \underline{T} \quad (2-23a)$$

$$\underline{Y}_0^* = \underline{T}^{-1} \underline{Y}_0 \underline{C}^{-1} \underline{T} \quad (2-23b)$$

$$\underline{V}^*(z) = \underline{T}^{-1} \underline{C} \underline{V}(z) \quad (2-23c)$$

$$\underline{V}^*(0) = \underline{T}^{-1} \underline{C} \underline{V}(0) \quad (2-23d)$$

$$\underline{I}_z^* = \underline{T}^{-1} \underline{I}_z \quad (2-23e)$$

$$\underline{I}_0^* = \underline{T}^{-1} \underline{I}_0 \quad (2-23f)$$

$$\underline{Y} = j \omega \underline{\Lambda} \quad (2-23g)$$

Equations (2-20) can then be written as

$$\begin{aligned} & [\underline{Y}_z^* \underline{E}^+ + \underline{Y}_z^* \underline{\Lambda} \underline{E}^- \underline{Y}_0^* + \underline{E}^- \underline{\Lambda}^{-1} + \underline{E}^+ \underline{Y}_0^*] \underline{V}^*(0) \\ & = [\underline{E}^+ + \underline{Y}_z^* \underline{\Lambda} \underline{E}^-] \underline{I}_0^* + \underline{I}_z^* \end{aligned} \quad (2-24a)$$

$$\underline{V}^*(z) = -\underline{\Lambda} \underline{E}^- \underline{I}_0^* + [\underline{E}^+ + \underline{\Lambda} \underline{E}^- \underline{Y}_0^*] \underline{V}^*(0) \quad (2-24b)$$

and the actual termination voltages can be determined by solving (2-24) for  $\underline{V}^*(0)$  and  $\underline{V}^*(z)$  and using (2-23c) and (2-23d) to obtain

$$\underline{V}(0) = \underline{C}^{-1} \underline{T} \underline{V}^*(0) \quad (2-25a)$$

$$\underline{V}(z) = \underline{C}^{-1} \underline{T} \underline{V}^*(z) \quad (2-25b)$$

These equations are summarized in Table 2.

Similarly, equations (2-19) for the Thevenin Equivalent representation of the terminal networks can be reduced to an equivalent form by defining

$$\underline{Z}_z^* = \underline{T}^{-1} \underline{C} \underline{Z}_z \underline{T} \quad (2-26a)$$

$$\underline{Z}_0^* = \underline{T}^{-1} \underline{C} \underline{Z}_0 \underline{T} \quad (2-26b)$$

$$\underline{I}_z^* = \underline{T}^{-1} \underline{I}(z) \quad (2-26c)$$

$$\underline{I}_0^* = \underline{T}^{-1} \underline{I}(0) \quad (2-26d)$$

$$\underline{V}_z^* = \underline{T}^{-1} \underline{C} \underline{V}_z \quad (2-26e)$$

$$\underline{V}_0^* = \underline{T}^{-1} \underline{C} \underline{V}_0 \quad (2-26f)$$

$$\underline{\gamma} = j \omega \underline{\Lambda} \quad (2-26g)$$

Equations (2-19) can then be written as

$$\begin{aligned} & [\underline{Z}_z^* \underline{E}^+ + \underline{Z}_z^* \underline{E}^- \underline{\Lambda}^{-1} \underline{Z}_0^* + \underline{\Lambda} \underline{E}^- + \underline{E}^+ \underline{Z}_0^*] \underline{I}_z^*(0) \\ & = [\underline{E}^+ + \underline{Z}_z^* \underline{E}^- \underline{\Lambda}^{-1}] \underline{V}_0^* - \underline{V}_z^* \end{aligned} \quad (2-27a)$$

$$\underline{I}_z^*(z) = -\underline{E}^- \underline{\Lambda}^{-1} \underline{V}_0^* + [\underline{E}^+ + \underline{E}^- \underline{\Lambda}^{-1} \underline{Z}_0^*] \underline{I}_z^*(0) \quad (2-27b)$$

and the actual termination currents can be obtained by solving (2-27) for  $\underline{I}_z^*(0)$  and  $\underline{I}_z^*(z)$  and using (2-26c) and (2-26d) to obtain



$$\underline{I}(0) = \underline{T} \underline{I}^*(0) \quad (2-28a)$$

$$\underline{I}(z) = \underline{T} \underline{I}^*(z) \quad (2-28b)$$

These equations are summarized in Table 3.

There are two reasons for using the equivalent representations in Table 2 and Table 3 rather than the representations in (2-20) and (2-19). First of all, note the direct similarity of the equations in Table 2 and Table 3. The only differences (other than symbols) between equations (1) and (2) in Table 2 and the corresponding equations (1) and (2) in Table 3 is that  $\underline{\Lambda}$  used in Table 2 corresponds to  $\underline{\Lambda}^{-1}$  in Table 3, and  $\underline{I}_z^*$  in Table 2 corresponds to  $-\underline{V}_z^*$  in Table 3. (Note that since  $\underline{\Lambda}$ ,  $\underline{\Lambda}^{-1}$  and  $\underline{E}^-$  are diagonal,  $\underline{E}^- \underline{\Lambda}^{-1} = \underline{\Lambda}^{-1} \underline{E}^-$  and  $\underline{E}^- \underline{\Lambda} = \underline{\Lambda} \underline{E}^-$ .) Therefore we may form the Norton Equivalent equations in the programs and not need to write a duplicate set for the Thevenin Equivalent representations.

The second reason for using the representations in Table 2 and Table 3 is that if the termination networks are purely resistive, i.e.,  $Z_0$ ,  $Z_z$ ,  $Y_0$  and  $Y_z$  are real, and the transformation matrix,  $\underline{T}$ , is frequency independent, i.e., perfect conductors are assumed (as in XTALK and FLATPAK), then the matrix multiplications as well as the inversion of  $\underline{T}$  to form  $\underline{T}^{-1}$  needed to obtain  $Y_0^*$ ,  $Y_z^*$ ,  $Z_0^*$ ,  $Z_z^*$  need only be performed once and need not be changed as the frequency is changed. Only equations (1) and (2) in Table 2 and Table 3 need be reformulated for each frequency. This can represent a significant savings in computation time when the line response for many frequencies is desired (as it usually is) since  $n^3$  operations (multiplications or divisions) are required to multiply two "full"  $n \times n$  matrices which is the minimum number of operations required to obtain the inverse of a general  $n \times n$  matrix [1].

TABLE 2

Programmed Equations for the Generalized  
Norton Equivalent Representation

- (1) 
$$\begin{aligned} & [ \underline{Y}_z^* \underline{E}^+ + \underline{Y}_z^* \underline{\Lambda} \underline{E}^- \underline{Y}_0^* + \underline{E}^- \underline{\Lambda}^{-1} + \underline{E}^+ \underline{Y}_0^* ] \underline{V}^*(0) \\ & = [ \underline{E}^+ + \underline{Y}_z^* \underline{\Lambda} \underline{E}^- ] \underline{I}_0^* + \underline{I}_z^* \end{aligned}$$
- (2) 
$$\underline{V}^*(z) = -\underline{\Lambda} \underline{E}^- \underline{I}_0^* + [ \underline{E}^+ + \underline{\Lambda} \underline{E}^- \underline{Y}_0^* ] \underline{V}^*(0)$$
- (3) 
$$\underline{T}^{-1} \underline{Y} \underline{Z} \underline{T} = \underline{T}^{-1} \{ j\omega \underline{C} [ \underline{R}_c + j\omega \underline{L}_c + j\omega \underline{L} ] \} \underline{T} = \underline{Y}^2$$
- (4) 
$$\underline{Y} = j\omega \underline{\Lambda}$$
- (5) 
$$\underline{I}(0) = \underline{I}_0 - \underline{Y}_0 \underline{V}(0) \quad , \quad \underline{I}(z) = -\underline{I}_z + \underline{Y}_z \underline{V}(z)$$
- (6) 
$$\underline{Y}_0^* = \underline{T}^{-1} \underline{Y}_0 \underline{C}^{-1} \underline{T} \quad , \quad \underline{Y}_z^* = \underline{T}^{-1} \underline{Y}_z \underline{C}^{-1} \underline{T}$$
- (7) 
$$\underline{I}_0^* = \underline{T}^{-1} \underline{I}_0 \quad , \quad \underline{I}_z^* = \underline{T}^{-1} \underline{I}_z$$
- (8) 
$$\underline{E}^+ = \frac{1}{2} ( e^{\underline{Y}z} + e^{-\underline{Y}z} ) \quad , \quad \underline{E}^- = \frac{1}{2} ( e^{\underline{Y}z} - e^{-\underline{Y}z} )$$
- (9) 
$$\underline{V}(0) = \underline{C}^{-1} \underline{T} \underline{V}^*(0) \quad , \quad \underline{V}(z) = \underline{C}^{-1} \underline{T} \underline{V}^*(z)$$

TABLE 3

Programmed Equations for the Generalized  
Thevenin Equivalent Representation

$$(1) \quad [Z_{\underline{z}}^* E^+ + Z_{\underline{z}}^* E^- \Lambda^{-1} Z_0^* + \Lambda E^- + E^+ Z_0^*] \underline{I}^*(0) \\ = [E^+ + Z_{\underline{z}}^* E^- \Lambda^{-1}] \underline{V}_0^* - \underline{V}_{\underline{z}}^*$$

$$(2) \quad \underline{I}^*(z) = -E^- \Lambda^{-1} \underline{V}_0^* + [E^+ + E^- \Lambda^{-1} Z_0^*] \underline{I}^*(0)$$

$$(3) \quad \underline{T}^{-1} \underline{Y} \underline{Z} \underline{T} = \underline{T}^{-1} \{j\omega C[R_c + j\omega L_c + j\omega L]\} \underline{T} = \underline{\gamma}^2$$

$$(4) \quad \underline{\gamma} = j\omega \underline{\Lambda}$$

$$(5) \quad \underline{V}(0) = \underline{V}_0 - Z_0 \underline{I}(0) \quad , \quad \underline{V}(z) = \underline{V}_{\underline{z}} + Z_{\underline{z}} \underline{I}(z)$$

$$(6) \quad Z_0^* = \underline{T}^{-1} \underline{C} Z_0 \underline{T} \quad , \quad Z_{\underline{z}}^* = \underline{T}^{-1} \underline{C} Z_{\underline{z}} \underline{T}$$

$$(7) \quad \underline{V}_0^* = \underline{T}^{-1} \underline{C} \underline{V}_0 \quad , \quad \underline{V}_{\underline{z}}^* = \underline{T}^{-1} \underline{C} \underline{V}_{\underline{z}}$$

$$(8) \quad E^+ = \frac{1}{2} (e^{\underline{\gamma} z} + e^{-\underline{\gamma} z}) \quad , \quad E^- = \frac{1}{2} (e^{\underline{\gamma} z} - e^{-\underline{\gamma} z})$$

$$(9) \quad \underline{I}(0) = \underline{T} \underline{I}^*(0) \quad , \quad \underline{I}(z) = \underline{T} \underline{I}^*(z)$$

Note:  $\underline{V}^*(0) = \underline{V}_0^* - Z_0^* \underline{I}^*(0) \quad , \quad \underline{V}^*(z) = \underline{V}_{\underline{z}}^* + Z_{\underline{z}}^* \underline{I}^*(z)$   
 where:  $\underline{V}^*(0) = \underline{T}^{-1} \underline{C} \underline{V}(0) \quad , \quad \underline{V}^*(z) = \underline{T}^{-1} \underline{C} \underline{V}(z)$

### 2.3 Formulation of the Terminal Network Equations

The previous formulation requires that one determine the entries in the  $n \times n$  matrices  $\underline{Z}_0$ ,  $\underline{Z}_l$ ,  $\underline{Y}_0$  and  $\underline{Y}_l$ , and the  $n \times 1$  vectors,  $\underline{V}_0$ ,  $\underline{V}_l$ ,  $\underline{I}_0$  and  $\underline{I}_l$ , in the Thevenin and Norton Equivalent representations of the terminal networks in (2-12) and (2-13), respectively. In this section, some examples will be given to aid in determining these quantities.

To illustrate this, four examples will be used. The first example, Example 1, is shown in Figure 2-4a. In this example, there is no cross-coupling between the port terminals within the termination networks, i.e., at each end of the line, each endpoint of a wire is terminated directly to the reference conductor and is not physically connected to the endpoints of other wires at the same end of the line. Writing the following equations:

$$V_1(0) = 1 - 1 I_1(0) \quad (2-29a)$$

$$V_2(0) = -10 I_2(0) \quad (2-29b)$$

$$V_1(l) = 10^3 I_1(l) \quad (2-29c)$$

$$V_2(l) = 10^4 I_2(l) + 1 \quad (2-29d)$$

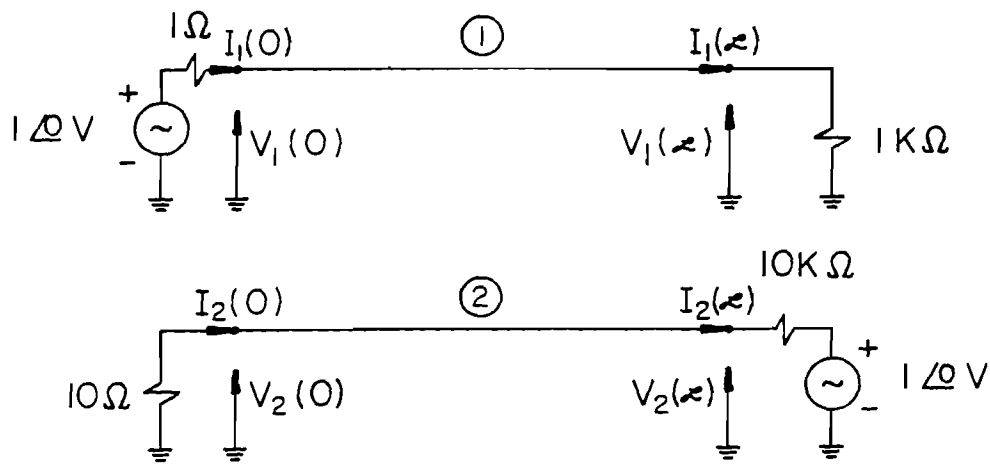
and comparing these equations to the Thevenin Equivalent representation

$$\underline{V}(0) = \underline{V}_0 - \underline{Z}_0 \underline{I}(0) \quad (2-30a)$$

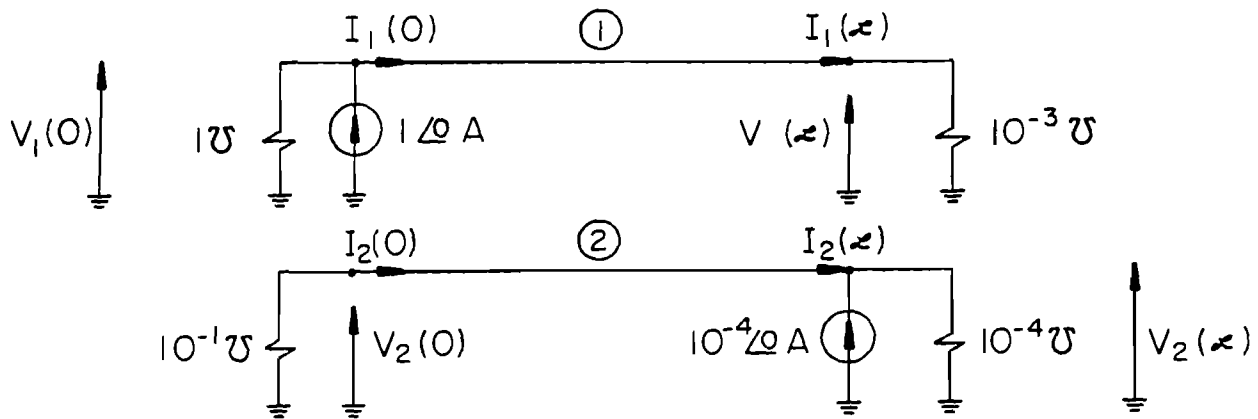
$$\underline{V}(l) = \underline{V}_l + \underline{Z}_l \underline{I}(l) \quad (2-30b)$$

where

$$\begin{aligned} \underline{V}(0) &= \begin{bmatrix} V_1(0) \\ V_2(0) \end{bmatrix} & \underline{V}(l) &= \begin{bmatrix} V_1(l) \\ V_2(l) \end{bmatrix} \\ \underline{I}(0) &= \begin{bmatrix} I_1(0) \\ I_2(0) \end{bmatrix} & \underline{I}(l) &= \begin{bmatrix} I_1(l) \\ I_2(l) \end{bmatrix} \end{aligned} \quad (2-31)$$



(a) Example 1



(b) Example 2

Fig. 2-4. Example termination networks. (No cross-coupling)

one can readily identify

$$\begin{aligned} \underline{v}_0 &= \begin{bmatrix} 1 \\ 0 \end{bmatrix} & \underline{z}_0 &= \begin{bmatrix} 1 & 0 \\ 0 & 10 \end{bmatrix} \\ \underline{v}_z &= \begin{bmatrix} 0 \\ 1 \end{bmatrix} & \underline{z}_z &= \begin{bmatrix} 10^3 & 0 \\ 0 & 10^4 \end{bmatrix} \end{aligned} \quad (2-32)$$

Similarly, one can convert the termination networks to a Norton equivalent representation in Figure 2-4b and obtain (Example 2).

$$I_2(0) = 1 - 1 V_1(0) \quad (2-33a)$$

$$I_2(0) = -10^{-1} V_2(0) \quad (2-33b)$$

$$I_1(z) = 10^{-3} V_1(z) \quad (2-33c)$$

$$I_2(z) = -10^{-4} + 10^{-4} V_2(z) \quad (2-33d)$$

Comparing these equations to the Norton Equivalent representation

$$\underline{I}(0) = \underline{I}_0 - \underline{Y}_0 \underline{V}(0) \quad (2-34a)$$

$$\underline{I}(z) = -\underline{I}_z + \underline{Y}_z \underline{V}(z) \quad (2-34b)$$

where  $\underline{I}(0)$ ,  $\underline{I}(z)$ ,  $\underline{V}(0)$ ,  $\underline{V}(z)$  are given in (2-31), one can readily identify for Example 2

$$\begin{aligned} \underline{I}_0 &= \begin{bmatrix} 1 \\ 0 \end{bmatrix} & \underline{Y}_0 &= \begin{bmatrix} 1 & 0 \\ 0 & 10^{-1} \end{bmatrix} \\ \underline{I}_z &= \begin{bmatrix} 0 \\ 10^{-4} \end{bmatrix} & \underline{Y}_z &= \begin{bmatrix} 10^{-3} & 0 \\ 0 & 10^{-4} \end{bmatrix} \end{aligned} \quad (2-35)$$

Note that

$$\underline{I}_0 = \underline{z}_0^{-1} \underline{V}_0 \quad (2-36a)$$

$$\underline{Y}_0 = \underline{Z}_0^{-1} \quad (2-36b)$$

$$\underline{I}_f = \underline{Z}_f^{-1} \underline{V}_f \quad (2-36c)$$

$$\underline{Y}_f = \underline{Z}_f^{-1} \quad (2-36d)$$

Note also that as far as the network terminal characteristics are concerned, the termination networks in Figure 2-4a are the same as those in Figure 2-4b.

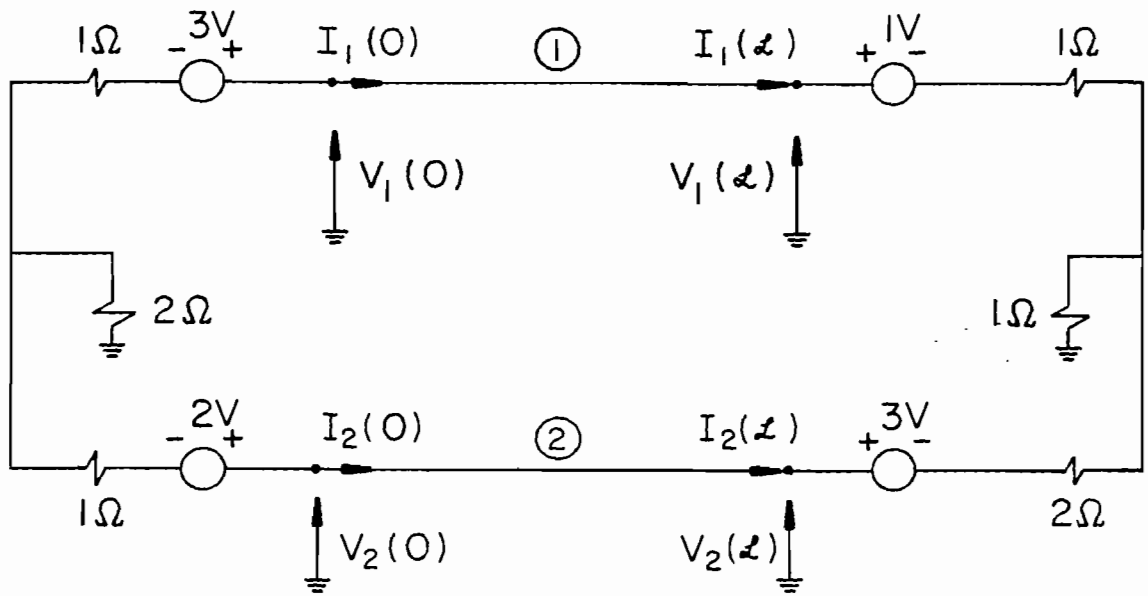
The third and fourth examples, Example 3 and Example 4, are shown in Figure 2-5. As far as terminal characteristics are concerned, the terminations in Figure 2-5a and in Figure 2-5b are the same as shown by the following. First, write the Norton Equivalent characterization for the terminations in Figure 2-5b as (treat the terminal currents as independent sources and write the node-voltage circuit equations of the networks)

$$\underbrace{\begin{bmatrix} I_1(0) \\ I_2(0) \end{bmatrix}}_{\underline{I}(0)} = \underbrace{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}_{\underline{I}_0} - \underbrace{\begin{bmatrix} .6 & -.4 \\ -.4 & .6 \end{bmatrix}}_{\underline{Y}_0} \underbrace{\begin{bmatrix} V_1(0) \\ V_2(0) \end{bmatrix}}_{\underline{V}_0} \quad (2-37a)$$

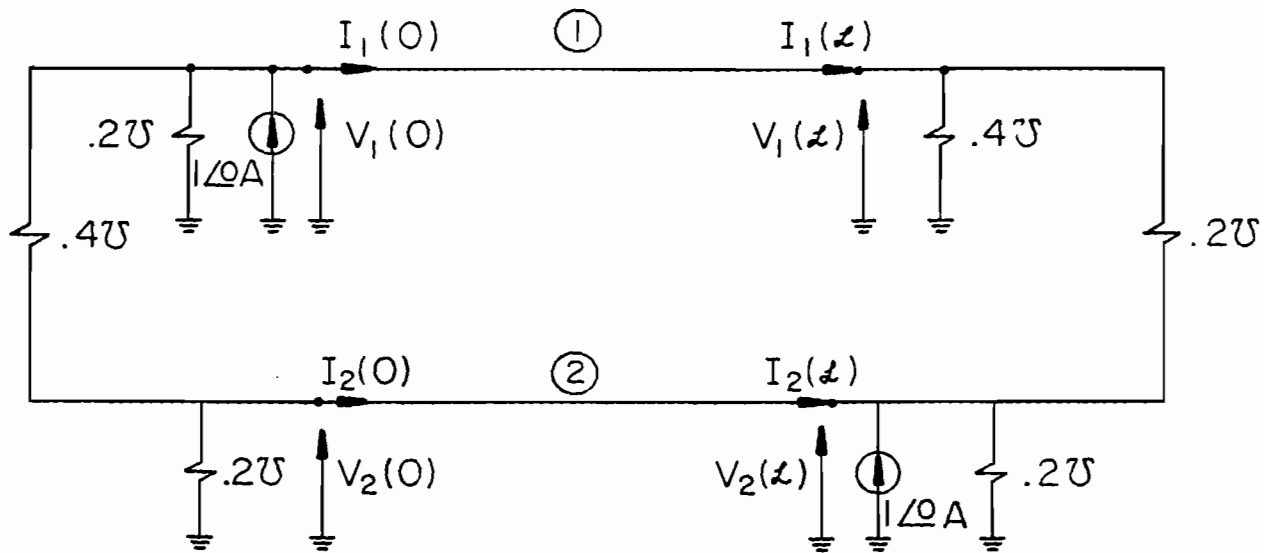
$$\underbrace{\begin{bmatrix} I_1(z) \\ I_2(z) \end{bmatrix}}_{\underline{I}(z)} = \underbrace{\begin{bmatrix} 0 \\ 1 \end{bmatrix}}_{\underline{I}_z} + \underbrace{\begin{bmatrix} .6 & -.4 \\ -.4 & .6 \end{bmatrix}}_{\underline{Y}_z} \underbrace{\begin{bmatrix} V_1(z) \\ V_2(z) \end{bmatrix}}_{\underline{V}_z} \quad (2-37b)$$

Similarly, from Figure 2-5a write the Thevenin Equivalent characterization as (treat the terminal voltages as independent sources and write the loop current circuit equations of the networks)

$$\underbrace{\begin{bmatrix} V_1(0) \\ V_2(0) \end{bmatrix}}_{\underline{V}(0)} = \underbrace{\begin{bmatrix} 3 \\ 2 \end{bmatrix}}_{\underline{V}_0} - \underbrace{\begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix}}_{\underline{Z}_0} \underbrace{\begin{bmatrix} I_1(0) \\ I_2(0) \end{bmatrix}}_{\underline{I}(0)} \quad (2-38a)$$



(a) Example 3



(b) Example 4

Fig. 2-5. Example termination networks. (cross-coupling)



$$\begin{bmatrix} V_1(z) \\ V_2(z) \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} + \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} I_1(z) \\ I_2(z) \end{bmatrix} \quad (2-38b)$$

$\underbrace{\hspace{1.5cm}}_{\underline{V}(z)} \quad \quad \quad \underbrace{\hspace{1.5cm}}_{\underline{Z}(z)} \quad \quad \quad \underbrace{\hspace{1.5cm}}_{\underline{I}(z)}$

Note that

$$\underline{Y}_0 = \underline{Z}_0^{-1} \quad (2-39a)$$

$$\underline{Y}_f = \underline{Z}_f^{-1} \quad (2-39b)$$

$$\underline{I}_0 = \underline{Y}_0 \underline{V}_0 \quad (2-39c)$$

$$\underline{I}_f = \underline{Y}_f \underline{V}_f \quad (2-39d)$$

and as far as the terminal characteristics of the networks are concerned, the termination networks in Figure 2-5a are the same as those in Figure 2-5b.

The above examples will serve a dual purpose. Each of the computer programs will be run for each of the above four examples for the same transmission line structure. Typical solution printouts will be shown for these results. This will serve as a partial check on the proper functioning of the programs since the corresponding terminal voltages ( $V_1(0)$ ,  $V_2(0)$ ,  $V_1(z)$ ,  $V_2(z)$ ) for Example 1 should equal those for Example 2. Similarly the corresponding terminal voltages for Example 3 should equal those for Example 4.

As can be seen from the above examples, if there is no cross-coupling within the termination networks, then formulation of the entries in  $\underline{V}_0$ ,  $\underline{V}_f$ ,  $\underline{Z}_0$  and  $\underline{Z}_f$  or  $\underline{I}_0$ ,  $\underline{I}_f$ ,  $\underline{Y}_0$  and  $\underline{Y}_f$  is particularly simple. The situation in which there is no cross-coupling within the termination networks is generally the problem of interest in wire-coupled interference calculations.

However, it was felt that the more general case of allowing cross-coupling within the terminal networks be included in the capabilities of the programs.

To save computer time, one has four options for inputting the terminal data: OPTIONS 11, 12, 21, or 22. The first digit in each number indicates to each program that the terminal characterization chosen is either the Thevenin Equivalent (1) or Norton Equivalent (2). The second digit indicates to the program whether the admittance ( $\underline{Y}_0$  and  $\underline{Y}_l$ ) or impedance ( $\underline{Z}_0$  and  $\underline{Z}_l$ ) matrices are diagonal (1), i.e., no cross-coupling, or full (2), i.e., cross-coupling. For example, OPTION 11 indicates Thevenin Equivalent, diagonal impedance matrices; OPTION 22 indicates Norton Equivalent, full admittance matrices; OPTION 12 indicates Thevenin Equivalent, full impedance matrices, and OPTION 21 indicates Norton Equivalent, diagonal admittance matrices.

This saves computer time and user effort in inputting the data. For example, in cases where  $\underline{Z}_0$  (or  $\underline{Z}_l$ , or  $\underline{Y}_0$  or  $\underline{Y}_l$ ) must be multiplied by another  $n \times n$  matrix such as in  $\underline{T} \underline{Z}_0$ , if  $\underline{Z}_0$  is diagonal one only needs  $n^2$  multiplications to form this product whereas if  $\underline{Z}_0$  is full,  $n^3$  multiplications are needed to form the product. The programs are written to take advantage of this. In addition, if the terminal admittance or impedance matrices are in fact diagonal, then the user need only input the entries on the main diagonal and is saved the drudgery of inputting the remaining zero entries. The specific details for inputting this termination network data will be given in Chapter IV, the User's Manual.

#### 2.4 Common Impedance Coupling and the Calculation of Conductor Self Impedances

Programs XTALK and FLATPAK assume that all conductors are perfect conductors. Programs XTALK2 and FLATPAK2, however, do not assume perfect conductors and these programs include the per-unit-length conductor resistance and internal inductance, the items  $r_{c_i}$  and  $\ell_{c_i}$ , respectively, in Figure 2-2 and (2-5) as well as the reference conductor<sup>1</sup> resistance,  $r_{c_0}$ , and

inductance,  $l_{c_0}$ .

The reason for writing two separate programs to consider the same transmission line structure such as XTALK and XTALK2 is that the inclusion of conductor losses in the transmission line solution requires a longer computer run time and more array storage than when perfect conductors are assumed. This can be seen in Tables 2 and 3 in that the transformation matrix  $\tilde{T}$  will be frequency dependent (and complex) when losses are included, whereas  $\tilde{T}$  will be frequency independent (and real) when perfect conductors are assumed, i.e.,  $R_{\tilde{c}} = L_{\tilde{c}} = \frac{0}{n \times n}$ . Therefore when perfect conductors are assumed (in XTALK and FLATPAK), one need only compute  $\tilde{T}$  once per problem and the same  $\tilde{T}$  can be used throughout the frequency iteration. When lossy conductors are considered (in XTALK2 and FLATPAK2), one must recompute  $\tilde{T}$  at each frequency in addition to reforming at each frequency those matrix products involving  $\tilde{T}$  in Table 2 and Table 3.

The primary effect of imperfect conductors is to introduce common impedance coupling. Consider a transmission line in which there is no cross-coupling within the termination networks. In this case, clearly the voltages induced via electromagnetic field coupling at the ends of a "receptor" circuit consisting of one conductor (wire) and the reference conductor due to a "generator" circuit consisting of another wire and the reference conductor will approach zero as the frequency of excitation is reduced to zero. However, the reference conductor impedance can couple a signal into the receptor circuit even at D-C and this is usually termed common impedance coupling.

To illustrate this, consider Figure 2-6. In Figure 2-6a, a three-conductor transmission line is shown. The reference conductor has a certain total impedance,  $Z_0$ , which may be considerably smaller in magnitude than

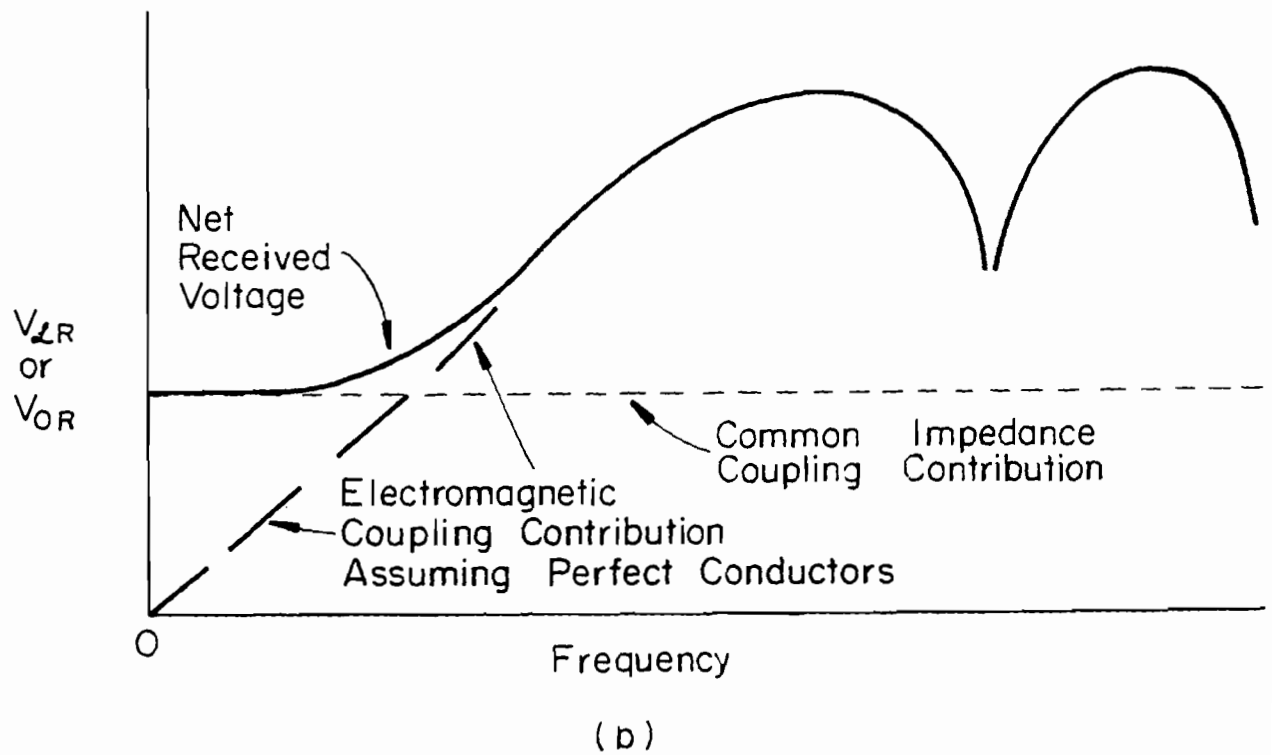
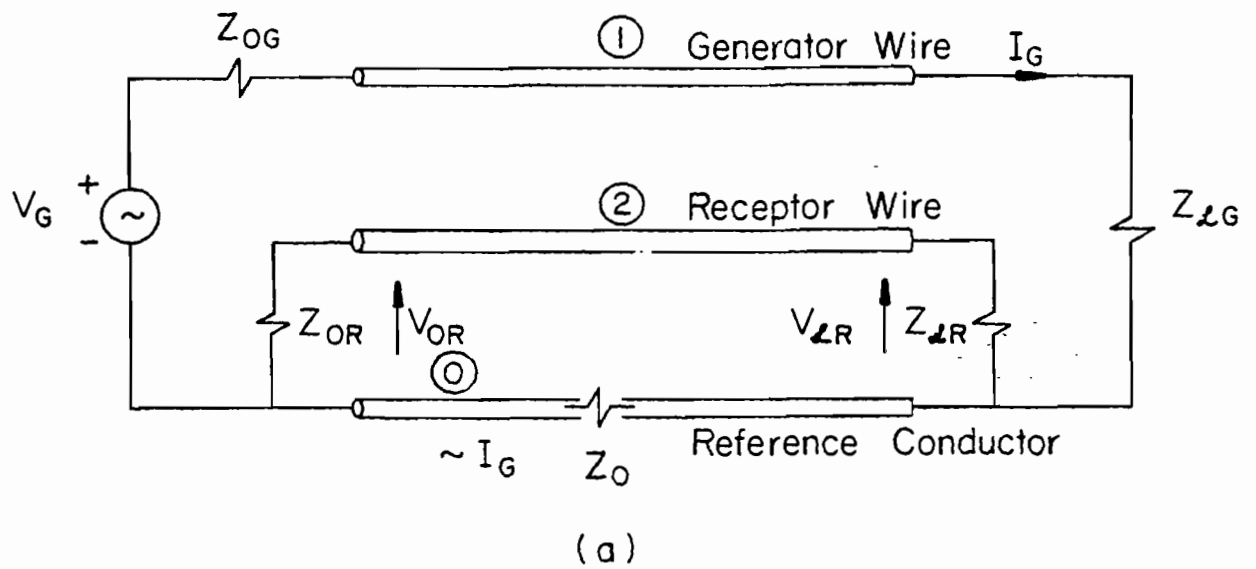


Fig. 2-6. Illustration of common impedance coupling.

$Z_{OR}$  or  $Z_{LR}$ . Consequently, the current in the generator wire at frequencies approaching D-C may be determined as

$$I_G \approx \frac{V_G}{Z_{OG} + Z_{LG}} \quad (2-40)$$

The major portion of this current will pass through the reference conductor producing a voltage drop across  $Z_0$ . This results in received voltages

$$V_{LR} \approx - \left[ \frac{Z_{LR}}{Z_{LR} + Z_{OR}} \right] Z_0 I_G \quad (2-41a)$$

$$V_{OR} \approx \left[ \frac{Z_{OR}}{Z_{LR} + Z_{OR}} \right] Z_0 I_G \quad (2-41b)$$

Although this portion of the total received voltage may be "small" it may nevertheless be larger than the contribution due to electromagnetic field coupling as shown in Figure 2-6b. Consequently, this common impedance coupling generates a "floor" of induced voltage where a solution assuming perfect conductors would indicate a perhaps negligibly small received voltage at the lower frequencies.

The frequency at which this common impedance coupling becomes significant depends on many factors some of which are line geometry (which affects the level of the electromagnetic portion of the coupling) and type of reference conductor. Reference conductors consisting of a #36 gauge wire or a large, thick ground plane would certainly not produce the same level of common impedance coupling.

The above separation and superposition of the two coupling mechanisms is only correct when one dominates the other by a considerable amount. To obtain a quantitatively correct answer, one must include the conductor self impedances directly in the transmission line solution and this is done in

XTALK2 and FLATPAK2.

The transmission lines considered by all programs in this report consist of  $n$  wires (cylindrical conductors) and a reference conductor. In XTALK2, there are three choices for the reference conductor; (1) a wire, (2) a finite ground plane and (3) an overall cylindrical shield surrounding the  $n$  wires. When the reference conductor is a finite ground plane, the user simply inputs the per-unit-length resistance and self inductance of the ground plane. Thus there are two cases remaining to be considered.

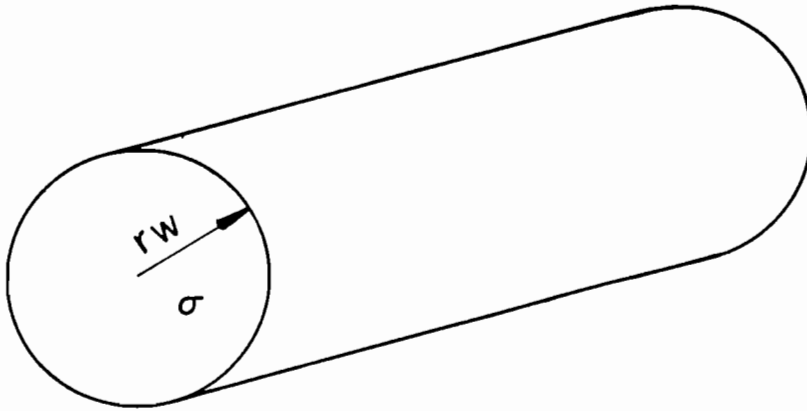
The per-unit-length self impedance of a solid cylinder of radius  $r_w$  shown in Figure 2-7a is given by the following. Define

$$\begin{aligned}\delta &= \frac{1}{\sqrt{\pi f \mu_v \sigma}} \\ &= \frac{1}{2\pi \sqrt{\sigma f} \times 10^{-7}}\end{aligned}\tag{2-42a}$$

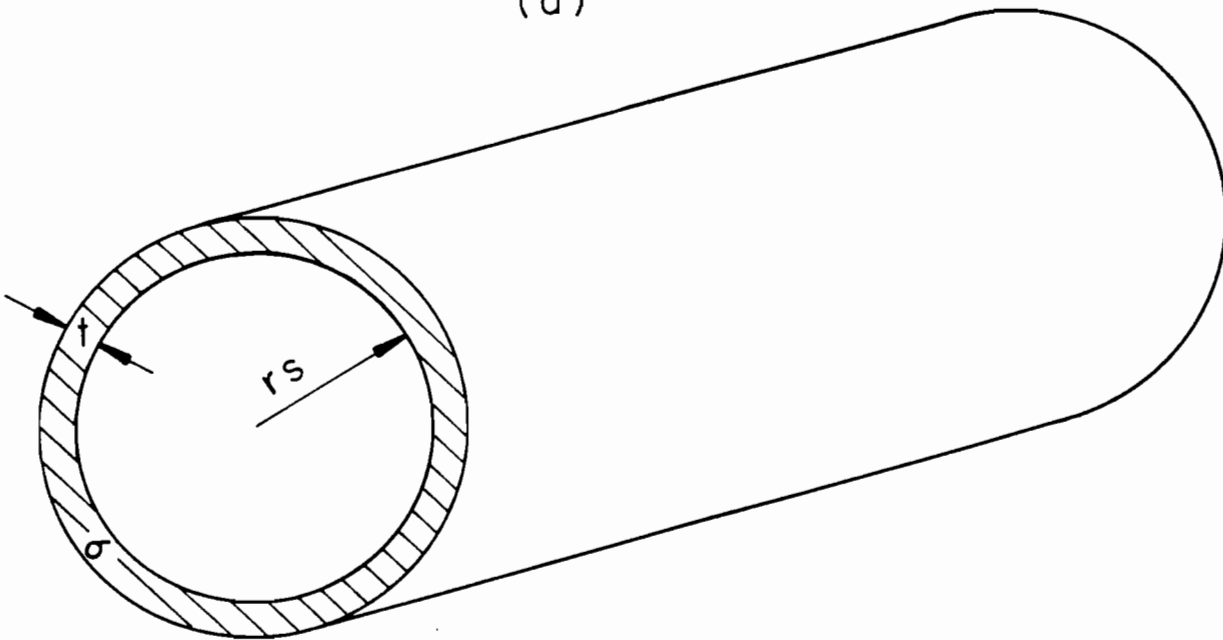
$$r_0 = \frac{1}{\pi \sigma r_w^2}\tag{2-42b}$$

$$l_0 = \frac{\mu_v}{8\pi} = .5 \times 10^{-7}\tag{2-42c}$$

where  $\sigma$  is the conductor conductivity,  $f$  is the frequency and  $\mu_v$  is the permeability of the metal which is assumed to be that of free space ( $\mu_v = 4\pi \times 10^{-7}$ ). The quantity  $\delta$  is the conventional skin depth factor. The equations for the per-unit-length self impedance of a solid cylindrical conductor including skin effect are obtained from [6]. The equations used in the computer programs approximate the actual equations given in reference [6], pp. 78-80. The programmed equations are



(a)



(b)

Fig. 2-7. Conductor dimensions for calculating common impedance.

$$(I) \quad r_w \leq \delta$$

$$r = r_0 \quad \text{ohms/meter} \quad (2-43a)$$

$$\ell = \ell_0 \quad \text{henrys/meter} \quad (2-43b)$$

$$(II) \quad \delta < r_w < 3\delta$$

$$r = \frac{1}{4} \left( \frac{r_w}{\delta} + 3 \right) r_0 \quad \text{ohms/meter} \quad (2-44a)$$

$$\ell = \left[ 1.15 - .15 \left( \frac{r_w}{\delta} \right) \right] \ell_0 \quad \text{henrys/meter} \quad (2-44b)$$

$$(III) \quad r_w \geq 3\delta$$

$$r = \frac{r_w}{2\delta} r_0 \quad \text{ohms/meter} \quad (2-45a)$$

$$\ell = \frac{2\delta}{r_w} \ell_0 \quad \text{henrys/meter} \quad (2-45b)$$

These equations are used to generate the per-unit-length self impedances of the transmission line wires ( $z_i = r + j\omega\ell$ ) and the reference conductor when the reference conductor is also a wire ( $z_0 = r + j\omega\ell$ ). They are stored within the program codes for XTALK2 and FLATPAK2 and the user needs to input only the physical dimensions of the wires and their conductivity.

For the purposes of computing these wire self impedances, the wires are considered to be stranded. The user inputs the radius of each strand (in mils) and the number of strands in each wire. The program then computes the per-unit-length self impedance of each strand and determines the net wire self impedance by dividing this result by the number of strands (the net resistance of the wire is considered to be the result of all strands of the wire in parallel). (All strands in a wire are considered to be identical)

The equations for the per-unit-length self impedance of the reference conductor when the reference conductor is a thin walled, overall, cylindrical



shield shown in Figure 2-7b are taken from reference [7], pp. 301-303 and include skin effect. The equations used in the computer programs are approximations of the actual equations. The skin depth,  $\delta$ , is given in (2-42a). Denote the interior radius of the cylinder by  $r_s$  and its wall thickness by  $t$ . The equations become [7]

$$r_0 = \frac{1}{\pi \sigma t (2r_s + t)} \quad (2-46)$$

(I)  $t \leq .5\delta$

$$r = r_0 \quad \text{ohms/meter} \quad (2-47a)$$

$$\omega l = .4 \left(\frac{t}{\delta}\right) r_0 \quad \text{ohms/meter} \quad (2-47b)$$

(II)  $t \geq 3\delta$

$$r = \frac{1}{2\pi r_s \sigma \delta} \quad \text{ohms/meter} \quad (2-48a)$$

$$\omega l = r \quad \text{ohms/meter} \quad (2-48b)$$

(III)  $.5\delta < t < 3\delta$

$$r = \frac{1}{2\pi r_s \sigma \delta} \left[ \frac{\sinh\left(\frac{2t}{\delta}\right) + \sin\left(\frac{2t}{\delta}\right)}{\cosh\left(\frac{2t}{\delta}\right) - \cos\left(\frac{2t}{\delta}\right)} \right] \quad \text{ohms/meter} \quad (2-49a)$$

$$\omega l = \frac{1}{2\pi r_s \sigma \delta} \left[ \frac{\sinh\left(\frac{2t}{\delta}\right) - \sin\left(\frac{2t}{\delta}\right)}{\cosh\left(\frac{2t}{\delta}\right) - \cos\left(\frac{2t}{\delta}\right)} \right] \quad \text{ohms/meter} \quad (2-49b)$$

The per-unit-length self impedance of the shield is given by  $z_0 = r + j\omega l$ .

These equations are stored in the XTALK2 program code. The user only needs to input the shield interior radius, the shield thickness and the conductivity of the shield.

## 2.5 Computation of the Per-Unit-Length Inductance and Capacitance Matrices

All of the formulations shown in Tables 2 and 3 require the computation of the  $n \times n$ , real, symmetric, per-unit-length transmission line inductance and capacitance matrices,  $\underline{L}$  and  $\underline{C}$ , respectively. The computation of these matrices will be discussed in this section.

### 2.5.1 Transmission Lines Consisting of Perfect Conductors in a Lossless, Homogeneous Medium, XTALK

This section considers  $(n+1)$  conductor transmission lines consisting of  $(n+1)$  perfect conductors in a lossless, homogeneous medium. The lines consist of  $n$  wires and three choices of reference conductor (the zero-th conductor) cross sections of which are shown in Figure 2-8. Computer program XTALK considers these cases.

The per-unit-length inductance and capacitance matrices for lines in a homogeneous medium are related by [1]

$$\underline{L} \underline{C} = \mu \epsilon \underline{1}_n \quad (2-50)$$

where  $\mu$  and  $\epsilon$  are the permeability and permittivity of the surrounding homogeneous medium. The per-unit-length capacitance matrix can be found from a knowledge of the per-unit-length inductance matrix from (2-50) as

$$\underline{C} = \mu \epsilon \underline{L}^{-1} \quad (2-51)$$

A logical choice for the surrounding medium in Figure 2-8(a) and 2-8(b) would be free space with permeability  $\mu_v = 4\pi \times 10^{-7}$  henrys/meter and permittivity  $\epsilon_v = (1/36\pi) \times 10^{-9}$  farads/meter. However, for all structure types, the homogeneous medium may be characterized, for generality, by a relative dielectric constant (permittivity) of  $\epsilon_r$  and a relative permeability of  $\mu_r$ . (Although the permeability of typical dielectrics is that of free space,  $\mu_v$ ,

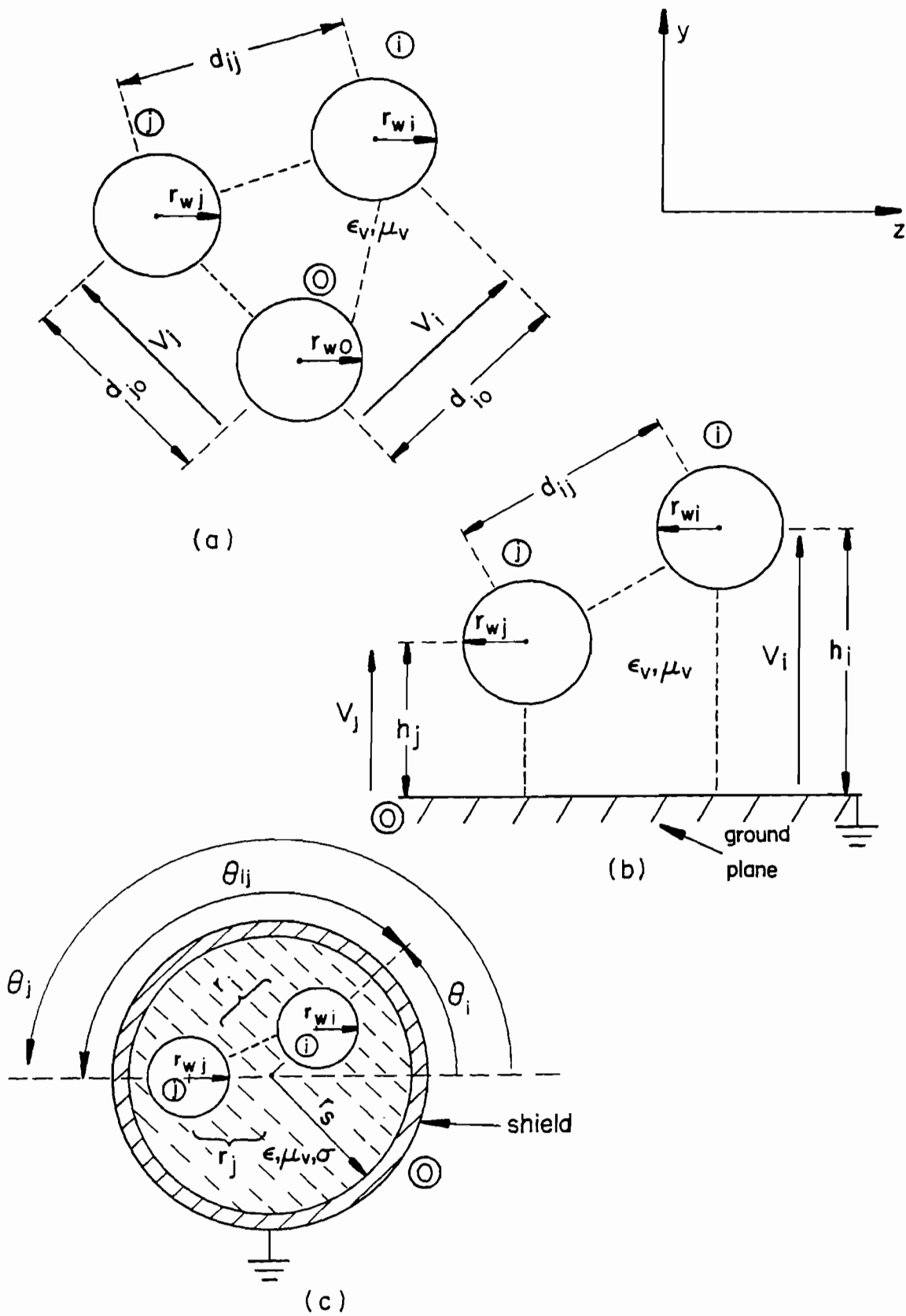


Fig. 2-8. Lines in a homogeneous medium.

the programs XTALK and XTALK2 allow for the more general case.)

For the case of lossless conductors in a lossless, homogeneous medium, the  $n \times n$  characteristic impedance matrix,  $\underline{Z}_C$ , in (2-11) is related to the per-unit-length inductance matrix by [1]

$$\underline{Z}_C = v \underline{L} = \frac{v_0}{\sqrt{\epsilon_r \mu_r}} \underline{L} \quad (2-52)$$

where  $v = 1/\sqrt{\mu\epsilon}$  is the velocity of light in the surrounding medium. The velocity of light in free space,  $v_0$ , to 7 digits is  $2.997925 \times 10^8$  meters/second.

The equations used in the programs for the entries in the per-unit-length transmission line matrix are derived in Volume I of this series [1] and are valid for "large" conductor separations. Generally this means that the smallest ratio of wire separation to wire radius should be no smaller than approximately 5. A more complete discussion of this is found in Volume I.

When the reference conductor is a wire as shown in Figure 2-8(a), the entries in the per-unit-length transmission line matrix are given by [1]

$$[\underline{L}]_{ii} = \frac{\mu_v \mu_r}{2\pi} \ln \left( \frac{d_{i0}^2}{r_{wi} r_{w0}} \right) \quad (2-53a)$$

$$[\underline{L}]_{ij} = \frac{\mu_v \mu_r}{2\pi} \ln \left( \frac{d_{i0} d_{j0}}{r_{w0} d_{ij}} \right) \quad (2-53b)$$

for  $i, j=1, \dots, n$  and  $i \neq j$  where  $d_{i0}$  is the center-to-center separation between the  $i$ -th wire and the reference conductor,  $d_{ij}$  is the center-to-center separation between the  $i$ -th and  $j$ -th wires, and  $r_{wi}$  and  $r_{w0}$  are the radii of the  $i$ -th and reference wires, respectively.

When the reference conductor is an infinite ground plane as shown in Figure 2-8(b), the entries in the per-unit-length inductance matrix are

given by [1]

$$[L]_{ii} = \frac{\mu_v \mu_r}{2\pi} \ln \left( \frac{2h_i}{r_{wi}} \right) \quad (2-54a)$$

$$[L]_{ij} = \frac{\mu_v \mu_r}{2\pi} \ln \left( \frac{\sqrt{d_{ij}^2 + 4h_i h_j}}{d_{ij}} \right) \quad (2-54b)$$

for  $i, j=1, \dots, n$  and  $i \neq j$  where  $h_i$  is the height of the  $i$ -th wire above the ground plane.

When the reference conductor is an overall cylindrical shield as shown in Figure 2-8(c), the entries in the per-unit-length inductance matrix are given by [1]

$$[L]_{ii} = \frac{\mu_v \mu_r}{2\pi} \ln \left( \frac{r_s^2 - r_i^2}{r_s r_{wi}} \right) \quad (2-55a)$$

$$[L]_{ij} = \frac{\mu_v \mu_r}{2\pi} \ln \left\{ \left( \frac{r_j}{r_s} \right) \sqrt{\frac{(r_i r_j)^2 + r_s^4 - 2r_i r_j r_s^2 \cos \theta_{ij}}{(r_i r_j)^2 + r_j^4 - 2r_i r_j^3 \cos \theta_{ij}}} \right\} \quad (2-55b)$$

for  $i, j=1, \dots, n$  and  $i \neq j$  where  $r_s$  is the interior radius of the shield,  $r_i$  is the separation of the  $i$ -th wire from the center of the shield and  $\theta_{ij}$  is the angular separation between the  $i$ -th and  $j$ -th wires

For the case of lossless conductors in a lossless, homogeneous medium, the equations for the terminal voltages and currents in Table 2 and Table 3 can be further simplified. Obviously, the transformation matrix,  $T$ , which diagonalizes the matrix product  $\underline{Y} \underline{Z}$  can be taken to be simply the identity matrix, i.e.,  $T = \underline{1}_n$ , as is clear from the fact that for this case  $\underline{Z} = j\omega \underline{L}$ ,  $\underline{Y} = j\omega \underline{C}$  and

$$\begin{aligned} \underline{Y} \underline{Z} &= -\omega^2 \underline{L} \underline{C} \\ &= \frac{-\omega^2}{v^2} \underline{1}_n \end{aligned} \quad (2-56)$$

Also, the  $n \times n$  diagonal matrix,  $\underline{\Lambda}$ , in Tables 2 and 3 becomes

$$\underline{\Lambda} = \frac{1}{v} \underline{1}_n \quad (2-57)$$

Therefore the equations for the terminal voltages,  $\underline{V}(0)$  and  $\underline{V}(z)$ , for the Norton Equivalent representation of the terminal networks in Table 2 simplify to [1] (see equations (2-19) and (2-20)).

$$\begin{aligned} & [\cos(\beta z) \{ \underline{Y}_z + \underline{Y}_0 \} + j \sin(\beta z) \{ \underline{Y}_z \underline{Z}_C \underline{Y}_0 + \underline{Z}_C^{-1} \}] \underline{V}(0) \\ & = [\cos(\beta z) \underline{1}_n + j \sin(\beta z) \underline{Y}_z \underline{Z}_C] \underline{I}_0 + \underline{I}_f \end{aligned} \quad (2-58a)$$

$$\underline{V}(z) = -j \sin(\beta z) \underline{Z}_C \underline{I}_0 + [\cos(\beta z) \underline{1}_n + j \sin(\beta z) \underline{Z}_C \underline{Y}_0] \underline{V}(0) \quad (2-58b)$$

where  $\beta$  is the phase constant

$$\beta = \omega/v \quad (2-59)$$

and the characteristic impedance matrix  $\underline{Z}_C$  is given in (2-52).

Similarly the equations for the terminal currents,  $\underline{I}(0)$  and  $\underline{I}(z)$ , for the Thevenin Equivalent representation in Table 3 simplify to

$$\begin{aligned} & [\cos(\beta z) \{ \underline{Z}_z + \underline{Z}_0 \} + j \sin(\beta z) \{ \underline{Z}_z \underline{Z}_C^{-1} \underline{Z}_0 + \underline{Z}_C \}] \underline{I}(0) \\ & = -\underline{V}_z + [\cos(\beta z) \underline{1}_n + j \sin(\beta z) \underline{Z}_z \underline{Z}_C^{-1}] \underline{V}_0 \end{aligned} \quad (2-60a)$$

$$\underline{I}(z) = -j \sin(\beta z) \underline{Z}_C^{-1} \underline{V}_0 + [\cos(\beta z) \underline{1}_n + j \sin(\beta z) \underline{Z}_C^{-1} \underline{Z}_0] \underline{I}(0) \quad (2-60b)$$

The terminal voltages can be obtained from the solution of (2-60) for the terminal currents,  $\underline{I}(0)$  and  $\underline{I}(z)$ , with the equations for the terminal networks

$$\underline{V}(0) = \underline{V}_0 - \underline{Z}_0 \underline{I}(0) \quad (2-61a)$$

$$\underline{V}(z) = \underline{V}_z + \underline{Z}_z \underline{I}(z) \quad (2-61b)$$

### 2.5.2 Transmission Lines Consisting of Imperfect (Lossy) Conductors in a Lossless, Homogeneous Medium, XTALK2

This section considers the (n+1) conductor transmission lines considered in the previous section and shown in Figure 2-8. However, the transmission line conductors are considered to be lossy. Computer program XTALK2 considers these cases.

The per-unit-length inductance and capacitance matrices are computed as in the previous section and satisfy the relation in (2-50). The entries in  $\underline{L}$  are given in (2-53), (2-54) and (2-55). The per-unit-length admittance matrix is given by

$$\underline{Y} = j\omega \underline{C} = j \frac{\omega}{\sqrt{2}} \underline{L}^{-1} \quad (2-62)$$

The per-unit-length impedance matrix is given by

$$\underline{Z} = \underline{R}_c + j\omega \underline{L}_c + j\omega \underline{L} \quad (2-63)$$

where the entries in  $\underline{R}_c$  and  $\underline{L}_c$  are due to imperfect conductors. The entries in  $\underline{R}_c$  and  $\underline{L}_c$  are given in (2-5) and these matrices can be separated as [1]

$$\underline{R}_c + j\omega \underline{L}_c = (r_{c_0} + j\omega l_{c_0}) \underline{U}_n + \underline{Z}_D \quad (2-64)$$

where  $\underline{U}_n$  is the  $n \times n$  unit matrix with one's in every position, i.e.,  $[\underline{U}_n]_{ij} = 1$ , and  $\underline{Z}_D$  is a diagonal matrix with

$$[\underline{Z}_D]_{ii} = r_{c_i} + j\omega l_{c_i} \quad (2-65)$$

and  $[\underline{Z}_D]_{ij} = 0$  for  $i, j=1, \dots, n$  and  $i \neq j$ . The calculation of the wire

self impedances,  $r_{c_i} + j\omega l_{c_i}$ , and the reference conductor self impedance,  $r_{c_0} + j\omega l_{c_0}$ , is discussed in section 2.4.

### 2.5.3 Transmission Lines Consisting of Perfect Conductors in a Lossless, Inhomogeneous Medium, FLATPAK

This section considers (n+1) conductor transmission lines consisting of (n+1) perfect conductors in a lossless, inhomogeneous medium. For example, dielectric insulations surrounding wires result in an inhomogeneous medium (dielectric insulation and the surrounding free space). The computer program FLATPAK considers a specific case of flatpack or ribbon cables. A ribbon cable consists of (n+1) identical wires with identical cylindrical dielectric insulations bonded together in a linear array as shown in Figure 2-9.

In this case, the relationship in (2-50) relating the per-unit-length inductance and capacitance matrices no longer holds. Clearly the surrounding medium does not influence the per-unit-length inductance matrix since the surrounding medium is considered to be homogeneous in its permeability characteristic,  $\mu_v$ . Therefore, one may compute the per-unit-length capacitance matrix with the wire dielectric insulations removed, denoted by  $C_{\sim 0}$ , and determine  $\underline{L}$  through (2-50) as

$$\underline{L} = \mu_v \epsilon_v \underline{C}_{\sim 0}^{-1} \quad (2-66)$$

Therefore, one needs to compute the per-unit-length capacitance matrix with and without the wire dielectric insulations present. A digital computer program, GETCAP, has been written to compute the per-unit-length capacitance matrices of ribbon cables. This program is described in detail in Volume II of this series [8].



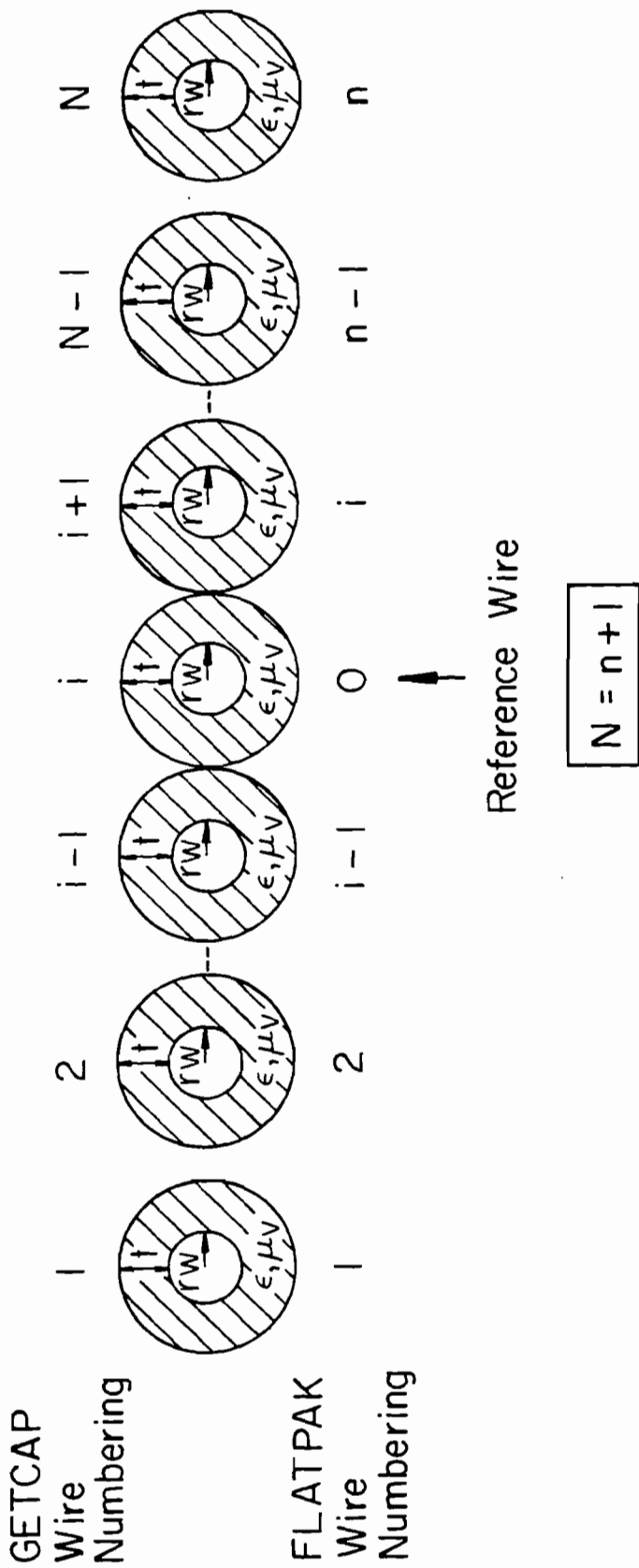


Fig. 2-9. An  $(n+1)$  wire ribbon (flatpack) cable.

The per-unit-length impedance and admittance matrices become

$$\underline{Z} = j\omega\underline{L} \quad (2-67a)$$

$$\underline{Y} = j\omega\underline{C} \quad (2-67b)$$

The transformation matrix,  $\underline{T}$ , which diagonalizes the matrix product  $\underline{Y} \underline{Z}$  must therefore diagonalize the product  $\underline{C} \underline{L}$  as

$$\begin{aligned} \underline{T}^{-1} \underline{Y} \underline{Z} \underline{T} &= -\omega^2 \underline{T}^{-1} \underline{C} \underline{L} \underline{T} \\ &= -\omega^2 \underline{\Lambda}^2 \end{aligned} \quad (2-68)$$

In addition, it can be shown that [1]

$$\underline{T}^{-1} = \underline{T}^t \underline{C}^{-1} \quad (2-69)$$

where  $\underline{T}^t$  is the transpose of  $\underline{T}$ . A digital computer subroutine NROOT (which uses subroutine EIGEN) is used to accomplish this reduction and is discussed in a later section.

#### 2.5.4 Transmission Lines Consisting of Imperfect (Lossy) Conductors in a Lossless, Inhomogeneous Medium, FLATPAK2

This section considers (n+1) conductor transmission lines consisting of (n+1) lossy conductors in a lossless, inhomogeneous medium. The program FLATPAK2 considers a particular case of flatpack or ribbon cables discussed in the previous section.

The per-unit-length capacitance and inductance matrices are computed assuming perfect conductors and can be obtained with GETCAP as described in the previous section.

The self impedances of the wires are identical since the wires in the ribbon cable are typically identical. Therefore the pre-unit-length

impedance and admittance matrices become

$$\underline{Z} = z(\underline{U}_{\sim n} + \underline{1}_{\sim n}) + j\omega \underline{L} \quad (2-70a)$$

$$\underline{Y} = j\omega \underline{C} \quad (2-70b)$$

where  $z = r + j\omega l$  is the self impedance of each wire.

### III. PROGRAM CODE DESCRIPTIONS

In this chapter, the content of each program will be described by card. (Each program is labeled in columns 72-80 with the card number.) All programs were written in double precision arithmetic and the program listings are given in Appendix A - Appendix D. A table is provided with each listing which shows the changes which are required to convert each program to single precision arithmetic. Listings of two of the required subroutines, NROOT and EIGEN, are provided in Appendix E - Appendix F. The remaining required subroutines, LEQT1C and EIGCC, are a part of the IMSL (International Mathematical and Statistical Library) package [9]. Appropriate alternate subroutines can be substituted for LEQT1C and EIGCC if the IMSL package is not available on the user's system.

#### 3.1 Program XTALK

A listing of XTALK is given in Appendix A.

Cards 001 through 047 contain general comments concerning the applicability of the program. This format will be followed in the other programs.

Cards 048 through 053 are comment cards pointing out that all arrays must be properly dimensioned for each problem before using the program.

Cards 054 through 059 dimension the arrays and declare variable types.

Card 060 gives the value of  $\pi$  and the speed of light in free space.

Cards 061 through 065 define the complex numbers  $1+j0$ ,  $0+j0$ , and  $0+j1$  as well as other constants.

Cards 071 through 118 read and print an initial portion of the input data.

Cards 123 through 170 read and print the line dimensions and compute the entries in the characteristic impedance matrix. The entries in the characteristic impedance matrix,  $Z_C$ , are related to the per-unit-length inductance matrix for the three structure types given in (2-53), (2-54) and (2-55) by  $Z_C = v L$ . Cards 132 through 139 compute the main diagonal entries of  $Z_C$ . Cards 141 through 170 compute the off-diagonal entries. The  $n \times 1$  complex



Arrays V1 and V2 are used to temporarily store the  $Z_i$  and  $Y_i$  coordinates and the  $r_i$  and  $\theta_i$  coordinates of the wires in the real parts of the arrays (see Figure 4-1, Figure 4-2, Figure 4-3). The  $n \times n$  complex array M1 is used to temporarily store the characteristic impedance matrix in the real parts. Although the actual quantities stored are real, it was decided to use the real parts of these complex arrays to store these quantities rather than define additional real arrays. V1, V2 and M1 will be needed (as complex arrays) later.

Cards 175 through 181 compute the inverse of the characteristic impedance matrix which is temporarily stored in the real part of the  $n \times n$  complex array M2. M2 will be needed (as a complex array) later. The matrix inverse is computed with subroutine LEQTIC which is described in section 3.5.

Cards 190 through 226 read and print the entries in the terminal impedance characterizations. These matrix characterizations are given in (2-30) for the Thevenin Equivalent characterization and in (2-34) for the Norton Equivalent characterization. The  $n \times 1$  complex arrays I0 and IL store the entries in  $\underline{I}(0)$  and  $\underline{I}(1)$ , respectively, for the Norton Equivalent in (2-34) or  $\underline{V}(0)$  and  $\underline{V}(1)$ , respectively, for the Thevenin Equivalent in (2-30). The  $n \times n$  complex arrays Y0 and YL store the entries in  $\underline{Y}_0$  and  $\underline{Y}_1$ , respectively, for the Norton Equivalent in (2-34) or  $\underline{Z}_0$  and  $\underline{Z}_1$ , respectively, for the Thevenin Equivalent in (2-30).

Cards 231 through 291 contain certain matrix and vector multiplications which are independent of frequency. If one requests the analysis to be done at more than one frequency (such as in computing the frequency response of the line), then these time-consuming multiplications need be computed only for the first frequency and need not be recomputed for the additional fre-

quencies. To explain these cards, consider the similarity of the forms of the equations for the Norton Equivalent characterization given in (2-58) and the Thevenin Equivalent characterization given in (2-60). The analogous variables in these two equations are summarized as:

<u>(2-58)</u>	<u>(2-60)</u>
$\underline{Y}(\underline{f})$	$\underline{Z}(\underline{f})$
$\underline{Y}_0$	$\underline{Z}_0$
$\underline{Z}_C$	$\underline{Z}_C^{-1}$
$\underline{Z}_C^{-1}$	$\underline{Z}_C$
$\underline{I}_0$	$\underline{V}_0$
$\underline{I}(\underline{f})$	$-\underline{V}(\underline{f})$
$\underline{V}(0)$	$\underline{I}(0)$
$\underline{V}(\underline{f})$	$\underline{I}(\underline{f})$

Therefore equations (2-58) can be programmed and used for both cases if analogous variables are substituted. Cards 231 through 240 swap the entries in M1 and M2 if the Thevenin Equivalent characterization is chosen. Cards 251 through 291 form the quantities in (2-58)

$\underline{Z}_C \underline{Y}_0$	<u>Array</u> M1	(3-1a)
$\underline{Y}(\underline{f}) \underline{Z}_C \underline{Y}_0 + \underline{Z}_C^{-1}$	M2	(3-1b)
$\underline{Z}_C \underline{I}_0$	V1	(3-1c)
$\underline{Y}(\underline{f}) \underline{Z}_C \underline{I}_0$	V2	(3-1d)

for the Norton Equivalent characterization or the quantities in (2-60)

$\underline{Z}_C^{-1} \underline{Z}_0$	<u>Array</u> M1	(3-2a)
$\underline{Z}(\underline{f}) \underline{Z}_C^{-1} \underline{Z}_0 + \underline{Z}_C$	M2	(3-2b)

$$\underline{Z}_C^{-1} \underline{V}_0 \quad V1 \quad (3-2c)$$

$$\underline{Z}_L \underline{Z}_C^{-1} \underline{V}_0 \quad V2 \quad (3-2d)$$

for the Thevenin Equivalent characterization.

Cards 295 through 300 read the frequency and form

$$\beta L = \frac{2\pi f}{v} L \quad (3-3a)$$

$$\sin(\beta L) \quad (3-3b)$$

$$\cos(\beta L) \quad (3-3c)$$

Cards 306 through 316 form equation (2-58a) for the Norton Equivalent characterization or (2-60a) for the Thevenin Equivalent characterization. These equations are solved with subroutine LEQT1C in card 320. The solutions ( $\underline{V}(0)$  for (2-58a) or  $\underline{I}(0)$  for (2-60a)) are stored in the array B.

Cards 332 through 336 form equation (2-58b) or (2-60b) and the entries in  $\underline{V}(L)$  for (2-58b) or  $\underline{I}(L)$  for (2-60b) are stored in the array WA.

Cards 337 through 365 print the terminal voltages  $\underline{V}(0)$  and  $\underline{V}(L)$ . Cards 337 through 352 form the terminal voltages, if the Thevenin Equivalent characterization is chosen, from

$$\underline{V}(0) = \underline{V}_0 - \underline{Z}_0 \underline{I}(0) \quad (3-4a)$$

$$\underline{V}(L) = \underline{V}_L + \underline{Z}_L \underline{I}(L) \quad (3-4b)$$

since the elements of the arrays B and WA are the following:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
B	$\underline{V}(0)$	$\underline{I}(0)$
WA	$\underline{V}(L)$	$\underline{I}(L)$

Cards 353 through 365 print the resulting terminal voltages,  $\underline{V}(0)$  and  $\underline{V}(L)$ .



### 3.2 Program XTALK2

A listing of XTALK2 is given in Appendix B.

Cards 001 through 190 have the same purpose and are of the same general structure as cards 001 through 181 in XTALK. The slight exceptions are that instead of computing the characteristic impedance matrix and its inverse as is done in XTALK, the per-unit-length capacitance matrix and its inverse are computed here. The per-unit-length inductance matrix,  $\underline{L}$ , and capacitance matrix,  $\underline{C}$ , are related by

$$\underline{L} \underline{C} = \frac{1}{v^2} \underline{1}_n \quad (3-5a)$$

or

$$v \underline{C} = \frac{1}{v} \underline{L}^{-1} \quad (3-5b)$$

where  $v$  is the velocity of light in the surrounding medium given by

$$v = \frac{1}{\sqrt{\epsilon \mu}} = \frac{v_0}{\sqrt{\epsilon_r \mu_r}} \quad (3-5c)$$

$\epsilon$  is the permittivity of the medium,  $\mu$  is the permeability of the medium,  $v_0$  is the velocity of light in free space ( $v_0 = 3 \times 10^8$  m/sec) and  $\epsilon_r$  and  $\mu_r$  are the relative permittivity and permeability, respectively. The characteristic impedance matrix is given by

$$\underline{Z}_C = v \underline{L} \quad (3-6)$$

Therefore  $\underline{C}^{-1} = v \underline{Z}_C$ .  $\underline{C}$  is stored in array C and  $\underline{C}^{-1}$  is stored in array CI.

Cards 195 through 223 read and print the characteristics of the reference conductor and the  $n$  wires to be using in calculating their self impedances.

Cards 233 through 269 read and print the termination network character-

stics and are identical to the corresponding cards in XTALK.

Cards 275 through 332 perform certain frequency independent matrix multiplications for reasons similar to those given in 3.1 for the analogous group of cards. These cards form, for the Norton or Thevenin Equivalent characterizations, certain quantities in Tables 2 and 3:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
M1	$\underline{Y}_0 \underline{C}^{-1}$	$\underline{C} \underline{Z}_0$
M2	$\underline{Y}_L \underline{C}^{-1}$	$\underline{C} \underline{Z}_L$
V1	$\underline{I}_0$	$\underline{C} \underline{V}_0$
V2	$\underline{I}_L$	$\underline{C} \underline{V}_L$

Cards 328 through 332 form the sums of entries in each row of  $\underline{C}$  and are stored in the array V3.

Cards 336 through 340 read the frequency and form the quantities  $\omega=2\pi f$  and  $j\omega$ .

Cards 346 through 385 form the self impedances of the wires and the reference conductor. The equations for these self impedance terms are given in (2-42) through (2-49) in section 2.4. The self impedance of the reference conductor is stored as the complex variable  $Z_0$  and the self impedances of the  $n$  wires are temporarily stored in the array B.

Cards 391 through 398 compute the eigenvalues and eigenvectors of the product of the per-unit-length admittance and impedance matrices,  $\underline{YZ}$ . The per-unit-length admittance matrix is given by

$$\underline{Y} = j \omega \underline{C} \quad (3-7)$$

and the per-unit-length impedance matrix is given by

$$\underline{Z} = z_0 \underline{U}_n + \underline{Z}_D + j \omega \underline{L} \quad (3-8)$$

where  $\underline{U}_n$  is an  $n \times n$  unit matrix with ones in every position,  $z_0$  is the self impedance of the reference conductor and  $\underline{Z}_D$  is an  $n \times n$  diagonal matrix with the self impedance of the  $i$ -th wire in the  $i$ -th row and  $i$ -th column. The matrix product becomes (with the relation in (3-5a))

$$\underline{Y} \underline{Z} = j\omega \underline{C} [z_0 \underline{U}_n + \underline{Z}_D + j\omega \underline{L}] = j\omega z_0 \underline{C} \underline{U}_n + j\omega \underline{C} \underline{Z}_D - \frac{\omega^2}{2} \underline{1}_n \quad (3-9)$$

Note that  $\underline{C} \underline{U}_n$  is simply an  $n \times n$  matrix with the sum of all elements in the  $i$ -th row of  $\underline{C}$  in each of the entries in the  $i$ -th row of  $\underline{C} \underline{U}_n$ . These quantities were previously stored in the array V3. The subroutine EIGCC computes the  $n \times 1$  eigenvectors of  $\underline{Y} \underline{Z}$ ,  $\underline{T}_i$ , and their associated eigenvalues,  $\gamma_i^2$ . The matrix  $\underline{T} = [\underline{T}_1, \underline{T}_2, \dots, \underline{T}_n]$  will diagonalize  $\underline{Y} \underline{Z}$  as [1]

$$\underline{T}^{-1} \underline{Y} \underline{Z} \underline{T} = \underline{\gamma}^2 \quad (3-10)$$

where  $\underline{\gamma}^2$  is an  $n \times n$  diagonal matrix with  $\gamma_i^2$  in the  $i$ -th position on the main diagonal. This is required in Tables 2 and 3.  $\underline{T}$  is stored in array T and the  $n$  entries on the main diagonal of  $\underline{\gamma}^2$  are temporarily stored in the array B.

Cards 403 through 410 compute the inverse of  $\underline{T}$  which is stored in array TI.

Cards 416 through 448 compute certain other quantities in Tables 2 and 3. These are

Array	Norton	Thevenin
Y0	$\underline{Y}_0^* = \underline{T}^{-1} \underline{Y}_0 \underline{C}^{-1} \underline{T}$	$\underline{Z}_0^* = \underline{T}^{-1} \underline{C} \underline{Z}_0 \underline{T}$
YL	$\underline{Y}_L^* = \underline{T}^{-1} \underline{Y}_L \underline{C}^{-1} \underline{T}$	$\underline{Z}_L^* = \underline{T}^{-1} \underline{C} \underline{Z}_L \underline{T}$
I0	$\underline{I}_0^* = \underline{T}^{-1} \underline{I}_0$	$\underline{V}_0^* = \underline{T}^{-1} \underline{C} \underline{V}_0$
IL	$\underline{I}_L^* = \underline{T}^{-1} \underline{I}_L$	$-\underline{V}_L^* = -\underline{T}^{-1} \underline{C} \underline{V}_L$

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
EP	$E^+ = \frac{1}{2}(e^{\gamma L} + e^{-\gamma L})$	$E^+ = \frac{1}{2}(e^{\gamma L} + e^{-\gamma L})$
EN	$E^- = \frac{1}{2}(e^{\gamma L} - e^{-\gamma L})$	$E^- = \frac{1}{2}(e^{\gamma L} - e^{-\gamma L})$
G	$\Lambda = \frac{1}{j\omega} \gamma$	$\Lambda = \frac{1}{j\omega} \gamma$

Cards 449 through 458 form equation (1) in Tables 2 and 3. This equation is solved with subroutine LEQTIC in card 462 with the result stored in array B as:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
B	$\underline{V}^*(0)$	$\underline{I}^*(0)$

Cards 480 through 484 form equation (2) in Tables 2 and 3 with the result stored as

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
G	$\underline{V}^*(l)$	$\underline{I}^*(l)$

Cards 485 through 531 form the terminal voltages  $\underline{V}(0)$  and  $\underline{V}(l)$  by back transforming according to equation (9) in Tables 2 and 3.

### 3.3 Program FLATPAK

A listing of FLATPAK is given in Appendix C.

Cards 001 through 057 are similar to corresponding cards in the previous programs.

Cards 062 through 097 read a portion of the input data describing the structure of the line. The per-unit-length capacitance matrix,  $\underline{C}$ , (computed with GETCAP) is stored in array C. The per-unit-length capacitance matrix with the wire insulations removed,  $\underline{C}_0$ , (computed with GETCAP) is stored in array C0.

Cards 105 through 113 compute the eigenvectors and corresponding eigen-

Values of the matrix product  $\underline{C} \underline{L}$ . Subroutine NROOT computes the matrix such that

$$\underline{K}^{-1} \underline{C}^{-1} \underline{C}_0 \underline{K} = \underline{\psi} \quad (3-11)$$

such that  $\underline{\psi}$  is a diagonal matrix.  $\underline{K}$  is stored in array TI. The problem of interest is finding  $\underline{T}$  such that

$$\underline{T}^{-1} \underline{C} \underline{L} \underline{T} = \underline{\gamma}^2 \quad (3-12)$$

where

$$\underline{L} = \frac{1}{v_0^2} \underline{C}_0 \quad (3-13)$$

Taking the inverse of both sides of (3-11) results in

$$\underline{K}^{-1} \underline{C}_0^{-1} \underline{C} \underline{K} = \underline{\psi}^{-1} \quad (3-14)$$

Taking the transpose of both sides of (3-14) results in

$$\underline{K}^t \underline{C} \underline{C}_0^{-1} \underline{K}^{-1t} = \underline{\psi}^{-1} \quad (3-15)$$

(Since  $\underline{C}$  and  $\underline{C}_0$  are symmetric,  $\underline{C}^t = \underline{C}$  and  $\underline{C}_0^{-1t} = \underline{C}_0^{-1}$ . Also  $\underline{\psi}$  is diagonal. Therefore  $\underline{\psi}^{-1t} = \underline{\psi}^{-1}$ .) Thus comparing (3-15) to (3-12) and using (3-13) we identify

$$\underline{K} = \underline{T}^{-1t} \quad (3-16a)$$

$$\frac{1}{v_0^2} \underline{\psi}^{-1} = \underline{\gamma}^2 \quad (3-16b)$$

and  $\underline{T}^{-1t}$  is stored in array C and array G contains the square roots of entries on the main diagonal of  $\underline{\gamma}^2$ ,  $\underline{\gamma}$ .

Cards 114 through 128 compute  $\underline{T}$  and  $\underline{\gamma}^{-1}$  if the Thevenin Equivalent characterization is chosen. Thus, contained in arrays TI and G are:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
TI	$\tilde{T}^{-1t}$	$\tilde{T}$
G	$\tilde{Y}$	$\tilde{Y}^{-1}$

Cards 138 through 175 read and print the termination network characteristics and are identical to the corresponding cards in the previous programs.

Cards 182 through 220 form the following frequency independent quantities (see Tables 2 and 3)

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
Y0	$\tilde{Y}_0^* = \tilde{T}^{-1} \tilde{Y}_0 \tilde{C}^{-1} \tilde{T}$	$\tilde{Z}_0^* = \tilde{T}^{-1} \tilde{C} \tilde{Z}_0 \tilde{T}$
YL	$\tilde{Y}_l^* = \tilde{T}^{-1} \tilde{Y}_l \tilde{C}^{-1} \tilde{T}$	$\tilde{Z}_l^* = \tilde{T}^{-1} \tilde{C} \tilde{Z}_l \tilde{T}$
I0	$\tilde{I}_0^* = \tilde{T}^{-1} \tilde{I}_0$	$\tilde{V}_0^* = \tilde{T}^{-1} \tilde{C} \tilde{V}_0$
IL	$\tilde{I}_l^* = \tilde{T}^{-1} \tilde{I}_l$	$-\tilde{V}_l^* = -\tilde{T}^{-1} \tilde{C} \tilde{V}_l$

Since  $\tilde{T}^{-1}$  satisfies

$$\tilde{T}^{-1} = \tilde{T}^t \tilde{C}^{-1} \quad (3-17)$$

then

$$\tilde{T}^{-1t} = \tilde{C}^{-1} \tilde{T} \quad (3-18)$$

and these relations allow the entries in the arrays Y0, YL, I0 and IL to be more easily generated as:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
Y0	$\tilde{Y}_0^* = \tilde{T}^{-1} \tilde{Y}_0 \tilde{T}^{-1t}$	$\tilde{Z}_0^* = \tilde{T}^t \tilde{Z}_0 \tilde{T}$
YL	$\tilde{Y}_l^* = \tilde{T}^{-1} \tilde{Y}_l \tilde{T}^{-1t}$	$\tilde{Z}_l^* = \tilde{T}^t \tilde{Z}_l \tilde{T}$
I0	$\tilde{I}_0^* = \tilde{T}^{-1} \tilde{I}_0$	$\tilde{V}_0^* = \tilde{T}^t \tilde{V}_0$
IL	$\tilde{I}_l^* = \tilde{T}^{-1} \tilde{I}_l$	$-\tilde{V}_l^* = -\tilde{T}^t \tilde{V}_l$

Cards 224 through 227 read the frequency and compute  $\omega = 2\pi f$ .

Cards 233 through 248 form equation (1) in Tables 2 and 3.

Equation (1) in Tables 2 and 3 is solved with subroutine LEQT1C in card 252.

Cards 264 through 268 form equation (2) in Tables 2 and 3. The arrays B and WA now contain, with respect to Tables 2 and 3:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
B	$\underline{V}^*(0)$	$\underline{I}^*(0)$
WA	$\underline{V}^*(z)$	$\underline{I}^*(z)$

The terminal voltages,  $\underline{V}(0)$  and  $\underline{V}(z)$  are computed in cards 269 through 286 by back transforming  $\underline{V}^*(0)$  and  $\underline{V}^*(z)$  through (see Tables 2 and 3)

<u>Norton</u>	<u>Thevenin</u>
$\underline{V}(0) = \underline{C}^{-1} \underline{T} \underline{V}^*(0)$	$\underline{V}^*(0) = \underline{V}_0^* - \underline{Z}_0^* \underline{I}^*(0)$
$= \underline{T}^{-1t} \underline{V}^*(0)$	
$\underline{V}(z) = \underline{C}^{-1} \underline{T} \underline{V}^*(z)$	$\underline{V}(0) = \underline{C}^{-1} \underline{T} \underline{V}^*(0)$
$= \underline{T}^{-1t} \underline{V}^*(z)$	$= \underline{T}^{-1t} \underline{V}^*(0)$
	$\underline{V}^*(z) = \underline{V}_z^* + \underline{Z}_z^* \underline{I}^*(z)$
	$\underline{V}(z) = \underline{C}^{-1} \underline{T} \underline{V}^*(z)$
	$= \underline{T}^{-1t} \underline{V}^*(z)$

Cards 287 through 301 print the resulting terminal voltages.

### 3.4 Program FLATPAK2

A listing of FLATPAK2 is given in Appendix D.

Cards 001 through 106 are similar to corresponding cards (001 through 097) in FLATPAK.

Cards 112 through 133 compute the inverse of the per-unit-length

capacitance matrix which is stored in array C1. The per-unit-length inductance matrix,  $\underline{L}$ , is also computed from the relation

$$\underline{L} = \frac{1}{v^2} \underline{C}_0^{-1} \quad (3-19)$$

Cards 138 through 144 read the characteristics of the wires in the ribbon cable (all wires are assumed to be identical) for use in computing their self impedances.

Cards 154 through 191 read and print the characteristics of the termination networks and are identical to the corresponding cards in the previous programs.

Cards 197 through 262 form certain frequency independent quantities in Tables 2 and 3:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
M1	$\underline{Y}_0 \underline{C}^{-1}$	$\underline{C} \underline{Z}_0$
M2	$\underline{Y}_l \underline{C}^{-1}$	$\underline{C} \underline{Z}_l$
V1	$\underline{I}_0$	$\underline{C} \underline{V}_0$
V2	$\underline{I}_l$	$\underline{C} \underline{V}_l$

Cards 251 through 262 form the quantities  $\underline{C} \underline{L}$  which is stored in array C0 and the sums of the elements in the i-th row of  $\underline{C}$  which are stored in array V3.

Cards 266 through 270 read the frequency and form  $\omega = 2\pi f$  and  $j\omega$ .

Cards 274 through 283 form the self impedances of the wires which are stored in the complex variable Z (all wires are identical).

Cards 289 through 295 compute the transformation matrix  $\underline{T}$  such that

$$\underline{T}^{-1} \underline{Y} \underline{Z} \underline{T} = \underline{Y}^2 \quad (3-20)$$



where  $\underline{\gamma}^2$  is a diagonal matrix and

$$\begin{aligned} \underline{Y} \underline{Z} &= j\omega \underline{C} (z \underline{U}_n + z \underline{1}_n + j\omega \underline{L}) \\ &= j\omega z \underline{C} \underline{U}_n + j\omega z \underline{C} - \omega^2 \underline{C} \underline{L} \end{aligned} \quad (3-21)$$

Subroutine EIGCC computes  $\underline{T}$  and stores it in array T and stores the entries on the main diagonal of  $\underline{\gamma}^2$  temporarily in Array B.

The inverse of  $\underline{T}$  is computed with LEQT1C in cards 300 through 307 and is stored in array TI.

Cards 313 through 345 compute certain quantities in Tables 2 and 3:

<u>Array</u>	<u>Norton</u>	<u>Thevenin</u>
Y0	$\underline{Y}_0^* = \underline{T}^{-1} \underline{Y}_0 \underline{C}^{-1} \underline{T}$	$\underline{Z}_0^* = \underline{T}^{-1} \underline{C} \underline{Z}_0 \underline{T}$
YL	$\underline{Y}_L^* = \underline{T}^{-1} \underline{Y}_L \underline{C}^{-1} \underline{T}$	$\underline{Z}_L^* = \underline{T}^{-1} \underline{C} \underline{Z}_L \underline{T}$
IO	$\underline{I}_0^* = \underline{T}^{-1} \underline{I}_0$	$\underline{V}_0^* = \underline{T}^{-1} \underline{C} \underline{V}_0$
IL	$\underline{I}_L^* = \underline{T}^{-1} \underline{I}_L$	$-\underline{V}_L^* = -\underline{T}^{-1} \underline{C} \underline{V}_L$
EP	$\underline{E}^+ = \frac{1}{2}(e^{-\underline{Y}z} + e^{-\underline{Y}z})$	$\underline{E}^+ = \frac{1}{2}(e^{-\underline{Y}z} + e^{-\underline{Y}z})$
EN	$\underline{E}^- = \frac{1}{2}(e^{-\underline{Y}z} - e^{-\underline{Y}z})$	$\underline{E}^- = \frac{1}{2}(e^{-\underline{Y}z} - e^{-\underline{Y}z})$
G	$\underline{\Lambda} = \frac{1}{j\omega} \underline{\gamma}$	$\underline{\Lambda} = \frac{1}{j\omega} \underline{\gamma}$

Cards 346 through 355 form equation (1) in Tables 2 and 3 which is solved with subroutine LEQT1C in card 359.

Cards 376 through 380 form equation (2) in Tables 2 and 3. Thus the arrays B and G contain:

<u>Arrays</u>	<u>Norton</u>	<u>Thevenin</u>
B	$\underline{V}^*(0)$	$\underline{I}^*(0)$
G	$\underline{V}^*(z)$	$\underline{I}^*(z)$

Cards 381 through 406 form  $\underline{V}(0)$  and  $\underline{V}(z)$  by back transforming  $\underline{V}^*(0)$  and  $\underline{V}^*(z)$  as described in FLATPAK using the relations in Table 2 and Table 3:

$$\underline{V}(0) = \underline{C}^{-1} \underline{T} \underline{V}^*(0)$$

$$\underline{V}(z) = \underline{C}^{-1} \underline{T} \underline{V}^*(z)$$

Cards 407 through 427 print the terminal voltages.

### 3.5 Required Subroutines

The four programs require certain subroutines: LEQT1C, EIGCC, NROOT, and EIGEN. The individual programs require:

<u>Program</u>	<u>Required Subroutines</u>
XTALK	LEQT1C
XTALK2	LEQT1C, EIGCC
FLATPAK	LEQT1C, NROOT, EIGEN
FLATPAK2	LEQT1C, EIGCC

The required subroutines must follow the main program and precede the data cards.

#### 3.5.1 Subroutine LEQT1C

Subroutine LEQT1C is a general subroutine for solving a system of  $n$  simultaneous, complex equations. The program is a part of the IMSL (International Mathematical and Statistical Library) package [9].

The subroutine solves the system of equations

$$\underline{A} \underline{X} = \underline{B} \quad (3-22)$$

where  $\underline{A}$  is an  $n \times n$  complex matrix,  $\underline{B}$  is an  $n \times m$  complex matrix and  $\underline{X}$  is an  $n \times m$  complex matrix whose columns,  $\underline{X}_i$ , are solutions to

$$\underline{A} \underline{X}_i = \underline{B}_i \quad (3-23)$$

where  $\underline{B}_i$  is the  $i$ -th column of  $\underline{B}$ .

The calling statement is

```
CALL LEQT1C(A,N,N,B,N,M,WA,IER)
```

where

$\underline{A} \rightarrow \underline{A}$

$\underline{B} \rightarrow \underline{B}$

$N \rightarrow n$

$M \rightarrow m$

and WA is a complex working vector of length  $n$ . IER is an error parameter which is returned as<sup>1</sup>

IER = 128  $\rightarrow$  no solution error

IER = 129  $\rightarrow$   $\underline{A}$  is algorithmically singular [9].

The solution  $\underline{X}$  is returned in array B and the contents of array A are destroyed.

Subroutine LEQT1C can be used to find the inverse of an  $n \times n$  matrix by computing

$$\underline{A} \underline{X} = \underline{I}_n \quad (3-24)$$

where  $\underline{I}_n$  is the  $n \times n$  identity matrix. Thus the solution is  $\underline{X} = \underline{A}^{-1}$ . LEQT1C

<sup>1</sup>The solution error parameter is printed out whenever LEQT1C is used. The printed error is IER-128 so that the solution error should be 0.

is used in numerous places to invert real matrices by defining the real part of  $\underline{A}$  to be the matrix and the imaginary part to be zero. Upon solution, the real part of  $\underline{X}$  is the inverse of the real matrix,  $\underline{A}$ .

### 3.5.2 Subroutine EIGCC

Subroutine EIGCC is also a part of the IMSL subroutine package [9] and is used to find the eigenvalues and eigenvectors of an  $n \times n$  complex matrix,  $\underline{M}$ . Denote the  $n \times 1$  (complex) eigenvectors,  $\underline{T}_i$ , of  $\underline{M}$  as  $\underline{T}_1, \underline{T}_2, \dots, \underline{T}_n$  and the corresponding (complex) eigenvalues as  $b_1, b_2, \dots, b_n$ . EIGCC computes the  $n \times n$  matrix  $\underline{T} = [\underline{T}_1, \underline{T}_2, \underline{T}_3, \dots, \underline{T}_n]$  such that

$$\underline{T}^{-1} \underline{M} \underline{T} = \underline{B} \quad (3-25)$$

where  $\underline{B}$  is an  $n \times n$  diagonal matrix with  $[\underline{B}]_{ii} = b_i$  and  $[\underline{B}]_{ij} = 0$  for  $i, j=1, \dots, n$  and  $i \neq j$ .

The calling statement is

```
CALL EIGCC(M,N,N,2,B,T,WK,IER)
```

where WK is a real working vector of length  $2n(n+1)$ . IER is an error parameter which is returned as  $IER = 128 + J$ <sup>1</sup>. This indicates that the routine failed to converge on the  $j$ -th eigenvalue [9]. The precision of the eigenvector, eigenvalue solution is returned in the first position of array WK, WK(1), and indicates [9]

	<u>Solution Precision</u>
WK (1) < 1	→ Excellent
1 < WK (1) < 100	→ Good
WK (1) > 100	→ Poor

<sup>1</sup>The solution error is printed out as IER-128. A successful solution would then be indicated by 0.

The matrix  $\underline{T}$  is stored in the  $n \times n$  array  $T$  and the eigenvalues,  $b_i$ , are stored in the  $n \times 1$  array  $B$  in the same order as the columns of  $T$ .

### 3.5.3 Subroutines NROOT and EIGEN

Subroutines NROOT and EIGEN are a set of subroutines from the IBM Scientific Subroutine Package (SSP) [10] which compute the eigenvectors and eigenvalues of the matrix product

$$\underline{B}^{-1} \underline{A} \quad (3-26)$$

where  $\underline{A}$  and  $\underline{B}$  are  $n \times n$  real, symmetric matrices and  $\underline{B}$  is positive definite. A listing of NROOT is provided in Appendix E and a listing of EIGEN is provided in Appendix F. These subroutines are used to find the eigenvalues and eigenvectors of the product of the per-unit-length capacitance,  $\underline{C}$ , and inductance,  $\underline{L}$ , matrices as

$$\underline{C} \underline{L} \quad (3-27)$$

Subroutine NROOT calls subroutine EIGEN.

NROOT computes the  $n \times n$  real matrix  $\underline{T}$  such that

$$\underline{T}^{-1} \underline{B}^{-1} \underline{A} \underline{T} = \underline{G} \quad (3-28)$$

where  $\underline{G}$  is an  $n \times n$  diagonal matrix with  $[\underline{G}]_{ii} = g_i$  and  $[\underline{G}]_{ij} = 0$  for  $i, j=1, \dots, n$  and  $i \neq j$ . The eigenvectors  $\underline{T}_i$  correspond to the eigenvalues  $g_i$  and  $\underline{T} = [\underline{T}_1, \underline{T}_2, \dots, \underline{T}_n]$ .

The calling statement is

```
CALL NROOT(N,A,B,G,T,N*N)
```

where

Array

A → A  
~  
B → B  
~  
N → n  
G → G  
~  
T → T  
~

The  $n \times 1$  array  $G$  returns the eigenvalues  $g_i$  in the same sequence as the columns (corresponding eigenvectors) of  $T$ .

The subroutine operates in the following manner [1,11]. NROOT first computes the  $n \times n$ , real, orthogonal transformation matrix  $S$  such that

$$(\underline{S}^{-1} = \underline{S}^t)$$

$$\underline{S}^t \underline{B} \underline{S} = \underline{H} \quad (3-29)$$

where  $\underline{H}$  is an  $n \times n$  diagonal matrix with  $[\underline{H}]_{ii} = h_i$  and  $[\underline{H}]_{ij} = 0$  for  $i, j=1, \dots, n$ . EIGEN is called for this calculation. Since  $\underline{B}$  is real, symmetric, positive definite, the eigenvalues of  $\underline{B}$ ,  $h_i$ , are real, nonzero and positive. Therefore NROOT forms the square root of  $\underline{H}$ ,  $\underline{H}^{1/2}$  and its inverse  $\underline{H}^{-1/2}$ .

NROOT then forms the products

$$\underline{M} = \underline{S} \underline{H}^{-1/2} \quad (3-30)$$

and

$$\underline{M}^t \underline{A} \underline{M} \quad (3-31)$$

which is real, symmetric. NROOT calls EIGEN once again to find the  $n \times n$  real, orthogonal matrix  $\underline{W}$  such that  $(\underline{W}^{-1} = \underline{W}^t)$

$$\underline{W}^t [\underline{M}^t \underline{A} \underline{M}] \underline{W} = \underline{G} \quad (3-32)$$

and  $\underline{G}$  is diagonal. The transformation matrix  $\underline{T}$  is given by

$$\underline{T} = \underline{S} \underline{H}^{-1/2} \underline{W} \quad (3-33)$$

To show that  $\underline{T}$  in fact diagonalizes  $\underline{B}^{-1} \underline{A}$ , form

$$\begin{aligned} \underline{T}^{-1} \underline{B}^{-1} \underline{A} \underline{T} &= \\ \underline{W}^t \underline{H}^{1/2} \underline{S}^t \underline{B}^{-1} \underline{A} \underline{S} \underline{H}^{-1/2} \underline{W} &= \\ \underbrace{\underline{W}^t \underline{H}^{1/2} \underline{S}^t \underline{B}^{-1} \underline{S} \underline{H}^{1/2}}_{\underline{I}} \underbrace{\underline{H}^{-1/2} \underline{S}^t \underline{A} \underline{S} \underline{H}^{-1/2}}_{\underline{M}^t \underline{A} \underline{M}} \underline{W} &= \underline{G} \end{aligned} \quad (3-34)$$

The NROOT subroutine used in the program FLATPAK and shown in Appendix G is slightly different from the NROOT subroutine given in SSP [10]. The difference is that the eigenvectors in NROOT in Appendix G are not normalized. This is required for NROOT to be used in FLATPAK so that the transformation matrix  $\underline{T}$  which diagonalizes the matrix product  $\underline{C} \underline{L}$  as

$$\underline{T}^{-1} \underline{C} \underline{L} \underline{T} = \underline{\gamma}^2 \quad (3-35)$$

will satisfy the identity

$$\underline{T}^{-1} = \underline{T}^t \underline{C}^{-1} \quad (3-36)$$

If the columns of  $\underline{T}$  (the eigenvectors) are normalized, (3-36) will no longer be true.

#### IV. USER'S MANUAL

This section will serve as a user's manual for the use of the programs. All input data are punched on cards which must follow the main program (and any subroutines). The format of the data input cards as well as suggestions for program useage are included. All of the programs require three groups of data input:

Group I	{	Transmission Line Structure Characteristics Cards	}
Group II	{	Termination Network Characterization Cards Group II(a) Group II(b)	}
Group III	{	Frequency Cards	}

These card groups must follow the main program (and any required subroutines) in the above order. The data entries are either in Integer (I) format, e.g., 35, or in Exponential (E) format, e.g., 12.6E-3. All data entries must be right-justified in the assigned card column block.

In all four programs, the user must appropriately dimension all arrays for each problem. Comment cards are provided at the beginning of each program to assist the user in providing proper dimensions. All arrays must be properly dimensioned by repunching the dimension statement cards in a program before using the program.

##### 4.1 The Frequency Cards, Group III

Each frequency card contains one and only one frequency for which an analysis is desired. The format of the frequency card is shown in Table 4. The frequency in Hertz is punched in columns 1-10 of each card and must be



TABLE 4

Format of the Frequency Group Cards, Group III

frequency (Hertz)	<u>card column</u>	<u>format</u>
	1-10	E

Total number = unlimited

right justified in the card block consisting of card columns 1-10. For example, if one wished to input a frequency of 1 M Hz, one may punch

```
          1 . E 6
          ↑ ↑ ↑ ↑
card columns 7 8 9 10
```

If, instead, the frequency was punched as

```
          1 . E 6
          ↑ ↑ ↑ ↑
card columns 6 7 8 9
```

The program would take this to be a frequency of  $10^{60}$  Hertz (zeros are added to fill out the assigned card block). This right-justification of data in an assigned card block applies to all other data entries.

More than one frequency card may be included in the frequency card group. Each program will process the data provided by Groups I and II and compute the response at the frequency on the first frequency card. It will then recompute the response at each frequency on the remaining frequency cards. The program assumes that the data on card Groups I and II are to be used for all the remaining frequencies. If this is not intended by the user, then one may only run the program for one frequency at a time. This feature, however, can be quite useful. If the termination networks are purely resistive, i.e., frequency independent, then one may use as many frequency cards as desired in this frequency card group and the program will compute the response of the line at each frequency without the necessity for the user to input the data in Groups I and II for each additional frequency. Many of the time-consuming calculations which are independent of frequency need to be computed

only once so that this mode of useage will save considerable computation time when the response at many frequencies is desired. If, however, the termination network characteristics (in Group II) are complex (which implies frequency dependent), one must run the program for only one frequency at a time.

#### 4.2 The Termination Network Characterization Cards, Group II

This group of cards conveys the terminal characteristics of the termination networks at the ends of the line,  $x = 0$  and  $x = \mathcal{L}$ . The termination networks are characterized by either the Thevenin Equivalent or the Norton Equivalent characterization. These characterizations are of the form

$$\left. \begin{aligned} \underline{V}(0) &= \underline{V}_0 - \underline{Z}_0 \underline{I}(0) \\ \underline{V}(\mathcal{L}) &= \underline{V}_{\mathcal{L}} + \underline{Z}_{\mathcal{L}} \underline{I}(\mathcal{L}) \end{aligned} \right\} \begin{array}{l} \text{Thevenin} \\ \text{Equivalent} \end{array} \quad (4-1a)$$

$$\left. \begin{aligned} \underline{I}(0) &= \underline{I}_0 - \underline{Y}_0 \underline{V}(0) \\ \underline{I}(\mathcal{L}) &= -\underline{I}_{\mathcal{L}} + \underline{Y}_{\mathcal{L}} \underline{V}(\mathcal{L}) \end{aligned} \right\} \begin{array}{l} \text{Norton} \\ \text{Equivalent} \end{array} \quad (4-1b)$$

and are discussed in detail in section 2.3. The transmission line consists of  $n$  wires which are numbered from 1 to  $n$  and a reference conductor for the line voltages. The reference conductor is numbered as the zero (0) conductor. Thus  $\underline{V}_0, \underline{V}_{\mathcal{L}}, \underline{I}_0, \underline{I}_{\mathcal{L}}$  are  $n \times 1$  vectors and  $\underline{Z}_0, \underline{Z}_{\mathcal{L}}, \underline{Y}_0, \underline{Y}_{\mathcal{L}}$  are  $n \times n$  matrices which are assumed to be symmetric.

The impedance or admittance matrices,  $\underline{Z}_0$  and  $\underline{Z}_{\mathcal{L}}$  or  $\underline{Y}_0$  and  $\underline{Y}_{\mathcal{L}}$ , respectively, may either be "full" in which all entries are not necessarily zero or may be diagonal in which only the entries on the main diagonals are not necessarily zero and the off-diagonal entries are zero. The user may select one of four options for communicating the entries in the vectors and matrices in

2). These are:

- OPTION = 11      { Thevenin Equivalent representation;  
diagonal impedance matrices,  $Z_0$  and  $Z_x$ . }
- OPTION = 12      { Thevenin Equivalent representation;  
full impedance matrices,  $Z_0$  and  $Z_x$ . }
- OPTION = 21      { Norton Equivalent representation;  
diagonal admittance matrices,  $Y_0$  and  $Y_x$ . }
- OPTION = 22      { Norton Equivalent representation;  
full admittance matrices,  $Y_0$  and  $Y_x$ . }

The structure and ordering of the data in Group II are given in Table 5 and can be summarized in the following manner. The first group of cards in Group II, Group II(a), will describe the entries on the main diagonal in  $Y_0(Z_0)$ ,  $Y_{0ii}(Z_{0ii})$ , and  $Y_x(Z_x)$ ,  $Y_{xii}(Z_{xii})$ , and the entries in  $I_0(V_0)$ ,  $I_{0i}(V_{0i})$ , and  $I_x(V_x)$ ,  $I_{xi}(V_{xi})$ . These cards must be in the order from  $i = 1$  to  $i = n$ . Each of these entries is in general, complex. Therefore two card blocks are assigned for each entry; one for the real part and one for the imaginary part. For example, consider a 4 conductor line (3 wires and a reference conductor). Here  $n$  would be 3. Suppose the Thevenin Equivalent characterization is selected, with the following entries in the characterization matrices:

$$V_0 = \begin{bmatrix} 1 + j2 \\ 3 + j5 \\ 6 + j4 \end{bmatrix}$$

$$Z_0 = \begin{bmatrix} 7+j8 & 0 & 0 \\ 0 & j9 & 0 \\ 0 & 0 & 10+j11 \end{bmatrix}$$

$$V_x = \begin{bmatrix} 12 \\ j13 \\ 14+j15 \end{bmatrix}$$

$$Z_x = \begin{bmatrix} 16 & 0 & 0 \\ 0 & 17+j18 & 0 \\ 0 & 0 & j19 \end{bmatrix}$$

TABLE 5 (cont.)

Format of the Termination Network Characterization Cards, Group II

<u>Group II(a) (total = n)</u>		<u>card column</u>	<u>format</u>	
$Y_{0ii}(Z_{0ii})$	{	real part	1-10	E
	}	imaginary part	11-20	E
$I_{0i}(V_{0i})$	{	real part	21-30	E
	}	imaginary part	31-40	E
$Y_{1ii}(Z_{1ii})$	{	real part	41-50	E
	}	imaginary part	51-60	E
$I_{1i}(V_{1i})$	{	real part	61-70	E
	}	imaginary part	71-80	E

Note: A total of n cards must be present for an n wire line and must be arranged in the order:

- wire 1
- wire 2
- .
- .
- .
- wire n

TABLE 5

Group II(b) (  $\left. \begin{array}{l} \text{total} = n(n-1)/2 \text{ if OPTION} = 12 \text{ or } 22 \\ \text{total} = 0 \text{ if OPTION} = 11 \text{ or } 21 \end{array} \right\}$  )

	<u>card column</u>	<u>format</u>	
$Y_{0ij}(Z_{0ij})$	{ real part	1-10	E
	{ imaginary part	11-20	E
$Y_{1ij}(Z_{1ij})$	{ real part	41-50	E
	{ imaginary part	51-60	E

Note: If OPTION = 12 or 22, a total of  $n(n-1)/2$  cards must be present and must follow Group II(a). If OPTION = 11 or 21, this card group is omitted. The cards must be arranged so as to describe the entries in the upper triangle portion of  $Y_0(Z_0)$  and  $Y_1(Z_1)$  by rows, i.e., the cards must contain the 12 entries, the 13 entries, ---, the  $ln$  entries, the 23 entries, ---, the  $2n$  entries, ---- etc. The ordering of the cards is therefore:

wires 1,2  
wires 1,3  
.  
.  
wires 1,n  
wires 2,3  
wires 2,4  
.  
.  
wires 2,n  
.  
.  
wires (n-1), n

One would have selected OPTION 11. The n=3 cards would be arranged (in this order)

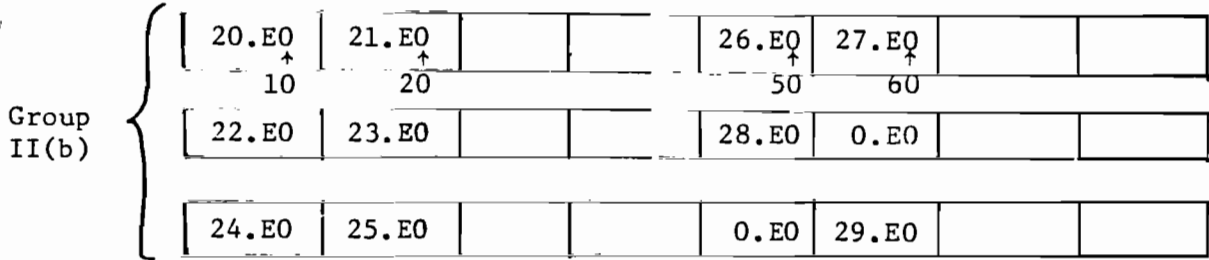
Group II(a)	7.E0	8.E0	1.E0	2.E0	16.E0	0.E0	12.E0	0.E0
	↑	↑	↑	↑	↑	↑	↑	↑
	10	20	30	40	50	60	70	80
	0.E0	9.E0	3.E0	5.E0	17.E0	18.E0	0.E0	13.E0
	10.E0	11.E0	6.E0	4.E0	0.E0	19.E0	14.E0	15.E0

If the terminal impedance matrices were not diagonal, e.g., OPTION 12 is selected, then  $n(n-1)/2$  additional cards, Group II(b), would follow the above n cards comprising Group II(a). These cards describe the entries in the upper triangle portion of the termination impedance or admittance matrices by rows. Suppose the networks are characterized by the same  $\underline{V}_0$  and  $\underline{V}_L$  vectors as above but the  $\underline{Z}_0$  and  $\underline{Z}_L$  matrices are

$$\underline{Z}_0 = \begin{bmatrix} 7 + j8 & 20 + j21 & 22 + j23 \\ 20 + j21 & j9 & 24 + j25 \\ 22 + j23 & 24 + j25 & 10 + j11 \end{bmatrix}$$

$$\underline{Z}_L = \begin{bmatrix} 16 & 26 + j27 & 28 \\ 26 + j27 & 17 + j18 & j29 \\ 28 & j29 & j19 \end{bmatrix}$$

The following  $n(n-1)/2 = 3$  cards must follow the above 3 cards in the order of the 12 entries first, the 13 entries next and then the 23 entries:



### 4.3 Program XTALK

XTALK considers (n+1) conductor transmission lines consisting of n wires in a lossless, homogeneous surrounding medium and a reference conductor for the line voltages. The n wires and the reference conductor are considered to be perfect (lossless) conductors. There are three choices for the reference conductor type:

- TYPE = 1: The reference conductor is a wire.
- TYPE = 2: The reference conductor is an infinite ground plane.
- TYPE = 3: The reference conductor is an overall cylindrical shield.

Cross-sectional views of each of these three structure types are shown in Figure 4-1, 4-2 and 4-3, respectively.

For the TYPE 1 structure shown in Figure 4-1, an arbitrary rectangular coordinate system is established with the center of the coordinate system at the center of the reference conductor. The radii of all (n+1) wires,  $r_{wi}$ , as well as the Z and Y coordinates of each of the n wires serve to completely describe the structure. Negative coordinate values must be input as negative data items. For example,  $Z_i$  and  $Y_j$  in Figure 4-1 would be negative numbers.



TYPE = 1

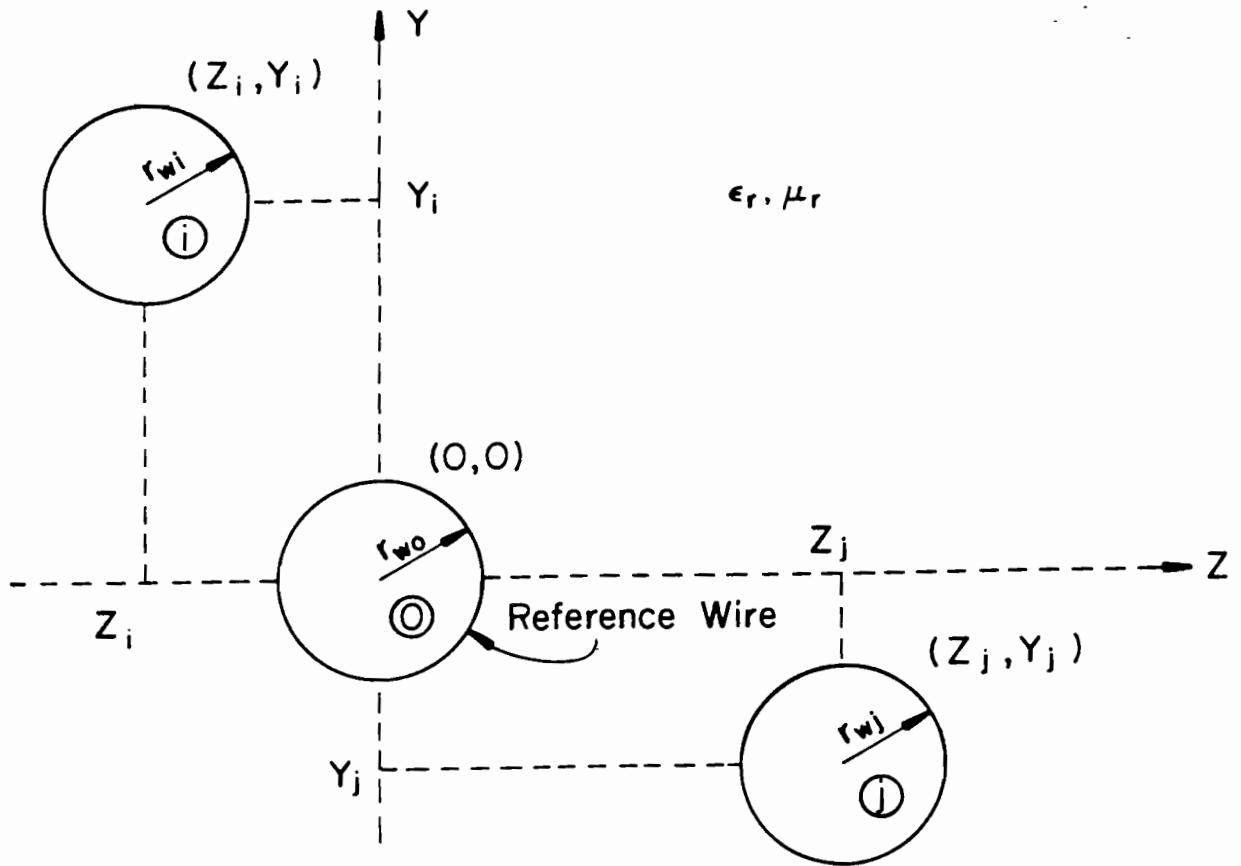


Figure 4-1. Type 1 structure.

TYPE = 2

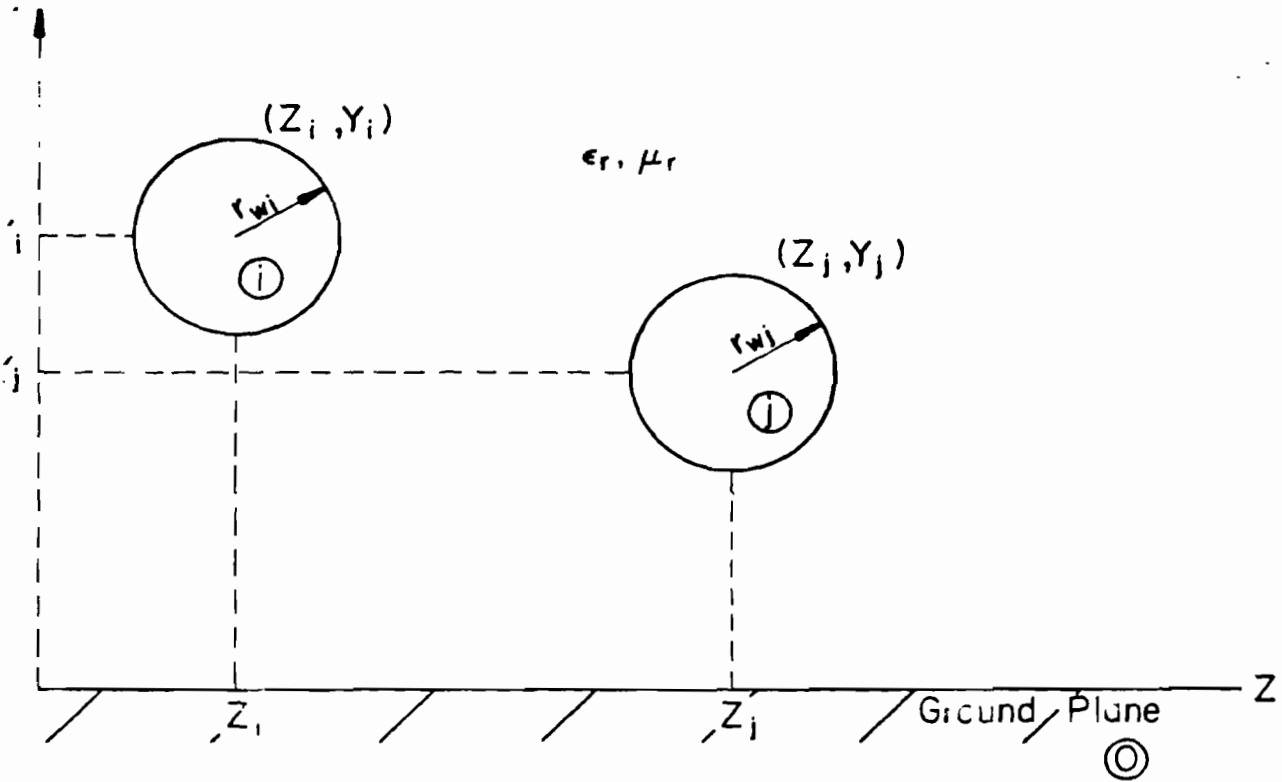


Figure 4-2. Type 2 structure.

TYPE = 3

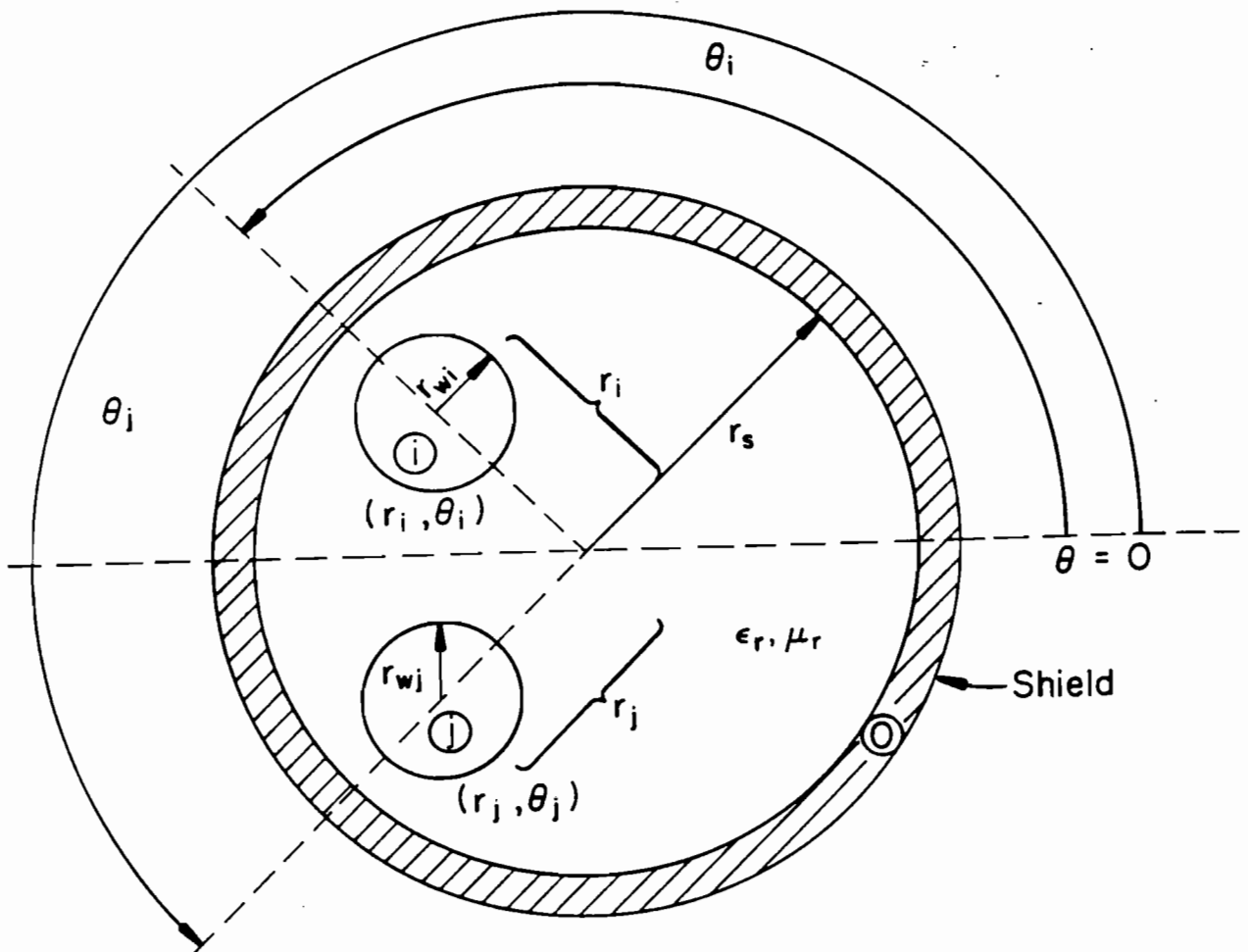


Figure 4-3. Type 3 structure.

For the TYPE 2 structure shown in Figure 4-2, an arbitrary coordinate system is established with the ground plane as the Z axis. The coordinates  $Y_i$  and  $Y_j$  (positive quantities) define the heights of the wires above the ground plane. The necessary data are the Z and Y coordinates and the radius,  $r_{wi}$ , of each wire.

For the TYPE 3 structure shown in Figure 4-3, an arbitrary angular coordinate system is established with the center of the coordinate system at the center of the shield. The necessary parameters are the radii of the wires,  $r_{wi}$ , the angular position,  $\theta_i$ , and the radial position,  $r_i$ , of each wire and the interior radius of the shield,  $r_s$ .

The format of the structural characteristics cards, Group I, are shown in TABLE 6. The first card contains the structure TYPE number (1,2,or 3), the load structure OPTION number (11,12,21, or 22), the number of wires, n, the relative dielectric constant of the surrounding medium (homogeneous),  $\epsilon_r$ , the relative permeability of the surrounding medium (homogeneous),  $\mu_r$ , and the total length of the transmission line,  $L$ , (meters). If TYPE 1 or 3 is selected, a second card is required which contains the radius of the reference wire,  $r_{w0}$ , (mils) for TYPE 1 structures or the interior radius of the shield,  $r_s$ , (meters) for TYPE 3 structures. For TYPE 2 structures, this card is absent. These cards are followed by n cards each of which contain the radii of the wires,  $r_{wi}$ , (mils) and the  $Z_i$  and  $Y_i$  coordinates of each wire (meters) for TYPE 1 and 2 structures or the angular coordinates  $r_i$  (meters) and  $\theta_i$  (degrees) of the i-th wire for TYPE 3 structures. These n cards must be arranged in the order  $i = 1, i = 2, \dots, i = n$ .

#### 4.4 Program XTALK2

XTALK2 considers the same structure types as XTALK. The only difference between the programs is that XTALK2 considers imperfect conductors. This

TABLE 6

Format of the Structure Characteristics Cards, Group I, for XTALK

<u>Card Group #1 (total = 1):</u>	<u>card column</u>	<u>format</u>
(a) TYPE (1,2,3)	10	I
(b) LOAD STRUCTURE OPTION (11,12,21, or 22)	19 - 20	I
(c) n (number of wires)	29 - 30	I
(d) $\epsilon_r$ (relative dielectric constant of the surrounding medium)	36 - 45	E
(e) $\mu_r$ (relative permeability of the surrounding medium)	51 - 60	E
(f) $\mathcal{L}$ (line length in meters)	66 - 75	E
<u>Card Group #2 (total = 1 if TYPE = 1 or 3, total = 0 if TYPE = 2)</u>		
(a) TYPE = 1: $r_{w0}$ (radius of reference wire in <u>mils</u> )	6 - 15	E
(b) TYPE = 2: absent		
(c) TYPE = 3: $r_s$ (interior radius of shield in <u>meters</u> )	6 - 15	E
<u>Card Group #3 (total = n)</u>		
(a) $r_{wi}$ (wire radius in <u>mils</u> )	6 - 15	E
(b) $Z_i$ for TYPE 1 or 2 in <u>meters</u> $r_i$ for TYPE 3 in <u>meters</u>	21 - 30	E
(c) $Y_i$ for TYPE 1 or 2 in <u>meters</u> $\theta_i$ for TYPE 3 in <u>degrees</u>	36 - 45	E

Note: Cards in Group #3 must be arranged in the order:

wire 1  
wire 2  
.  
.  
wire n

requires an additional set of cards in Group I which must follow those in Table 6. The format of these cards is shown in Table 7.

#### 4.5 Program FLATPAK

FLATPAK considers  $(n+1)$  wire flatpak or ribbon cables as shown in Figure 4-4. The  $(n+1)$  wires are considered to be perfect conductors. In addition, the surrounding media are assumed to be lossless. The required cards in the Structure Characteristics card group, Group I, are shown in Table 8.

The first card is similar to the previous programs and communicates three items to the program. The first entry on the card is the number  $n$  which is the number of wires in the cable exclusive of the reference wire. The second entry on the card is the load structure option which is to be selected from the choices 11, 12, 21, or 22 as discussed in section 3.2. The third entry on this card is the total length of the cable in meters.

Card Group 2 concerns the entries in the per-unit-length capacitance matrix,  $\underline{C}$ , for the ribbon cable. Since  $\underline{C}$  is symmetric, it is only necessary to input the entries on the main diagonal of  $\underline{C}$  and the entries in the upper (or lower) triangle of  $\underline{C}$ . Computer program GETCAP [8] was designed to compute these items. GETCAP has the provision for providing a punched card output of the entries in  $\underline{C}$  in the form required by FLATPAK.

A few comments are in order to assist users of GETCAP. The program is documented in Volume II of this series [8]. However, some confusion as to the wire numbering sequence in GETCAP and FLATPAK may arise. The wires in the cable are numbered from left to right with numbers from 1 to  $N=n+1$  for use in the GETCAP program with the reference wire number chosen from this sequence. In the FLATPAK program, the wires are numbered from left to

TABLE 7 (Cont.)

Format of the Structure Characteristics Cards, Group I, for XTALK 2

<u>Card Group #1</u>	same as XTALK (TABLE 6)		
<u>Card Group #2</u>	same as XTALK (TABLE 6)		
<u>Card Group #3</u>	same as XTALK (TABLE 6)		
<u>Card Group #4</u> (total = 1)		<u>card column</u>	<u>format</u>
TYPE = 1: (a) radius of strands in reference wire ( <u>mils</u> )		6 - 15	E
(b) conductivity of strands ( <u>siemens/meter</u> )		21 - 30	E
(c) number of strands in reference wire		39 - 40	I
TYPE = 2: (a) per-unit-length resistance of ground plane ( <u>ohms/meter</u> )		6 - 15	E
(b) per-unit-length inductance of ground plane ( <u>henrys/meter</u> )		21 - 30	E
TYPE = 3: (a) thickness of shield ( <u>meters</u> )		6 - 15	E
(b) conductivity of shield ( <u>siemens/meter</u> )		21 - 30	E
<u>Card Group # 5</u> (total = n)			
(a) radius of wire strands ( <u>mils</u> )		6 - 15	E
(b) conductivity of wire strands ( <u>siemens/ meter</u> )		21 - 30	E
(c) number of strands in wire		39 - 40	I

NOTE: Cards in Group #5 must be arranged for wires from 1 to n.

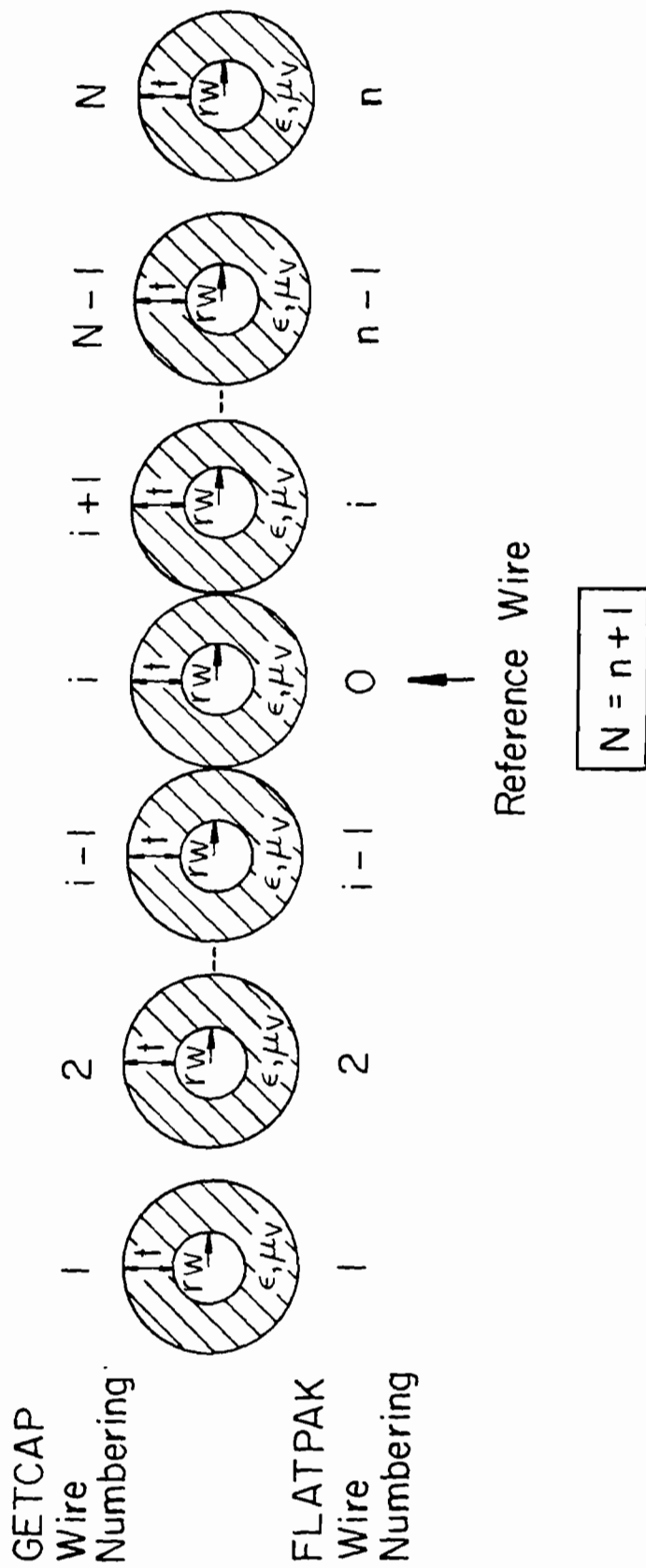


Figure 4-4. Wire numbering for ribbon (flatpack) cables.



TABLE 8

Format of the Structure Characteristics Cards, Group I, for FLATPAK

<u>Card Group #1</u> (total = 1)	<u>Card Column</u>	<u>Format</u>
(a) Number of wires (exclusive of the reference wire) (n)	9 - 10	I
(b) LOAD STRUCTURE OPTION (11,12,21, or 22)	19 - 20	I
(c) Line length ( <u>meters</u> ) $\mathcal{L}$	21 - 30	E
 <u>Card Group #2</u> (total = $n(n+1)/2$ )		
(a) i	5 - 6	I
(b) j	10 - 11	I
(c) $[C]_{ij}$ ( <u>farads/meter</u> ) (Entries in the per-unit-length transmission line capacitance matrix with the wire dielectric insulations in place, computed with GETCAP)	14 - 26	E
 <u>Card Group #3</u> (total = $n(n+1)/2$ )		
(a) i	5 - 6	I
(b) j	10 - 11	I
(c) $[C_0]_{ij}$ ( <u>farads/meter</u> ) (Entries in the per-unit-length transmission line capacitance matrix with the wire dielectric insulations removed, computed with GETCAP)	14 - 26	E

with numbers from 1 to n with the reference wire numbered as the zero wire as shown in Figure 4-4. Whether the cross section of the cable figure 4-4 is at  $x=0$  looking to the right (increasing  $x$ ) or at  $x = L$  looking to the left (decreasing  $x$ ) is irrelevant so long as the user is consistent in using the same cross section for wire numbering in GETCAP and this program when assigning the load termination entries.

The third group of cards in Group I, Card Group #3, are the elements of the per-unit-length transmission line capacitance matrix computed with the electric insulations removed,  $C_0$ . GETCAP may be used to compute these matrices and provide punched card output for direct use as data input for FLATPAK.

#### Program FLATPAK 2

FLATPAK 2 considers  $(n+1)$  wire ribbon cables as in FLATPAK. However, FLATPAK 2 considers the  $(n+1)$  wires to be imperfect (lossy) conductors.

The format of the Structure Characteristic Cards, Group I, is shown in Figure 9. Only one additional card over those required for FLATPAK is needed. If all wires in the cable are assumed to be identical, this card describes the characteristics of these wires for use in computing the wire self impedances.

#### Examples of Program Useage

In this section, some typical examples will be shown to illustrate the use of the programs. Entries on the data cards as well as typical printouts of the results will be shown.

The terminal network structures for the examples are those comprising Examples 1, 2, 3, and 4 shown in Figure 2-4 and Figure 2-5. For Examples

TABLE 9

Format of the Structure Characteristics Cards, Group I, for FLATPAK 2

	<u>Card Column</u>	<u>Format</u>
<u>Card Group #1</u> same as FLATPAK		
<u>Card Group #2</u> same as FLATPAK		
<u>Card Group #3</u> same as FLATPAK		
<u>Card Group #4</u> (total = 1)		
(a) radius of wire strands ( <u>mils</u> )	6 - 15	E
(b) conductivity of wire strands ( <u>siemens/meter</u> )	21 - 30	E
(c) number of strands in each wire	39 - 40	I

1 and 2, the entries in the Thevenin Equivalent characterization matrices are given in (2-32) and the entries in the Norton Equivalent characterization matrices are given in (2-35). For Examples 3 and 4, the entries in the Norton Equivalent characterization matrices are given in (2-37) and the entries in the Thevenin Equivalent characterization matrices are given in (2-38).

The terminal voltages for each wire (with respect to the reference conductor) at  $x=0$  and  $x=l$  are the entries in  $\underline{V}(0)$  and  $\underline{V}(l)$ , respectively. The magnitudes and angles of the entries in  $\underline{V}(0)$  ( $\underline{V}(l)$ ) are denoted by VOM and VOA (VLM and VLA), respectively, on the computer printouts. Two frequencies will be considered, 10 MHz and 100 MHz.

#### 4.7.1 Examples of the XTALK Program

The transmission line structure chosen for all examples in this section is that of two wires with another wire as the reference conductor. The wire radii (mils) are 6.3 mils (thousands of a inch) for wires #1 and #2 with the reference wire of radius 6.3 mils. The three wires are in a linear array with  $Z_1 = 1.27$  mm,  $Y_1 = 0$ ,  $Z_2 = 2.54$  mm,  $Y_2 = 0$ . The line length is 5 meters and the relative dielectric constant is chosen (for the purpose of illustration) to be 3.0 with a relative permeability of 1.0.

The data cards are shown in Figure 4-5 through 4-8 and the printouts are shown in Figure 4-9 through 4-12.

#### 4.7.2 Examples of the XTALK 2 Program

The line considered for XTALK in 4.7.1 will be used here. Each wire will be stranded, copper ( $\sigma = 5.8 \times 10^7$ ) with 7 strands in each wire. The radius of each strand is 2.5 mils.

The data cards are shown in Figure 4-13 through 4-16 and the printouts are shown in Figure 4-17 through 4-20.

#### 4.7.3 Examples of the FLATPAK Program

A three wire ribbon cable will be considered. The wire radii are .16002 mm, the insulation thicknesses are .3479 mm and the center-to-center separations of the wires are 1.27 mm. The insulations are polyvinyl chloride and a relative dielectric constant of 3.5 is assumed. The reference wire is the middle wire in the cable. The elements in the per-unit-length capacitance matrix (with and without the dielectric insulations) were computed with GETCAP [8].

The data cards are shown in Figure 4-21 through 4-24 and the printouts are shown in Figure 4-25 through 4-28.

#### 4.7.4 Examples of the FLATPAK 2 Program

The three wire ribbon cable considered in the previous section with the FLATPAK program will be investigated. Each wire is stranded with 7 strands (copper) and each strand is of radius 2.5 mils.

The data cards are shown in Figure 4-29 through 4-32 and the printouts are shown in Figure 4-33 through 4-36.











```

XALK
2 PARALLEL LINES
TYPE OF STRUCTURE 1
LINE STRUCTURE OPTION 11
LINE LENGTH 5000000 CM METERS
ELECTRIC CONSTANT OF THE MEDIUM 3.0000000
PERMITTIVITY OF THE MEDIUM 1.0000000
VOLTAGE SOURCE AT 450 WITH RADIUS 5000000 CM
X COORDINATE (METERS) Y COORDINATE (METERS)
1 1.0000000 1.0000000
2 1.0000000 1.0000000
3 1.0000000 1.0000000
4 1.0000000 1.0000000
5 1.0000000 1.0000000
6 1.0000000 1.0000000
7 1.0000000 1.0000000
8 1.0000000 1.0000000
9 1.0000000 1.0000000
10 1.0000000 1.0000000
11 1.0000000 1.0000000
12 1.0000000 1.0000000
13 1.0000000 1.0000000
14 1.0000000 1.0000000
15 1.0000000 1.0000000
16 1.0000000 1.0000000
17 1.0000000 1.0000000
18 1.0000000 1.0000000
19 1.0000000 1.0000000
20 1.0000000 1.0000000
21 1.0000000 1.0000000
22 1.0000000 1.0000000
23 1.0000000 1.0000000
24 1.0000000 1.0000000
25 1.0000000 1.0000000
26 1.0000000 1.0000000
27 1.0000000 1.0000000
28 1.0000000 1.0000000
29 1.0000000 1.0000000
30 1.0000000 1.0000000
31 1.0000000 1.0000000
32 1.0000000 1.0000000
33 1.0000000 1.0000000
34 1.0000000 1.0000000
35 1.0000000 1.0000000
36 1.0000000 1.0000000
37 1.0000000 1.0000000
38 1.0000000 1.0000000
39 1.0000000 1.0000000
40 1.0000000 1.0000000
41 1.0000000 1.0000000
42 1.0000000 1.0000000
43 1.0000000 1.0000000
44 1.0000000 1.0000000
45 1.0000000 1.0000000
46 1.0000000 1.0000000
47 1.0000000 1.0000000
48 1.0000000 1.0000000
49 1.0000000 1.0000000
50 1.0000000 1.0000000
51 1.0000000 1.0000000
52 1.0000000 1.0000000
53 1.0000000 1.0000000
54 1.0000000 1.0000000
55 1.0000000 1.0000000
56 1.0000000 1.0000000
57 1.0000000 1.0000000
58 1.0000000 1.0000000
59 1.0000000 1.0000000
60 1.0000000 1.0000000
61 1.0000000 1.0000000
62 1.0000000 1.0000000
63 1.0000000 1.0000000
64 1.0000000 1.0000000
65 1.0000000 1.0000000
66 1.0000000 1.0000000
67 1.0000000 1.0000000
68 1.0000000 1.0000000
69 1.0000000 1.0000000
70 1.0000000 1.0000000
71 1.0000000 1.0000000
72 1.0000000 1.0000000
73 1.0000000 1.0000000
74 1.0000000 1.0000000
75 1.0000000 1.0000000
76 1.0000000 1.0000000
77 1.0000000 1.0000000
78 1.0000000 1.0000000
79 1.0000000 1.0000000
80 1.0000000 1.0000000
81 1.0000000 1.0000000
82 1.0000000 1.0000000
83 1.0000000 1.0000000
84 1.0000000 1.0000000
85 1.0000000 1.0000000
86 1.0000000 1.0000000
87 1.0000000 1.0000000
88 1.0000000 1.0000000
89 1.0000000 1.0000000
90 1.0000000 1.0000000
91 1.0000000 1.0000000
92 1.0000000 1.0000000
93 1.0000000 1.0000000
94 1.0000000 1.0000000
95 1.0000000 1.0000000
96 1.0000000 1.0000000
97 1.0000000 1.0000000
98 1.0000000 1.0000000
99 1.0000000 1.0000000
100 1.0000000 1.0000000

```

Figure 4-9. Output Listing, XTALK, Example 1.

37476  
 1 PARALLEL AIDS  
 THE OF SQUARES 1  
 LOAD SQUARE MATRONS 21  
 LINE LENGTHS: 4,000,000 60 MERRIS  
 RELAXIVE CONSTANT OF THE MERRIS: 1.000E 00  
 RELATIVE PERMEABILITY OF THE MEDIUM: 1.000E 00  
 CURR. SOURCE BY M-4  
 CURRENT SOURCE BY M-4  
 (AMPS) (DEGREES)  
 1 1 1.000E 00 0.0 1.000E 00 1.000E 00 0.0 1.000E 00 0.0  
 2 2 1.000E 00 0.0 1.000E 00 1.000E 00 0.0 1.000E 00 0.0  
 Y COORDINATE (M-1000)  
 1 1.000E 00  
 2 1.000E 00  
 CURRENT SOURCE AT REL  
 CURRENT SOURCE AT REL  
 (AMPS) (DEGREES)  
 1 1.000E 00 0.0  
 2 1.000E 00 0.0  
 CURRENT SOURCE AT REL  
 CURRENT SOURCE AT REL  
 (AMPS) (DEGREES)  
 1 1.000E 00 0.0  
 2 1.000E 00 0.0  
 RELATIVE PERMEABILITY OF THE MEDIUM: 1.000E 00  
 RELATIVE PERMEABILITY OF THE MEDIUM: 1.000E 00  
 RELATIVE PERMEABILITY OF THE MEDIUM: 1.000E 00

Figure 4-10. Output Listing, XTALK, Example 2.



876

```

XTALK
2 PARALLEL WIRES
TYPE OF STRUCTURE 1
LOAD STRUCTURE DEFINED BY
LINE LENGTHS 4000000 90 000000
RELUCTANCE CONSTANT OF THE MEDIUM 1.000E 00
RELATIVE PERMEABILITY OF THE MEDIUM 1.000E 00
CONSTANTS OF THE WIRES IN A WIRE WITH RADIUS 0.0000 00 WIRE
1 1 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00
2 1 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00
CURRENT SOURCE BY WIRE CURRENT SOURCE BY WIRE ADMITTANCE BY WIRE
WIRE (AMPS) WIRE (AMPS) WIRE (ELEMENT) (AMPS)
1 1 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00
2 1 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00
CURRENT SOURCE BY WIRE CURRENT SOURCE BY WIRE
WIRE (AMPS) WIRE (AMPS)
1 1.000E 00 1.000E 00
2 1.000E 00 1.000E 00
CONSTANTS OF THE MEDIUM WITH INVERSION NUMBER 0
RELUCTANCE CONSTANT OF THE MEDIUM 1.000E 00
RELATIVE PERMEABILITY OF THE MEDIUM 1.000E 00
SOLUTION ERROR
WIRE VOLTAGE VOLTAGE VOLTAGE VOLTAGE VOLTAGE VOLTAGE
1 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00
2 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00
WIRE VOLTAGE VOLTAGE VOLTAGE VOLTAGE VOLTAGE VOLTAGE
1 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00
2 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00 1.000E 00

```

Figure 4-12. Output Listing, XTALK, Example 4.













376

XTALK2									
2 PARALLEL WIRES									
TYPE OF STRUCTURE = 1									
LOAD STRUCTURE OPTION = 21									
LINE LENGTH = 5.000000 ON METERS									
DIFFERENTIAL CONDUCTIVITY OF THE MEDIUM = 3.0000 00									
RELATIVE PERMEABILITY OF THE MEDIUM = 1.0000 00									
PERMITTIVITY CONDUCTANCE FOR LINE VOLTAGES IS A WIRE WITH RADIUS = 5.1250 00 MILS									
WIRE NUMBER WIRE RADIUS (MILS) Z COORDINATE (METERS) Y COORDINATE (METERS)									
1	5.1250 00	1.2700-03	0.0						
2	5.1250 00	2.5400-03	0.0						
DEFINITION OF LENGTH CAPACITANCE MATRIX IN VECTOR FORM = 0									
DEFINITION OF WIRE TO STRAND WIRE RADIUS = 2.5000 00 MILS									
CONDUCTIVITY OF STRANDS IS 0.0000 00 SIEMENS PER METER									
NUMBER OF STRANDS = 2									
WIRE NUMBER WIRE RADIUS (MILS) CONDUCTIVITY (SIEMENS PER METER) NUMBER OF STRANDS									
1	5.1250 00	3.0000 00	2						
2	5.1250 00	3.0000 00	2						
CURRENT SOURCE AT X#L									
CURRENT SOURCE AT X#L ADMITTANCE AT X#L CURRENT SOURCE AT X#L									
REAL IMAG REAL IMAG REAL IMAG REAL IMAG									
1	1.0000 00	0.0	1.0000 00	0.0	1.0000-03	0.0	0.0	0.0	0.0
2	1.0000 00	0.0	0.0	0.0	1.0000-04	0.0	1.0000-04	0.0	0.0
EIGEN SOLUTION ERROR = 0									
EIGEN SOLUTION PRECISION = 1.0000 00									
TRANSFORMATION MATRIX INVERSION ERROR = 0									
WIRE V0N(VOLTS) V0A(DEGREES) VLN(VOLTS) VLA(DEGREES)									
1	5.0310-01	1.7350 00	3.3330 00	-1.6700 02					
2	1.6810-01	-5.8210 01	5.8720-01	-3.8210 01					
FREQUENCY (HERTZ) = 1.0000 00 SOLUTION ERROR = 0									
EIGEN SOLUTION ERROR = 0									
EIGEN SOLUTION PRECISION = 1.0000 00									
TRANSFORMATION MATRIX INVERSION ERROR = 0									
WIRE V0N(VOLTS) V0A(DEGREES) VLN(VOLTS) VLA(DEGREES)									
1	5.0740-01	4.6750-01	1.2470 00	8.1070 00					
2	4.0500-02	-7.9900 01	8.8550-02	1.0350 02					

Figure 4-18. Output Listing, XTALK2, Example 2.















1 PARALLEL WIRES

LINE LENGTH 5.000000 00 METERS

LOAD STRUCTURE OPTION= 11

TRANSMISSION MATRIX INVERSION FAILURE

LINE	VOLTAGE SOURCE AT REF		VOLTAGE SOURCE AT X=L		IMPEDANCE AT X=L		VOLTAGE SOURCE AT X=L	
	(VOLTS)	(OHMS)	REAL	IMAG	REAL	IMAG	REAL	IMAG
1	1.000000	0.0	1.000000	0.0	1.000000	0.0	0.0	0.0
2	1.000000	0.0	0.0	0.0	1.000000	0.0	1.000000	0.0

PROGRAM Y(0,0,0) 1.000000 0 SOLUTION ERROR 0

LINE	V (VOLTS)	V A(DEGREES)	VLM(VOLTS)	VLA(DEGREES)
1	1.000000	-1.564000	3.897000	-5.376000
2	1.000000	1.564000	1.579000	-1.665000

PROGRAM Y(0,0,0) 1.000000 0 SOLUTION ERROR 0

LINE	V (VOLTS)	V A(DEGREES)	VLM(VOLTS)	VLA(DEGREES)
1	1.000000	-1.564000	2.485000	-1.321000
2	1.000000	1.564000	1.567000	-1.771000

Figure 4-25. Output Listing, FLATPAK, Example 1.

FLATPAK

3 PARALLEL WIRES

LINE LENGTH 5.00000000 METERS

LOAD STRUCTURE OPTIONS ?1

PORT	ADMITTANCE AT X=0 (SIEMENS)		CURRENT SOURCE AT X=0 (AMPS)		ADMITTANCE AT X=L (SIEMENS)		CURRENT SOURCE AT X=L (AMPS)	
	REAL	IMAG	REAL	IMAG	REAL	IMAG	REAL	IMAG
1	1.00000000	0.00000000	1.00000000	0.00000000	1.00000000	0.00000000	0.00000000	0.00000000
2	1.00000000	0.00000000	0.00000000	0.00000000	1.00000000	0.00000000	1.00000000	0.00000000

SOLUTION PHASE 0

WIRE	V (VOLTS)	V/A (DEGREES)	VLM (VOLTS)	VLA (DEGREES)
1	1.00000000	-0.00000000	1.00000000	-0.00000000
2	1.00000000	1.00000000	1.00000000	1.00000000

SOLUTION PHASE 0

WIRE	V (VOLTS)	V/A (DEGREES)	VLM (VOLTS)	VLA (DEGREES)
1	1.00000000	-0.00000000	1.00000000	-0.00000000
2	1.00000000	1.00000000	1.00000000	1.00000000

Figure 4-26. Output Listing, FLATPAK, Example 2.

LINE LENGTH 5.000000 00 METERS

LOAD STRUCTURE OPTION= 12

TRANSFORMATION MATRIX IMPEDANCE MATRIX

WIRE	IMPEDANCE AT XE (OHMS)		VOLTAGE SOURCE AT XE (VOLTS)		IMPEDANCE AT XEL (OHMS)		VOLTAGE SOURCE AT XEL (VOLTS)	
	REAL	IMAG	REAL	IMAG	REAL	IMAG	REAL	IMAG
1	1.0000	0.0000	1.0000	0.0000	2.0000	0.0000	1.0000	0.0000
2	1.0000	0.0000	2.0000	0.0000	3.0000	0.0000	3.0000	0.0000
3	2.0000	0.0000	2.0000	0.0000	1.0000	0.0000	0.0000	0.0000

FREQUENCY (HERTZ)= 1.000000 07 SOLUTION ERROR= 0

WIRE	V (VOLTS)	V/A (DEGREES)	VLM (VOLTS)	VLA (DEGREES)
1	2.0000 00	-5.4930 -71	1.0000 00	-2.0390 00
2	3.0000 00	-1.3370 00	2.0000 00	-5.3170 -01

FREQUENCY (HERTZ)= 1.000000 08 SOLUTION ERROR= 0

WIRE	V (VOLTS)	V/A (DEGREES)	VLM (VOLTS)	VLA (DEGREES)
1	2.9980 00	-1.3370 00	1.0010 00	-3.9830 00
2	3.0000 00	-2.9450 00	2.0070 00	-9.1020 -01

Figure 4-27. Output Listing, FLATPAK, Example 3.

FLATPAK

3 PARALLEL WIRES

LINE LENGTH= 5.000000 CC METERS

LOAD STRUCTURE OPTION= 22

WIRE	ADMITTANCE AT XEL		CURRENT SOURCE AT XEL		ADMITTANCE AT XEL		CURRENT SOURCE AT XEL	
	REAL	IMAG	REAL	IMAG	REAL	IMAG	REAL	IMAG
1	6.000000	0.0	1.000000	0.0	6.000000	0.0	0.0	0.0
2	0.0	0.0	0.0	0.0	0.000000	0.0	1.000000	0.0
3	0.0	0.0	0.0	0.0	-2.000000	0.0	0.0	0.0

COMPUTATION OF SOLUTION ERRORS

WIRE	V (VOLTS)	VIA (DEGREES)	VLM (VOLTS)	VLA (DEGREES)
1	1.000000	-1.495000	1.000000	-2.003900
2	0.000000	-1.317000	0.000000	-5.317000

COMPUTATION OF SOLUTION ERRORS

WIRE	V (VOLTS)	VIA (DEGREES)	VLM (VOLTS)	VLA (DEGREES)
1	0.000000	-1.317000	1.000000	-1.993000
2	0.000000	-0.945000	0.000000	-0.102000

Figure 4-28. Output Listing, FLATPAK, Example 4.











PERFORMED IN THE CAPACITANCE MATRIX INVERSION ERROR C  
 PERFORMED IN THE CAPACITANCE MATRIX INVERSION ERROR C  
 MESSAGE: T 48000 WITH A 500 STANDARD DEVIATION 2.50000E-05 MILS  
 CONDUCTIVITY OF AIR: 5.00E-17 OHM-CM PER METER  
 NUMBER OF STAGES: 7

PORT	IMPEDANCE AT K&L (OHMS)		VOLTAGE SOURCE AT K&L (VOLTS)		IMPEDANCE AT K&L (OHMS)		VOLTAGE SOURCE AT K&L (VOLTS)	
	REAL	IMAG	REAL	IMAG	REAL	IMAG	REAL	IMAG
1	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	0.00	0.00
2	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000

PERFORMED IN THE CAPACITANCE MATRIX INVERSION ERROR C  
 PERFORMED IN THE CAPACITANCE MATRIX INVERSION ERROR C  
 MESSAGE: T 48000 WITH A 500 STANDARD DEVIATION 2.50000E-05 MILS  
 CONDUCTIVITY OF AIR: 5.00E-17 OHM-CM PER METER  
 NUMBER OF STAGES: 7

PORT	VLM(VOLTS)		VLA(DEGREES)		VLM(VOLTS)		VLA(DEGREES)	
	REAL	IMAG	REAL	IMAG	REAL	IMAG	REAL	IMAG
1	3.7920	-7.6170	3.7920	-5.6180	3.7920	-7.6170	3.7920	-5.6180
2	7.7500	1.1500	1.0130	-1.1330	1.0130	-1.1330	1.0130	-1.1330

PERFORMED IN THE CAPACITANCE MATRIX INVERSION ERROR C  
 PERFORMED IN THE CAPACITANCE MATRIX INVERSION ERROR C  
 MESSAGE: T 48000 WITH A 500 STANDARD DEVIATION 2.50000E-05 MILS  
 CONDUCTIVITY OF AIR: 5.00E-17 OHM-CM PER METER  
 NUMBER OF STAGES: 7

PORT	VLM(VOLTS)		VLA(DEGREES)		VLM(VOLTS)		VLA(DEGREES)	
	REAL	IMAG	REAL	IMAG	REAL	IMAG	REAL	IMAG
1	9.0880	-6.9440	2.4210	-1.1730	9.0880	-6.9440	2.4210	-1.1730
2	6.5720	9.1640	1.5080	-1.7700	1.5080	-1.7700	1.5080	-1.7700

Figure 4-33. Output Listing, FLATPAK2, Example 1.

FLATPAK2

3 PARALLEL WIRES

LINE LENGTH= 5.000000 CM METERS

LOAD STRUCTURE OPTION= 21

\*\*\*\*\* WITH CAPACITANCE MATRIX INVERSION ERROR \*

\*\*\*\*\* CAPACITANCE MATRIX INVERSION ERROR \*

\*\*\*\*\* WITH LINE LENGTH OF PARALLEL WIRES = 5.00 CM METERS \*\*\*\*\*

\*\*\*\*\* CAPACITANCE MATRIX INVERSION ERROR \*\*\*\*\*

\*\*\*\*\* WITH LINE LENGTH OF PARALLEL WIRES = 5.00 CM METERS \*\*\*\*\*

LINE	NO	ADMITTANCE AT XEL (SIEMENS)	CURRENT SOURCE AT XEL (AMPS)	ADMITTANCE AT XEL (SIEMENS)	CURRENT SOURCE AT XEL (AMPS)
		REAL	IMAG	REAL	IMAG
1	1	1.0000E-03	0.00	1.0000E-03	0.00
1	2	1.0000E-04	0.00	1.0000E-04	0.00

\*\*\*\*\* SOLUTION ERROR \*\*\*\*\*

\*\*\*\*\* SOLUTION ERROR \*\*\*\*\*

\*\*\*\*\* SOLUTION ERROR \*\*\*\*\*

LINE	VOLTS	PHASE (DEGREES)	VOLTS	PHASE (DEGREES)
	REAL	IMAG	REAL	IMAG
1	1.7320E-03	-5.6190E-01	1.7320E-03	-5.6190E-01
2	1.6130E-03	-1.1170E-02	1.6130E-03	-1.1170E-02

\*\*\*\*\* SOLUTION ERROR \*\*\*\*\*

\*\*\*\*\* SOLUTION ERROR \*\*\*\*\*

\*\*\*\*\* SOLUTION ERROR \*\*\*\*\*

LINE	VOLTS	PHASE (DEGREES)	VOLTS	PHASE (DEGREES)
	REAL	IMAG	REAL	IMAG
1	1.7320E-03	-5.6190E-01	1.7320E-03	-5.6190E-01
2	1.6130E-03	-1.1170E-02	1.6130E-03	-1.1170E-02

Figure 4-34. Output Listing, FLATPAK 2., Example 2.



376

```

FLATPAK?
3 PARALLEL WIRES
LINE LENGTH= 5.000000 00 METERS
LOAD STRUCTURE OPTION= 22
PER-UNIT-LENGTH CAPACITANCE MATRIX INVERSION ERROR= 0
PER-UNIT-LENGTH CAPACITANCE MATRIX INVERSION ERROR= 0
WIRE AND STRANDS WITH POSITIVE RADIUS OR RADIUS= 25000.00 MILS
CONDUCTIVITY OF WIRE STRANDS= 5.0E+09 OHM CM PER METER
NUMBER OF STRANDS= 3
ADMITTANCE AT X=L      CURRENT SOURCE AT X=L      ADMITTANCE AT X=L      CURRENT SOURCE AT X=L
(SIEMENS)              (AMPS)              (SIEMENS)              (AMPS)
WIRE 1  REAL          IMAG          REAL          IMAG          REAL          IMAG          REAL          IMAG
1 1  2.00000E+01  0.00000E+00  1.00000E+00  0.00000E+00  6.00000E-01  0.00000E+00  0.00000E+00  0.00000E+00
2 1  2.00000E+01  0.00000E+00  2.00000E+01  0.00000E+00  2.00000E-01  0.00000E+00  1.00000E+00  0.00000E+00
1 2  -4.00000E+01  0.00000E+00  -2.00000E-01  0.00000E+00  -2.00000E-01  0.00000E+00
FREQUENCY(HERTZ)= 1.00000E+07      SOLUTION ERROR= 0
EIGEN SOLUTION ERROR= 0
EIGEN SOLUTION PRECISION= 1.0E-02
TRANSFORMATION MATRIX INVERSION ERROR= 0
WIRE 1  V1A(VOLTS)  V1A(DEGREES)  V1B(VOLTS)  V1B(DEGREES)
1  2.0000E+00  -5.5520E-01  1.0000E+00  -2.0150E+00
2  2.0000E+00  -1.3410E+00  2.0000E+00  -5.3530E-01
WIRE 2  V2A(VOLTS)  V2A(DEGREES)  V2B(VOLTS)  V2B(DEGREES)
1  2.0000E+00  -1.4520E+00  9.9930E-01  -6.0590E+00
2  1.9997E+00  -3.6230E+00  2.9940E+00  -9.6950E-01
EIGEN SOLUTION ERROR= 0
EIGEN SOLUTION PRECISION= 1.0E-02
TRANSFORMATION MATRIX INVERSION ERROR= 0
WIRE 1  V1A(VOLTS)  V1A(DEGREES)  V1B(VOLTS)  V1B(DEGREES)
1  2.0000E+00  -1.4520E+00  9.9930E-01  -6.0590E+00
2  1.9997E+00  -3.6230E+00  2.9940E+00  -9.6950E-01

```

Figure 4-36. Output Listing, FLATPAK2, Example 4.

## V. SUMMARY

Four digital computer programs, XTALK, XTALK 2, FLATPAK, FLATPAK 2, for analyzing the electromagnetic coupling within an  $(n+1)$  conductor, uniform transmission line are presented. Sinusoidal steady state behavior of the line as well as the TEM or "quasi-TEM" mode of propagation are assumed.

XTALK and XTALK 2 consider lines consisting of  $n$  wires (cylindrical conductors) and a reference conductor. The surrounding medium is homogeneous and lossless. XTALK assumes that all  $(n+1)$  conductors are perfect conductors whereas XTALK 2 considers the conductors to be lossy. There are three choices for the reference conductor: a wire, a ground plane, an overall cylindrical conductor.

FLATPAK and FLATPAK 2 consider  $(n+1)$  wire ribbon (flatpack) cables in which all wires are identical and are coated with cylindrical, dielectric insulations of identical thicknesses. All wires lie in a horizontal plane and all adjacent wires are separated by identical distances. FLATPAK considers the wires to be perfect conductors and FLATPAK 2 considers the wires to be lossy. The dielectric insulations are considered to be lossless.

General termination networks are provided for at the ends of the line and the programs compute the voltages (with respect to the reference conductor) at the terminals of these termination networks for sinusoidal steady state excitation of the line.

## REFERENCES

- [1] C. R. Paul, Applications of Multiconductor Transmission Line Theory to the Prediction of Cable Coupling, Volume I, Multiconductor Transmission Line Theory, Technical Report, Rome Air Development Center, Griffiss AFB, NY, RADC-TR-76-101, Volume I, April 1976, (A025028).
- [2] C. R. Paul, "Useful Matrix Chain Parameter Identities for the Analysis of Multiconductor Transmission Lines", IEEE Trans. on Microwave Theory and Techniques, Volume MTT-23, No. 9, pp. 756-760, September 1975.
- [3] J. L. Bogdanor, R. A. Pearlman and M. D. Siegel, Intrasystem Electromagnetic Compatibility Analysis Program, Technical Report, RADC-TR-74-342, Rome Air Development Center, Griffiss AFB, NY, December 1974, Vol I, (A008526), Vol II, (A008527), Vol III, (A008528).
- [4] C. R. Paul, Applications of Multiconductor Transmission Line Theory to the Prediction of Cable Coupling, Volume III, Prediction of Crosstalk in Random Cable Bundles, Technical Report, RADC-TR-76-101, (A038316) Rome Air Development Center, Griffiss AFB NY to appear.
- [5] C. R. Paul, Applications of Multiconductor Transmission Line Theory to the Prediction of Cable Coupling, Volume IV, Prediction of Crosstalk in Ribbon Cables, Technical Report, RADC-TR-76-101, Rome Air Development Center, Griffiss AFB, NY, to appear.
- [6] W. C. Johnson, Transmission Lines and Networks, New York: McGraw-Hill, 1950.
- [7] S. Ramo, J. R. Whinnery, and T. VanDuzer, Fields and Waves in Communication Electronics, New York: John Wiley, 1965.
- [8] A. E. Feather and C. R. Paul, Applications of Multiconductor Transmission Line Theory to the Prediction of Cable Coupling, Volume II, Computation of the Capacitance Matrices for Ribbon Cables, Technical Report, Rome

Air Development Center, Griffiss AFB, NY, RADC-TR-76-101, Volume II,  
April 1976 , (A025029).

IMSL, Sixth Floor, GNB Building, 7500 Bellaire Boulevard, Houston,  
Texas 77036 (Fifth Edition, November 1975).

System/360 Scientific Subroutine Package, Version III, Fifth Edition  
(August 1970), IBM Corporation, Technical Publications Department, 112  
East Post Road, White Plains, New York 10601.

C. R. Paul, "Efficient Numerical Computation of the Frequency Response  
of Cables Illuminated by an Electromagnetic Field", IEEE Trans. on  
Microwave Theory and Techniques, Volume MTT-22, No. 4, pp. 454-457,  
April 1974.



APPENDICES

376

APPENDIX A

XTALK

Program Listing

```

C*****XTALK001
C
C          PROGRAM XTALK                      XTALK002
C          (FORTRAN IV, DOUBLE PRECISION)    XTALK003
C          WRITTEN BY                        XTALK004
C          CLAYTON R. PAUL                  XTALK005
C          DEPARTMENT OF ELECTRICAL ENGINEERING XTALK006
C          UNIVERSITY OF KENTUCKY          XTALK007
C          LEXINGTON, KENTUCKY 40506      XTALK008
C
C          A DIGITAL COMPUTER PROGRAM TO COMPUTE THE TERMINAL VOLTAGES
C          (WITH RESPECT TO THE REFERENCE CONDUCTOR) AT THE ENDS OF A
C          MULTICONDUCTOR TRANSMISSION LINE FOR THE TEM MODE OF
C          PROPAGATION.                    XTALK009
C
C          THE DISTRIBUTED PARAMETER, MULTICONDUCTOR TRANSMISSION LINE
C          EQUATIONS ARE SOLVED FOR STEADY STATE, SINUSOIDAL EXCITATION
C          OF THE LINE.                    XTALK010
C
C          THE LINE CONSISTS OF N WIRES (CYLINDRICAL CONDUCTORS) AND A
C          REFERENCE CONDUCTOR. THE REFERENCE CONDUCTOR MAY BE A WIRE
C          (TYPE=1), AN INFINITE GROUND PLANE (TYPE=2), OR AN OVERALL
C          CYLINDRICAL SHIELD (TYPE=3)    XTALK011
C
C          THE N WIRES ARE ASSUMED TO BE PARALLEL TO EACH OTHER AND THE
C          REFERENCE CONDUCTOR.          XTALK012
C
C          THE N WIRES AND THE REFERENCE CONDUCTOR ARE ASSUMED TO BE
C          PERFECT CONDUCTORS.           XTALK013
C
C          THE LINE IS IMMERSED IN A LINEAR, ISOTROPIC, AND HOMOGENEOUS
C          MEDIUM WITH A RELATIVE PERMEABILITY OF  $\mu_{RP}$  AND A RELATIVE
C          DIELECTRIC CONSTANT OF  $\epsilon_R$ . THE MEDIUM IS ASSUMED TO BE LOSSLESS.
C
C          LOAD STRUCTURE OPTION DEFINITIONS:
C          OPTION=11, THEVENIN EQUIVALENT LOAD STRUCTURES WITH DIAGONAL
C          IMPEDANCE MATRICES           XTALK014
C          OPTION=12, THEVENIN EQUIVALENT LOAD STRUCTURES WITH FULL
C          IMPEDANCE MATRICES           XTALK015
C          OPTION=21, NORTON EQUIVALENT LOAD STRUCTURES WITH DIAGONAL
C          ADMITTANCE MATRICES          XTALK016
C          OPTION=22, NORTON EQUIVALENT LOAD STRUCTURES WITH FULL
C          ADMITTANCE MATRICES          XTALK017
C
C          SUBROUTINES USED: LEQTC        XTALK018
C
C*****XTALK019
C
C          ALL VECTORS AND MATRICES IN THE FOLLOWING DIMENSION STATEMENTS
C          SHOULD BE OF SIZE N WHERE N IS THE NUMBER OF WIRES (EXCLUSIVE OF
C          THE REFERENCE CONDUCTOR), I.E., IO(N), IL(N), YO(N,N), YL(N,N), B(N),
C          A(N,N), WA(N), M1(N,N), M2(N,N), V1(N), V2(N)
C
C          IMPLICIT REAL*8 (A-H,O-Z)
C          INTEGER TYPE, OPTION
C          REAL*8 L, MOD2PI, MUR
C          COMPLEX*16 XJ, IO( 2), IL( 2), YO( 2, 2), YL( 2, 2), AI( 2, 2), BI( 2),
C          IWA( 2), MI( 2, 2), M2( 2, 2), V1( 2), V2( 2), SUMC, SUML, VC, VL, ZEROC,
C          ZC, A1, A2, ONEC
C          DATA P1/3.14159265359, V/2.99792508/
C          DATA CMT/2.54E-5/, MOD2PI/2.0E-7/, P5/.500/, Z550/0.00/, ONE/1.00/,
C
C          XTALK020
C          XTALK021
C          XTALK022
C          XTALK023
C          XTALK024
C          XTALK025
C          XTALK026
C          XTALK027
C          XTALK028
C          XTALK029
C          XTALK030
C          XTALK031
C          XTALK032
C          XTALK033
C          XTALK034
C          XTALK035
C          XTALK036
C          XTALK037
C          XTALK038
C          XTALK039
C          XTALK040
C          XTALK041
C          XTALK042
C          XTALK043
C          XTALK044
C          XTALK045
C          XTALK046
C          XTALK047
C          XTALK048
C          XTALK049
C          XTALK050
C          XTALK051
C          XTALK052
C          XTALK053
C          XTALK054
C          XTALK055
C          XTALK056
C          XTALK057
C          XTALK058
C          XTALK059
C          XTALK060
C          XTALK061

```

```

ITWO/2.DG/,FOUR/4.DG/,ONEBG/160.DG/
ONEC=DCMPLX(1.00,0.00)
ZEROC=DCMPLX(0.00,0.00)
XJ=DCMPLX(0.00,1.00)
C*****FREQUENCY INDEPENDENT CALCULATIONS*****
C
C READ AND PRINT INPUT DATA
C
C READ(5,1) TYPE,OPTION,N,ER,MUR,L
1 FORMAT(9X,11,2(8X,12),3(5X,E10.3))
IF(TYPE.GE.1.AND.TYPE.LE.3) GO TO 3
WRITE(6,2)
2 FORMAT(' STRUCTURE TYPE ERROR'///' TYPE MUST EQUAL 1,2,OR 3'///)
GO TO 82
3 IF(OPTION.EQ.11.OR.OPTION.EQ.12) GO TO 5
IF(OPTION.EQ.21.OR.OPTION.EQ.22) GO TO 5
WRITE(6,4)
4 FORMAT(' LOAD STRUCTURE OPTION ERROR'///' OPTION MUST EQUAL 11,12,21,OR 22'///)
GO TO 82
5 WRITE(6,6) N,TYPE,OPTION,L,ER,MUR
6 FORMAT(11H,50X,'XTALK'///
145X,12,' PARALLEL WIRES'///
243X,' TYPE OF STRUCTURE= ',11///
341X,' LOAD STRUCTURE OPTION= ',12///
439X,' LINE LENGTH= ',1PE13.6,' METERS'///
532X,' DIELECTRIC CONSTANT OF THE MEDIUM= ',1PF10.3///
631X,' RELATIVE PERMEABILITY OF THE MEDIUM= ',1PE10.3///)
GO TO (7,15,11),TYPE
7 READ(5,8) RWD
8 FORMAT(5X,E10.3)
WRITE(6,9) RWD
9 FORMAT(' REFERENCE CONDUCTOR FOR LINE VOLTAGES IS A WIRE WITH RADIUS= ',1PE10.3,' MILS'///)
RWD=RWD*CMTM
WRITE(6,10)
10 FORMAT(' WIRE NUMBER',4X,' WIRE RADIUS (MILS)',19X,
1'Z COORDINATE (METERS)',24X,' Y COORDINATE (METERS)',//)
GO TO 16
11 READ(5,12) RS
12 FORMAT(5X,E10.3)
WRITE(6,13) RS
13 FORMAT(' REFERENCE CONDUCTOR FOR LINE VOLTAGES IS A CYLINDRICAL CONDUCTOR WITH INTERIOR RADIUS= ',1PE10.3,' METERS'///)
RS2=RS*RS
WRITE(6,14)
14 FORMAT(' WIRE NUMBER',2X,' WIRE RADIUS (MILS)',2X,' SEPARATION BETWEEN WIRE AND CENTER OF SHIELD (METERS)',6X,' ANGULAR COORDINATE (DEGREES)'///)
GO TO 18
15 WRITE(6,16)
16 FORMAT(' REFERENCE CONDUCTOR FOR LINE VOLTAGES IS AN INFINITE GROUNDED PLANE'///)
WRITE(6,17)
17 FORMAT(' WIRE NUMBER',4X,' WIRE RADIUS (MILS)',19X,
1' HORIZONTAL COORDINATE (METERS)',16X,' WIRE HEIGHT (METERS)',//)
C
C READ AND PRINT LINE DIMENSIONS AND COMPUTE THE CHARACTERISTIC
C IMPEDANCE MATRIX, ZC (STORE ZC IN ARRAY M1)
C

```

```

XTALK062
XTALK063
XTALK064
XTALK065
XTALK066
XTALK067
XTALK068
XTALK069
XTALK070
XTALK071
XTALK072
XTALK073
XTALK074
XTALK075
XTALK076
XTALK077
XTALK078
XTALK079
XTALK080
XTALK081
XTALK082
XTALK083
XTALK084
XTALK085
XTALK086
XTALK087
XTALK088
XTALK089
XTALK090
XTALK091
XTALK092
XTALK093
XTALK094
XTALK095
XTALK096
XTALK097
XTALK098
XTALK099
XTALK100
XTALK101
XTALK102
XTALK103
XTALK104
XTALK105
XTALK106
XTALK107
XTALK108
XTALK109
XTALK110
XTALK111
XTALK112
XTALK113
XTALK114
XTALK115
XTALK116
XTALK117
XTALK118
XTALK119
XTALK120
XTALK121
XTALK122

```

18	C=MUD2PI*ONEC*V*DSQRT(MUR/ER)	XTALK123
	DO 24 I=1,N	XTALK124
	READ(5,19) RW,Z,Y	XTALK125
19	FORMAT(3(5X,E10.3))	XTALK126
	WRITE(6,20) 1,RW,Z,Y	XTALK127
20	FORMAT(2X,12,13X,1PE10.3,27X,1PE10.3,35X,1PE10.3/)	XTALK128
	V1(I)=ONEC*Z	XTALK129
	V2(I)=ONEC*Y	XTALK130
	RW=RW*CMTM	XTALK131
	GO TO (21,22,23),TYPE	XTALK132
21	D12=Z*Z+Y*Y	XTALK133
	M1(I,I)=C*DLOG(D12/(RW*RWO))	XTALK134
	GO TO 24	XTALK135
22	M1(I,I)=C*DLOG(TWO*Y/RW)	XTALK136
	GO TO 24	XTALK137
23	M1(I,I)=C*DLOG((PS2-Z*Z)/(KS*KW))	XTALK138
24	CONTINUE	XTALK139
	IF(IN.EQ.1) GO TO 24	XTALK140
	K1=N-1	XTALK141
	DO 28 I=1,K1	XTALK142
	K2=I+1	XTALK143
	DO 28 J=K2,N	XTALK144
	ZI=DREAL(V1(I))	XTALK145
	ZJ=DREAL(V1(J))	XTALK146
	YI=DREAL(V2(I))	XTALK147
	YJ=DREAL(V2(J))	XTALK148
	GO TO (25,26,27),TYPE	XTALK149
25	D12=Z1*Z1+Y1*Y1	XTALK150
	DJ2=ZJ*ZJ+YJ*YJ	XTALK151
	ZD=Z1-ZJ	XTALK152
	YD=Y1-YJ	XTALK153
	DIJ2=ZD*ZD+YD*YD	XTALK154
	M1(I,J)=P5*C*DLOG(D12*DJ2/(RWO*RWO*DIJ2))	XTALK155
	M1(J,I)=M1(I,J)	XTALK156
	GO TO 28	XTALK157
26	ZD=Z1-ZJ	XTALK158
	YD=Y1-YJ	XTALK159
	DIJ2=ZD*ZD+YD*YD	XTALK160
	M1(I,J)=P5*C*DLOG(ONE+FOUR*YI*YJ/DIJ2)	XTALK161
	M1(J,I)=M1(I,J)	XTALK162
	GO TO 28	XTALK163
27	THETA=(Y1-YJ)*PI/ONEC	XTALK164
	RI2=Z1*Z1	XTALK165
	RJ2=ZJ*ZJ	XTALK166
	M1(I,J)=P5*C*DLOG((RJ2/RS2)*(RI2*RJ2+RS2*RS2-TWO*Z1*ZJ*RS2*	XTALK167
	ICCS(THETA)))/(RI2*KJ2+RJ2*KJ2-TWO*Z1*ZJ*FJ2*CCS(THETA)))	XTALK168
	M1(J,I)=M1(I,J)	XTALK169
28	CONTINUE	XTALK170
		XTALK171
C	COMPUTE THE INVERSE OF THE CHARACTERISTIC IMPEDANCE MATRIX, ZCINV	XTALK172
C	(STORE ZCINV IN ARRAY M2)	XTALK173
C		XTALK174
29	DO 31 I=1,N	XTALK175
	DO 30 J=1,N	XTALK176
	A(I,J)=M1(I,J)	XTALK177
30	M2(I,J)=ZEROC	XTALK178
31	M2(I,I)=ONEC	XTALK179
	CALL LEUTIC(A,N,N,M2,N,N,O,WA,KER)	XTALK180
	KER=KER-128	XTALK181
C		XTALK182
C	READ AND PRINT ENTRIES IN LOAD ADMITTANCE (IMPEDANCE) MATRICES	XTALK183

```

AND SHORT CIRCUIT CURRENT SOURCE(OPEN CIRCUIT VOLTAGE SOURCE) VECTORS
VECTORS (STORE ADMITTANCE (IMPEDANCE) MATRICES AT X=0 IN ARRAY Y0
AND THOSE AT X=L IN ARRAY YL. STORE SHORT CIRCUIT CURRENT SOURCE
(OPEN CIRCUIT VOLTAGE SOURCE) VECTORS AT X=0 IN ARRAY I0 AND
THOSE AT X=L IN ARRAY IL.)
IF(OPTION.EQ.11.OR.OPTION.EQ.12) GO TO 34
WRITE(6,32)
2 FORMAT(//,18X,'ADMITTANCE AT X=0',10X,'CURRENT SOURCE AT X=0',
112X,'ADMITTANCE AT X=L',10X,'CURRENT SOURCE AT X=L'/)
WRITE(6,33)
33 FORMAT(21X,'(SIEMENS)',23X,'(AMPS)',22X,'(SIEMENS)',23X,'(AMPS)'/)
GO TO 37
34 WRITE(6,35)
35 FORMAT(//,18X,'IMPEDANCE AT X=0',11X,'VOLTAGE SOURCE AT X=0',
112X,'IMPEDANCE AT X=L',11X,'VOLTAGE SOURCE AT X=L'/)
WRITE(6,36)
36 FORMAT(23X,'(OHMS)',23X,'(VOLTS)',24X,'(OHMS)',23X,'(VOLTS)'/)
37 WRITE(6,38)
38 FORMAT(' ENTRY',10X,'REAL',11X,'IMAG',11X,'REAL',11X,'IMAG',11X,
1'REAL',11X,'IMAG',11X,'REAL',11X,'IMAG'//)
DO 41 I=1,N
READ(5,39) Y0R,Y0I,I0(I),YLR,YLI,IL(I)
39 FORMAT(8(E10.3))
Y0(I,I)=Y0R+XJ*Y0I
YL(I,I)=YLR+XJ*YLI
WRITE(6,40) I,I,Y0(I,I),I0(I),YL(I,I),IL(I)
40 FORMAT(1X,12,2X,12,9(5X,1PE10.3)/)
41 CONTINUE
IF(OPTION.EQ.11.OR.OPTION.EQ.21) GO TO 45
IF(N.EQ.1) GO TO 45
DO 44 I=1,K1
K2=I+1
DO 44 J=K2,N
READ(5,42) Y0R,Y0I,YLR,YLI
42 FORMAT(2(E10.3),20X,2(E10.3))
Y0(I,J)=Y0R+XJ*Y0I
YL(I,J)=YLR+XJ*YLI
Y0(J,I)=Y0(I,J)
YL(J,I)=YL(I,J)
WRITE(6,43) I,J,Y0(I,J),YL(I,J)
43 FORMAT(1X,12,2X,12,2(5X,1PE10.3),30X,2(5X,1PE10.3))
44 CONTINUE
IF THEVENIN EQUIVALENT IS SPECIFIED, SWAP ENTRIES IN M1 AND M2.
M1 WILL CONTAIN ZCINV AND M2 WILL CONTAIN ZC.
45 IF(OPTION.EQ.21.OR.OPTION.EQ.22) GO TO 47
DO 47 I=1,N
DO 46 J=1,N
A1=M1(I,J)
A2=M2(I,J)
M1(I,J)=A2
M1(J,I)=A2
M2(I,J)=A1
46 M2(J,I)=A1
47 IL(I)=-IL(I)
COMPUTE THE MATRIX ZC+ZL*ZCINV*Z0 FOR THE THEVENIN EQUIVALENT
OR ZCINV+YL*ZC*Y0 FOR THE NORTON EQUIVALENT. STORE IN ARRAY M2.
COMPUTE THE MATRIX ZCINV*Z0 FOR THE THEVENIN EQUIVALENT OR

```

```

XTALK184
XTALK185
XTALK186
XTALK187
XTALK188
XTALK189
XTALK190
XTALK191
XTALK192
XTALK193
XTALK194
XTALK195
XTALK196
XTALK197
XTALK198
XTALK199
XTALK200
XTALK201
XTALK202
XTALK203
XTALK204
XTALK205
XTALK206
XTALK207
XTALK208
XTALK209
XTALK210
XTALK211
XTALK212
XTALK213
XTALK214
XTALK215
XTALK216
XTALK217
XTALK218
XTALK219
XTALK220
XTALK221
XTALK222
XTALK223
XTALK224
XTALK225
XTALK226
XTALK227
XTALK228
XTALK229
XTALK230
XTALK231
XTALK232
XTALK233
XTALK234
XTALK235
XTALK236
XTALK237
XTALK238
XTALK239
XTALK240
XTALK241
XTALK242
XTALK243
XTALK244

```

```

C      ZC*Y0 FOR THE NORTON EQUIVALENT. STORE IN ARRAY M1.
C      COMPUTE THE VECTOR ZL*ZCINV*V0 FOR THE THEVENIN EQUIVALENT OR
C      YL*ZC+I0 FOR THE NORTON EQUIVALENT. STORE IN ARRAY V2.
C      COMPUTE THE VECTOR ZCINV*V0 FOR THE THEVENIN EQUIVALENT OR
C      ZC*I0 FOR THE NORTON EQUIVALENT. STORE IN ARRAY V1.
C
48  IF(OPTION.EQ.12.OR.OPTION.EQ.22) GO TO 54
    DO 50 I=1,N
      SUM0=ZEROC
      DO 49 J=1,N
        A(I,J)=M1(I,J)*Y0(J,J)
49  SUM0=SUM0+M1(I,J)*I0(J)
50  V1(I)=SUM0
      DO 52 I=1,N
        DO 51 J=1,N
          M2(I,J)=YL(I,I)*A(I,J)+M2(I,J)
52  V2(I)=YL(I,I)*V1(I)
          DO 53 I=1,N
            DO 53 J=1,N
53  M1(I,J)=A(I,J)
          GO TO 62
54  DO 57 I=1,N
      SUM0=ZEROC
      DO 56 J=1,N
        SUML=ZEROC
        DO 55 K=1,N
          SUML=SUML+M1(I,K)*Y0(K,J)
          SUM0=SUM0+M1(I,J)*I0(J)
56  A(I,J)=SUML
57  V1(I)=SUM0
          DO 60 I=1,N
            SUM0=ZEROC
            DO 59 J=1,N
              SUML=ZEROC
              DO 58 K=1,N
                SUML=SUML+YL(I,K)*A(K,J)
                M2(I,J)=SUML+M2(I,J)
59  SUM0=SUM0+YL(I,J)*V1(J)
60  V2(I)=SUM0
          DO 61 I=1,N
            DO 61 J=1,N
61  M1(I,J)=A(I,J)
62  BL=TWO*PI*DSQRT(MUF*EP)*L/V
      IF(KFR.NE.1) KER=0
      WRITE(6,03) KER
63  FORMAT(//,' CHARACTERISTIL IMPEDANCE MATRIX INVERSION ERROR= ',I2
1//)
C
C *****FREQUENCY DEPENDENT CALCULATIONS*****
C
64  CONTINUE
    READ(5,05,END=82) F
05  FORMAT(F10.3)
    BETAL=BL*F
    US=DSIN(BETAL)
    DC=DCOS(BETAL)
C
C      COMPUTE THE TERMINAL VOLTAGES
C
C      PERM THE EQUATIONS
C

```

```

XTALK245
XTALK246
XTALK247
XTALK248
XTALK249
XTALK250
XTALK251
XTALK252
XTALK253
XTALK254
XTALK255
XTALK256
XTALK257
XTALK258
XTALK259
XTALK260
XTALK261
XTALK262
XTALK263
XTALK264
XTALK265
XTALK266
XTALK267
XTALK268
XTALK269
XTALK270
XTALK271
XTALK272
XTALK273
XTALK274
XTALK275
XTALK276
XTALK277
XTALK278
XTALK279
XTALK280
XTALK281
XTALK282
XTALK283
XTALK284
XTALK285
XTALK286
XTALK287
XTALK288
XTALK289
XTALK290
XTALK291
XTALK292
XTALK293
XTALK294
XTALK295
XTALK296
XTALK297
XTALK298
XTALK299
XTALK300
XTALK301
XTALK302
XTALK303
XTALK304
XTALK305

```

376

```

IF(OPTION.EQ.12.OR.OPTION.EQ.22) GO TO 6F
DO 67 I=1,N
DO 66 J=1,N
A(I,J)=XJ*OS*M2(I,J)
A(I,I)=OC*(YO(I,I)+YL(I,I))+A(I,I)
B(I)=DC*IO(I)+XJ*OS*V2(I)+IL(I)
GO TO 71
DO 70 I=1,N
DO 69 J=1,N
A(I,J)=XJ*OS*M2(I,J)+DC*(YO(I,J)+YL(I,J))
B(I)=DC*IO(I)+XJ*OS*V2(I)+IL(I)

SOLVE THE EQUATIONS

1 CALL LEQTIC(A,N,N,B,1,N,0,WA,IER)
IER=IER-128
IF(IER.NE.1) IER=0
WRITE(6,72) F,IER
2 FORMAT(1H1,' FREQUENCY(HERTZ)= ',IPE11.4,10X,' SOLUTION ERROR= ',
12X,12///)
WRITE(6,73)
3 FORMAT(16X,' WIRE ',8X,' VOM(VOLTS) ',3X,' VOA(DEGREES) ',8X,
1'VLM(VOLTS) ',3X,' VLA(DEGREES) '///)

COMPUTE AND PRINT THE TERMINAL VOLTAGES

DO 75 I=1,N
SUMO=ZEROC
DO 74 J=1,N
74 SUMO=SUMO+M1(I,J)*B(J)
75 WA(I)=XJ*OS*(SUMO-VI(I))+DC*B(I)
DO 81 I=1,N
IF(OPTION.EQ.11.OR.OPTION.EQ.12) GO TO 76
VO=B(I)
VL=WA(I)
GO TO 79
76 IF(OPTION.EQ.12) GO TO 77
VO=IO(I)-YO(I,I)*B(I)
VL=-IL(I)+YL(I,I)*WA(I)
GO TO 79
77 SUMO=ZEROC
SUML=ZEROC
DO 78 J=1,N
SUMO=SUMO+YO(I,J)*B(J)
78 SUML=SUML+YL(I,J)*WA(J)
VO=IO(I)-SUMO
VL=-IL(I)+SUML
79 VOM=CDABS(VO)
VLM=CDABS(VL)
VOR=DREAL(VO)
VLI=DIMAG(VL)
VLR=DREAL(VL)
VLI=DIMAG(VL)
IF(VOR.EQ.ZERO.AND.VLI.EQ.ZERO) VOP=CMF
IF(VLR.EQ.ZERO.AND.VLI.EQ.ZERO) VLP=CNE
VOA=DATAN2(VO1,VOR)*CNF80/PI
VLA=DATAN2(VLI,VLR)*UNE80/PI
WRITE(6,80) I,VOM,VOA,VLM,VLA
80 FORMAT(17X,12,8X,1PE10.3,3X,1PE10.3,10X,1PE10.3,3X,1PE10.3/)
81 CONTINUE
GO TO 64

```

```

XTALK306
XTALK307
XTALK308
XTALK309
XTALK310
XTALK311
XTALK312
XTALK313
XTALK314
XTALK315
XTALK316
XTALK317
XTALK318
XTALK319
XTALK320
XTALK321
XTALK322
XTALK323
XTALK324
XTALK325
XTALK326
XTALK327
XTALK328
XTALK329
XTALK330
XTALK331
XTALK332
XTALK333
XTALK334
XTALK335
XTALK336
XTALK337
XTALK338
XTALK339
XTALK340
XTALK341
XTALK342
XTALK343
XTALK344
XTALK345
XTALK346
XTALK347
XTALK348
XTALK349
XTALK350
XTALK351
XTALK352
XTALK353
XTALK354
XTALK355
XTALK356
XTALK357
XTALK358
XTALK359
XTALK360
XTALK361
XTALK362
XTALK363
XTALK364
XTALK365
XTALK366

```



62 STOP  
END

XTALK367  
XTALK368

76

TABLE A-1

Changes in XTALK to Convert  
to Single Precision Arithmetic

Card 054

<u>Number</u>		<u>Double</u>		<u>Single</u>
6		REAL *8		REAL
7		COMPLEX *16		COMPLEX
30		3.141592653D0		3.1415926E0
50		2.997925D8		2.997925E8
062	change all	D's	to	E's
63		DCMPLX(1.D0,0.D0)		CMPLX(1.E0,0.E0)
64		DCMPLX(0.D0,0.D0)		CMPLX(0.E0,0.E0)
65		DCMPLX(0.D0,1.D0)		CMPLX(0.E0,1.E0)
123		DSQRT		SQRT
134		DLOG		ALOG
136		DLOG		ALOG
138		DLOG		ALOG
145		DREAL		REAL
146		DREAL		REAL
147		DREAL		REAL
148		DREAL		REAL
155		DLOG		ALOG
161		DLOG		ALOG
167		DLOG		ALOG
168		DCOS		COS
168		DCOS		COS

Card Number

Double

Single

287

DSQRT

SQRT

299

DSIN

SIN

300

DCOS

COS

353

CDABS

CABS

354

CDABS

CABS

355

DREAL

REAL

356

DIMAG

AIMAG

357

DREAL

REAL

358

DIMAG

AIMAG

361

DATAN2

ATAN2

362

DATAN2

ATAN2

376

APPENDIX B

XTALK2

Program Listing

```

*****XTALK001
C XTALK002
C PROGRAM XTALK2 XTALK003
C (SERIAL IV, DOUBLE PRECISION) XTALK004
C WRITTEN BY XTALK005
C CLAYTON R. PAUL XTALK006
C DEPARTMENT OF ELECTRICAL ENGINEERING XTALK007
C UNIVERSITY OF KENTUCKY XTALK008
C LEXINGTON, KENTUCKY 40506 XTALK009
C XTALK010
C A DIGITAL COMPUTER PROGRAM TO COMPUTE THE TERMINAL VOLTAGES
C (WITH RESPECT TO THE REFERENCE CONDUCTOR) AT THE ENDS OF A
C MULTICONDUCTOR TRANSMISSION LINE FOR THE TEM MODE OF
C PROPAGATION. XTALK011
C XTALK012
C XTALK013
C XTALK014
C XTALK015
C THE DISTRI BUTE D PARAMETERS, MULTICONDUCTOR TRANSMISSION LINE
C EQUATIONS ARE SOLVED FOR STEADY STATE, SINUSOIDAL EXCITATION
C OF THE LINE. XTALK016
C XTALK017
C XTALK018
C XTALK019
C XTALK020
C THE LINE CONSISTS OF N WIRES (CYLINDRICAL CONDUCTORS) AND A
C REFERENCE CONDUCTOR. THE REFERENCE CONDUCTOR MAY BE A WIRE
C (TYPE=1), AN INFINITE GROUND PLANE (TYPE=2), OR AN OVERALL
C CYLINDRICAL SHIELD (TYPE=3). XTALK021
C XTALK022
C XTALK023
C XTALK024
C THE N WIRES ARE ASSUMED TO BE PARALLEL TO EACH OTHER AND THE
C REFERENCE CONDUCTOR. XTALK025
C XTALK026
C XTALK027
C THE N WIRES AND THE REFERENCE CONDUCTOR ARE CONSIDERED TO BE
C IMPERFECT CONDUCTORS. THE SELF IMPEDANCES OF EACH WIRE AND THE
C REFERENCE CONDUCTOR INCLUDE SKIN EFFECT. XTALK028
C XTALK029
C XTALK030
C XTALK031
C THE LINE IS IMMERSED IN A LINEAR, ISOTROPIC, AND HOMOGENEOUS
C MEDIUM WITH A RELATIVE PERMEABILITY OF  $\mu_{R}$  AND A RELATIVE
C DIELECTRIC CONSTANT OF  $\epsilon_{R}$ . THE MEDIUM IS ASSUMED TO BE LOSSLESS. XTALK032
C XTALK033
C XTALK034
C XTALK035
C LOAD STRUCTURE OPTION DEFINITIONS:
C OPTION=11, THEVENIN EQUIVALENT LOAD STRUCTURES WITH DIAGONAL
C IMPEDANCE MATRICES XTALK037
C XTALK038
C OPTION=12, THEVENIN EQUIVALENT LOAD STRUCTURES WITH FULL
C IMPEDANCE MATRICES XTALK039
C XTALK040
C OPTION=21, NORTON EQUIVALENT LOAD STRUCTURES WITH DIAGONAL
C ADMITTANCE MATRICES XTALK041
C XTALK042
C OPTION=22, NORTON EQUIVALENT LOAD STRUCTURES WITH FULL
C ADMITTANCE MATRICES XTALK043
C XTALK044
C XTALK045
C XTALK046
C SUBROUTINES USED: LPTIO,PTACC XTALK047
C XTALK048
C *****XTALK049
C XTALK050
C ALL VECTORS AND MATRICES IN THE FOLLOWING DIMENSION STATEMENTS
C SHOULD BE OF SIZE N WHERE N IS THE NUMBER OF WIRES (EXCLUSIVE OF
C THE REFERENCE CONDUCTOR). I.E., NS(N),C(N,N),Z(N),Y(N),CI(N,N),
C ICI(N),ILIN),YLIN),YLIN),R(N),A(N,N),P(N,N),EN(N),EP(N),
C MN(N,N),MC(N,N),VN(N),V2(N),T(N,N),TT(N,N),G(N),V2(N),WA(N)
C THE VECTOR WA MUST BE OF LENGTH N(N+1) XTALK051
C XTALK052
C XTALK053
C XTALK054
C XTALK055
C XTALK056
C XTALK057
C XTALK058
C XTALK059
C XTALK060
C XTALK061
C IMPLICIT REAL*8 (A-H,O-Z)
C INTEGER TYPE,OPTION,IS(2)
C REAL*8 LVL,CADEN,C0(2,2),Z(2),Y(2),CI(2,2),V2(2),WK(12),
C INU(2),M1(2),M2(2),M3(2),M4(2)
C COMPLEX*16 ZU,ZUN,ZUM,ZL,ZC,ZV,Z2,ERP,EPN,GAM,UMEGA

```

376



```

      WRITE(6,17)
17  FORMAT(' WIRE NUMBER',4X,' WIRE RADIUS (MILS)',18X,
      1'HORIZONTAL COORDINATE (METERS)',16X,' WIRE HEIGHT (METERS)',//)
C
C      READ AND PRINT LINE DIMENSIONS AND COMPUTE THE INVERSE OF THE
C      PER-MIT-LENGTH CAPACITANCE MATRIX, CINV
C      (STORE CINV IN ARRAY CI)
C
18  DIMENSION I*VV/*R
      DO 24 I=1,N
      READ(5,18) RW,Z(I),Y(I)
19  FORMAT(3(FX,F10.7))
      A=I*(1,20) I=RW,Z(I),Y(I)
20  FORMAT(2X,10,10X,1PF10.3,27X,1PF10.3,35X,1PF10.3/)
      XW=R*CMTM
      GO TO (21,22,23),TYPE
21  D1=Z(I)*Z(I)+Y(I)*Y(I)
      C1(I,I)=D*LOG(D1/(RW*RW))
      GO TO 24
22  C1(I,I)=D*LOG(TWO*Y(I)/RW)
      GO TO 24
23  C1(I,I)=D*LOG((RS-Z(I))*Z(I)/(RS*RW))
24  CONTINUE
      IF(N.EQ.1) GO TO 29
      K1=N-1
      DO 25 I=1,K1
      K2=I+1
      DO 26 J=K2,N
      GO TO (25,26,27),TYPE
25  D1=Z(I)*Z(I)+Y(I)*Y(I)
      D2=Z(J)*Z(J)+Y(J)*Y(J)
      ZD=Z(I)-Z(J)
      YD=Y(I)-Y(J)
      D1J2=ZD*ZD+YD*YD
      C1(I,J)=-D*LOG(D1*D2/(RW*RW*D1J2))
      C1(J,I)=C1(I,J)
      GO TO 26
26  ZD=Z(I)-Z(J)
      YD=Y(I)-Y(J)
      D1J2=ZD*ZD+YD*YD
      C1(I,J)=D*LOG((D1*D2+D1J2*Y(I)*Y(J))/D1J2)
      C1(J,I)=C1(I,J)
      GO TO 26
27  THETA=(Y(I)-Y(J))/D1J2*90
      R1=Z(I)*Z(I)
      R2=Z(J)*Z(J)
      C1(I,J)=D*LOG((R2/R1)*((R1+R2+RS*RS-TWO*Z(I)*Z(J)*RS*
      LOGS(T-ETA))/(-1+R1+R2+R2*RS*RS-TWO*Z(I)*Z(J)*R2*LOGS(THETA)))
      C1(J,I)=C1(I,J)
28  CONTINUE
C
C      COMPUTE THE PER-MIT-LENGTH CAPACITANCE MATRIX, C
C      (STORE C IN ARRAY C)
C
29  DO 31 I=1,N
      DO 30 J=1,N
      A(I,J)=C1(I,J)*CMTC
30  P(I,J)=ZEROC
31  P(I,I)=ONEC
      CALL LFCOIN(A,1,1,N,1,1,NA,KTP)
      KP=KN-12

```

```

XTALK123
XTALK124
XTALK125
XTALK126
XTALK127
XTALK128
XTALK129
XTALK130
XTALK131
XTALK132
XTALK133
XTALK134
XTALK135
XTALK136
XTALK137
XTALK138
XTALK139
XTALK140
XTALK141
XTALK142
XTALK143
XTALK144
XTALK145
XTALK146
XTALK147
XTALK148
XTALK149
XTALK150
XTALK151
XTALK152
XTALK153
XTALK154
XTALK155
XTALK156
XTALK157
XTALK158
XTALK159
XTALK160
XTALK161
XTALK162
XTALK163
XTALK164
XTALK165
XTALK166
XTALK167
XTALK168
XTALK169
XTALK170
XTALK171
XTALK172
XTALK173
XTALK174
XTALK175
XTALK176
XTALK177
XTALK178
XTALK179
XTALK180
XTALK181
XTALK182
XTALK183

```

376

```

IF(KFR.NE.1) KIR=0
WRITE(I,22) KFR
32 FORMAT(//,' PER-UNIT-LENGTH CAPACITANCE MATRIX INVERSION ERROR= ',
1Z//)
DO 33 I=1,N
DO 33 J=1,N
33 C(I,J)=D-E/L(P(I,J))

READ AND PRINT CHARACTERISTICS OF THE WIRES AND THE REFERENCE
CONDUCTOR TO BE USED IN THE SELF IMPEDANCE CALCULATIONS

GO TO (34,40,37),TYPE
34 READ(5,34) RWSO,SIGO,NSO
35 FORMAT(2I5X,10Z3),8X,I2)
WRITE(I,35) RWSO,SIGO,NSO
36 FORMAT(//,' REFERENCE WIRE IS STRANDED WITH EACH STRAND OF RADIUS=
I= ',1PE10.3,' MILS//' CONDUCTIVITY OF REFERENCE WIRE STRANDS= ',
2PE10.3,' SIEMENS PER METER//' NUMBER OF STRANDS= ',I2//')
RWSO=RWSO*CMIL
GO TO 40
37 READ(5,37) IS,SIGC
38 FORMAT(2I5X,10Z3)
WRITE(I,38) IS,SIGC
39 FORMAT(//,' SHIELD THICKNESS= ',1PE10.3,' METERS//' SHIELD CONDUCTIVITY=
1PE10.3,' SIEMENS PER METER//')
GO TO 43
40 READ(5,40) RGP,LOG
41 FORMAT(2I5X,10Z3)
WRITE(I,42) RGP,LOG
42 FORMAT(//,' GROUND PLANE RESISTANCE= ',1PE10.3,' OHMS PER METER//
1//' GROUND PLANE INDUCTANCE= ',1PE10.3,' HENRYS PER METER//')
43 WRITE(I,44)
44 FORMAT(//,' WIRE NUMBER',4X,' WIRE STRAND RADIUS (MILS)',11X,
1//' CONDUCTIVITY (SIEMENS PER METER)',10X,' NUMBER OF STRANDS//')
DO 47 I=1,N
READ(5,47) Z(I),Y(I),NS(I)
45 FORMAT(2I5X,10Z3),8X,I2)
WRITE(I,46) Z(I),Y(I),NS(I)
46 FORMAT(2X,12,14X,1PE10.3,35X,1PE10.1,32X,I2//)
47 Z(I)=Z(I)*CMIL

C
C READ AND PRINT MATRICES IN LEAD ADMITTANCE (IMPEDANCE) MATRICES
C AND SHORT CIRCUIT CURRENT SOURCE (OPEN CIRCUIT VOLTAGE SOURCE)
C VECTORS.
C (SHORT ADMITTANCE (IMPEDANCE) MATRICES AT X=0 IN ARRAY Y0 AND
C TEST AT X=L IN ARRAY YL. SHORT CIRCUIT CURRENT SOURCE
C (OPEN CIRCUIT VOLTAGE SOURCE) VECTORS AT X=0 IN ARRAY I0 AND
C THIS AT X=L IN ARRAY IL.)
C
IF(OPTION.EQ.2) GO TO (OPTION.EQ.2) GO TO 40
WRITE(I,48)
48 FORMAT(//,' ADMITTANCE AT X=0',10X,' CURRENT SOURCE AT X=0',
11X,' ADMITTANCE AT X=L',10X,' CURRENT SOURCE AT X=L//')
WRITE(I,49)
49 FORMAT(2I5X,10Z3),10X,' (AMPS)',22X,' (SIEMENS)',10X,' (AMPS) //')
GO TO 53
50 WRITE(I,51)
51 FORMAT(//,' IMPEDANCE AT X=0',11X,' VOLTAGE SOURCE AT X=0',
11X,' IMPEDANCE AT X=L',11X,' VOLTAGE SOURCE AT X=L//')
WRITE(I,52)
52 FORMAT(2I5X,10Z3),10X,' (VOLTS)',22X,' (HMS)',22X,' (VOLTS) //')

```

```

XTALK184
XTALK185
XTALK186
XTALK187
XTALK188
XTALK189
XTALK190
XTALK191
XTALK192
XTALK193
XTALK194
XTALK195
XTALK196
XTALK197
XTALK198
XTALK199
XTALK200
XTALK201
XTALK202
XTALK203
XTALK204
XTALK205
XTALK206
XTALK207
XTALK208
XTALK209
XTALK210
XTALK211
XTALK212
XTALK213
XTALK214
XTALK215
XTALK216
XTALK217
XTALK218
XTALK219
XTALK220
XTALK221
XTALK222
XTALK223
XTALK224
XTALK225
XTALK226
XTALK227
XTALK228
XTALK229
XTALK230
XTALK231
XTALK232
XTALK233
XTALK234
XTALK235
XTALK236
XTALK237
XTALK238
XTALK239
XTALK240
XTALK241
XTALK242
XTALK243
XTALK244

```





```

60 DO 71 I=1,N
   DO 70 J=1,N
     V1(I,J)=Y0(I,I)*C1(I,J)
70 V2(I,J)=Y0(I,I)*C1(I,J)
   V1(I)=10(I)
71 V2(I)=1L(I)
   GO TO 76
72 DO 73 I=1,N
   DO 74 J=1,N
     SUM0=Z+K1(C)
     SUML=Z+R1(C)
     DO 75 K=1,N
       SUM0=SUM0+Y0(I,K)*C1(K,J)
       SUML=SUML+Y1(I,K)*C1(K,J)
73 V1(I,J)=SUM0
74 V2(I,J)=SUML
   V1(I)=10(I)
75 V2(I)=1L(I)
76 CONTINUE
C
C   SUM THE ENTRIES IN EACH ROW OF C AND STORE IN ARRAY V2
C
   DO 77 I=1,N
     S=ZFN0
     DO 78 J=1,N
77 S=S+C(I,J)
78 V2(I)=S
C
C*****RIGID BODY SPRING CALCULATIONS*****
C
79 CONTINUE
   READ(1,80) (N=1,1) R
80 FORMAT(2D0,2)
   J04504=TW*PI*R
   J04504=XJ*W04A
C
C   COMPUTE THE WIRE AND REFERENCE CONDUCTOR SELF IMPEDANCES
C   (STORE SELF IMPEDANCES OF EACH WIRE IN ARRAY R AND THE SELF
C   IMPEDANCE OF THE REFERENCE CONDUCTOR IS STORED IN VARIABLE Z0)
C
   LDC=M0*PI
   DO 81 I=1,N
     DELTA=NB/(TNC+1)*PI*(Y(I)*R*M0*PI)
     SDC=ND/(PI*Y(I))*Z(I)*Z(I)
     IF(Z(I).LE.0) GO TO 82
     IF(Z(I).GT.0) GO TO 82
     Z(I)=(R2*Z(I)/DELTA+H+H)*R0C+J04504*(ONE/PI-R1*Z(I)/DELTA)
     LDC=LDC/S(I)
   GO TO 83
81 R(I)=(R0C+J04504*LDC)/NS(I)
   GO TO 83
82 Z(I)=(R1*Z(I)+R0C/DELTA+J04504*TW*DELTA+LDC/Z(I))/NS(I)
83 CONTINUE
   GO TO (94,97,99),TYPE
84 DELTA=NB/(TNC+1)*PI*(Y(I)*R*M0*PI)
   SDC=ND/(PI*Y(I))*Z(I)*Z(I)
   IF(R1*Z(I).LE.0) GO TO 85
   IF(R1*Z(I).GT.0) GO TO 85
   Z0=(R2*(R1*Z(I)/DELTA+H+H)*R0C+J04504*(ONE/PI-R1*W0C/DELTA)*LDC)
   /NS0
   GO TO 85

```

```

XTALK306
XTALK307
XTALK308
XTALK309
XTALK310
XTALK311
XTALK312
XTALK313
XTALK314
XTALK315
XTALK316
XTALK317
XTALK318
XTALK319
XTALK320
XTALK321
XTALK322
XTALK323
XTALK324
XTALK325
XTALK326
XTALK327
XTALK328
XTALK329
XTALK330
XTALK331
XTALK332
XTALK333
XTALK334
XTALK335
XTALK336
XTALK337
XTALK338
XTALK339
XTALK340
XTALK341
XTALK342
XTALK343
XTALK344
XTALK345
XTALK346
XTALK347
XTALK348
XTALK349
XTALK350
XTALK351
XTALK352
XTALK353
XTALK354
XTALK355
XTALK356
XTALK357
XTALK358
XTALK359
XTALK360
XTALK361
XTALK362
XTALK363
XTALK364
XTALK365
XTALK366

```

```

84 ZC=(PI*(1+JONFCA*ALF(C))/NSC
GO TO 91
86 ZC=(P5+KAS*NDZ/DELTA+JONFCA*TNF*D-DELTA*LDZ/RWSC)/NSC
GO TO 91
87 ZC=(P6+JONFCA*LEF)
GO TO 91
88 KDC=(N1/PI)*SIN(TH*(TWO*NS+TH))
DELTA=(N1/(TWO*PI)*SQRT(SIGG*F*MGP4PI))
IF(TH*DELTA-LTA*NS) GO TO 87
IF(TF,DF,TH*F*DLIA) GO TO 90
X=TW*TH/DELTA
SINH=(DEXP(X)-EXP(-X))*0.5
COSH=(DEXP(X)+EXP(-X))*0.5
ZC=((SINH+*SIN(X))+XJ*(SINH-DSIN(X)))/(TWO*PI*RS*SIGG*DELTA*
IF(SINH-COS(X))
GO TO 91
89 ZC=(UN*XJ*P4*TH/DELTA)*0.000
GO TO 91
90 ZC=(UN*XJ)/(TWO*PI*RS*SIGG*DELTA)
C
C COMPUTE THE EIGENVALUES AND THE EIGENVECTORS OF THE PRODUCT YZ
C (STORE THE EIGENVECTORS AS COLUMNS OF ARRAY T. STORE THE
C EIGENVALUES IN ARRAY R6)
91 DO 97 I=1,N
DO 97 J=1,N
A(I,J)=JONFCA*(V(I)+ZC*O(I,J)+F(J))
92 A(I,I)=A(I,I)-ZC*UN*P3/VV
CALL SIGG0(A,N,N,UN,F,T,N,WS,LEF)
LEF=LEF-1.0
IF(LEF.LT.0) LEF=0
C
C COMPUTE THE INVERSE OF THE TRANSFORMATION MATRIX, T
C (STORE IN ARRAY T)
93 DO 94 I=1,N
DO 94 J=1,N
T(I,J)=ZERR0
94 T(I,I)=1.0
CALL LUT01(A,N,N,T,I,N,N,0,NA,MEF)
MEF=MEF-1.0
IF(MEF.LT.0) MEF=0
C
C COMPUTE THE TERMINAL VOLTAGES
C FROM THE EQUATIONS
95 DO 96 I=1,N
S=ZERR0
SL=ZERR0
DO 97 J=1,N
SUML=SUML+V(I)*T(I,J)
SUMR=SUMR+V(I)*T(I,J)
SL=SL+T(I,J)*V(I)
A(I,J)=S+X

```

```

XTALK347
XTALK348
XTALK349
XTALK350
XTALK351
XTALK352
XTALK353
XTALK354
XTALK355
XTALK356
XTALK357
XTALK358
XTALK359
XTALK360
XTALK361
XTALK362
XTALK363
XTALK364
XTALK365
XTALK366
XTALK367
XTALK368
XTALK369
XTALK370
XTALK371
XTALK372
XTALK373
XTALK374
XTALK375
XTALK376
XTALK377
XTALK378
XTALK379
XTALK380
XTALK381
XTALK382
XTALK383
XTALK384
XTALK385
XTALK386
XTALK387
XTALK388
XTALK389
XTALK390
XTALK391
XTALK392
XTALK393
XTALK394
XTALK395
XTALK396
XTALK397
XTALK398
XTALK399
XTALK400
XTALK401
XTALK402
XTALK403
XTALK404
XTALK405
XTALK406
XTALK407
XTALK408
XTALK409
XTALK410
XTALK411
XTALK412
XTALK413
XTALK414
XTALK415
XTALK416
XTALK417
XTALK418
XTALK419
XTALK420
XTALK421
XTALK422
XTALK423
XTALK424
XTALK425
XTALK426
XTALK427

```

376



110	J=1,N	YTALK480
	SO=SC-YO(I,J)*C(J)	YTALK490
111	SL=SL+YL(I,J)*C(J)	YTALK491
	YO(I,I)=IO(I)+C	YTALK492
112	YL(I,I)=-IL(I)+SL	YTALK493
	DO 113 I=1,N	YTALK494
	SO=ZERO	YTALK495
	SL=ZERO	YTALK496
	DO 112 J=1,N	YTALK497
	SO=SO+Y(I,J)*YO(J,J)	YTALK498
113	SL=SL+Y(I,J)*YL(J,J)	YTALK499
	P(I,I)=SO	YTALK500
114	A(I,I)=SL	YTALK501
	DO 115 I=1,N	YTALK502
	SO=ZERO	YTALK503
	SL=ZERO	YTALK504
	DO 115 J=1,N	YTALK505
	SO=SO+Y(I,J)*C(J)	YTALK506
115	SL=SL+Y(I,J)*C(J)	YTALK507
	P(I,I)=SO	YTALK508
116	A(I,I)=SL	YTALK509
117	DO 118 I=1,N	YTALK510
	SO=ZERO	YTALK511
	SL=ZERO	YTALK512
	DO 118 J=1,N	YTALK513
	SO=SO+Y(I,J)*P(J,J)	YTALK514
118	SL=SL+Y(I,J)*P(J,J)	YTALK515
	VO=S	YTALK516
	VL=SL	YTALK517
	VO=REAL(VO)	YTALK518
	VL=REAL(VL)	YTALK519
	VO=CMPLX(VO)	YTALK520
	VL=CMPLX(VL)	YTALK521
	VOI=PI*AC(VO)	YTALK522
	VLI=PI*AC(VL)	YTALK523
	IF(VLI.EQ.ZERO) VLI=ZERO	YTALK524
	IF(VLI.EQ.ZERO) VLI=ZERO	YTALK525
	IF(VLI.EQ.ZERO) VLI=ZERO	YTALK526
	VOI=ATAN2(VOI,VO)/PI	YTALK527
	VLI=ATAN2(VLI,VL)/PI	YTALK528
	WRITE(1,10) J,VOI,VLI,VL1,VL2	YTALK529
119	FORMAT(10X,10A,10F10.3,10X,10F10.3,10X,10F10.3)	YTALK530
120	CONTINUE	YTALK531
	GO TO 70	YTALK532
121	STOP	YTALK533
	END	YTALK534

876

TABLE B-1

Changes in XTALK2 to Convert  
to Single Precision Arithmetic

Delete Card 057

<u>Card Number</u>	<u>Double</u>	<u>Single</u>
059	REAL *8	REAL
061	COMPLEX *16	COMPLEX
065	3.141592653D0	3.1415926E0
065	2.997925D8	2.997925E8
066-068	change all D's	to E's
070	DCMLX(0.D0,0.D0)	CMPLX(0.E0,0.E0)
071	DCMLX(1.D0,0.D0)	CMPLX(1.E0,0.E0)
072	DCMLX(0.D0,1.D0)	CMPLX(0.E0,1.E0)
140	DLOG	ALOG
142	DLOG	ALOG
144	DLOG	ALOG
147	DLOG	ALOG
163	DLOG	ALOG
169	DLOG	ALOG
170	DCOS	COS
170	DCOS	COS
190	DREAL	REAL
348	DSQRT	SQRT
360	DSQRT	SQRT
374	DSQRT	SQRT
378	DEXP	EXP
378	DEXP	EXP

<u>Card Number</u>	<u>Double</u>	<u>Single</u>
379	DEXP	EXP
379	DEXP	EXP
380	DSIN	SIN
380	DSIN	SIN
381	DCOS	COS
432	CDSQRT	CSQRT
433	CDEXP	CEXP
434	CDEXP	CEXP
519	CDABS	CABS
520	CDABS	CABS
521	DREAL	REAL
522	DIMAG	AIMAG
523	DREAL	REAL
524	DIMAG	AIMAG
527	DATAN2	ATAN2
528	DATAN2	ATAN2

376

APPENDIX C

FLATPAK

Program Listing





```

READ(5,1) N,OPTION,L
1 FORMAT(IX,1Z,OX,1Z,EO,2)
IF(OPTION.EQ.11.OR.OPTION.EQ.12) GO TO 3
IF(OPTION.EQ.21.OR.OPTION.EQ.22) GO TO 3
WRITE(6,2)
2 FORMAT(' LOAD STRUCTURE OPTION ERROR'/' OPTION MUST EQUAL 11,12,21,22')
11,OR 22'/'')
GO TO 60
3 NP=1,N
WRITE(6,4) NP,L,OPTION
4 FORMAT(1F1,4X,'FLATPAR'/'/'
145X,1Z,' PARALLEL WIRES'/'/'
23X,' LINE LENGTH= ',1P12.6,' METERS'/'/'
342X,' LOAD STRUCTURE OPTION= ',1Z'/'')
C
C READ ENTRIES IN THE PER-UNIT-LENGTH TRANSMISSION LINE
C CAPACITANCE MATRIX, C (COMPUTED WITH GETCAP)
C (STORE C IN ARRAY C)
C
DO I=1,N
DO J=1,N
READ(5,5) N,M,L(K,M)
5 FORMAT(4X,1Z,OX,1Z,OX,1Z,EO)
6 C(M,K)=C(K,M)
C
C READ ENTRIES IN THE PER-UNIT-LENGTH TRANSMISSION LINE
C CAPACITANCE MATRIX WITH THE WIRE INSULATIONS REMOVED, CU, (COMPUTED
C WITH GETCAP)
C (STORE CU IN ARRAY CU)
C
DO I=1,N
DO J=1,N
READ(5,7) K,M,CU(K,M)
7 FORMAT(4X,1Z,OX,1Z,OX,1Z,EO)
8 CU(M,K)=CU(K,M)
C
C COMPUTE THE EIGENVECTORS (COLUMNS OF THE MATRIX T) AND EIGENVALUES
C OF THE MATRIX PRODUCT CU
C (THE ARRAYS T1 AND G CONTAIN T AND THE INVERSE OF THE EIGENVALUES
C FOR THE INVERSE EQUIVALENT OR THE INVERSE OF THE TRANSPOSE OF T
C AND THE EIGENVALUES FOR THE SHORTER EQUIVALENT, RESPECTIVELY)
C
IF(N.EQ.1) GO TO 9
CALL HROUT(N,CU,C,G,T1,NP)
GO TO 10
9 G(1,1)=C(1,1)/C(1,1)
T1(1,1)=(G(1,1)/SQRT(C(1,1)))
10 DO 12 I=1,N
DO 11 J=1,N
11 C(I,J)=T1(I,J)
12 G(I)=G(I)/(1+SQRT(1+C(I,1)))
IF(OPTION.EQ.21.OR.OPTION.EQ.22) GO TO 14
DO 14 I=1,N
DO 13 J=1,N
A(I,J)=T1(I,J)+G(I)
13 P(I,J)=2*G(I)
14 P(I,J)=G(I)
CALL HROUT(N,P,P,P,NO,NO,NO,NO)
KRF=KRF+100
IF(NP.EQ.1) KRF=0
FLATP062
FLATP063
FLATP064
FLATP065
FLATP066
FLATP067
FLATP068
FLATP069
FLATP070
FLATP071
FLATP072
FLATP073
FLATP074
FLATP075
FLATP076
FLATP077
FLATP078
FLATP079
FLATP080
FLATP081
FLATP082
FLATP083
FLATP084
FLATP085
FLATP086
FLATP087
FLATP088
FLATP089
FLATP090
FLATP091
FLATP092
FLATP093
FLATP094
FLATP095
FLATP096
FLATP097
FLATP098
FLATP099
FLATP100
FLATP101
FLATP102
FLATP103
FLATP104
FLATP105
FLATP106
FLATP107
FLATP108
FLATP109
FLATP110
FLATP111
FLATP112
FLATP113
FLATP114
FLATP115
FLATP116
FLATP117
FLATP118
FLATP119
FLATP120
FLATP121
FLATP122

```

```

      WRITE(6,15) KLF
15  FORMAT(//,' TRANSFORMATION MATRIX INVERSION ERROR= ',I2//)
      GO 17 I=1,N
      GO 16 J=1,N
16  T1(I,J)=UREAL(P(I,J,1))
17  U(I)=UNE/G(I)
C
C      READ AND PRINT ENTRIES IN LOAD ADMITTANCE (IMPEDANCE) MATRICES
C      AND SHORT CIRCUIT CURRENT SOURCE (OPEN CIRCUIT VOLTAGE SOURCE)
C      VECTORS
C      (STORE ADMITTANCE (IMPEDANCE) MATRICES AT X=0 IN ARRAY Y0 AND THOSE
C      AT X=L IN ARRAY YL. STORE SHORT CIRCUIT CURRENT SOURCE (OPEN
C      CIRCUIT VOLTAGE SOURCE) VECTORS AT X=0 IN ARRAY I0 AND THOSE
C      AT X=L IN ARRAY IL.)
C
20  IF (OPTION.EQ.11.OR.OPTION.EQ.12) GO TO 21
      WRITE(6,19)
19  FORMAT(//,10X,' ADMITTANCE AT X=0',10X,' CURRENT SOURCE AT X=0',
11X,' ADMITTANCE AT X=L',10X,' CURRENT SOURCE AT X=L'//)
      WRITE(6,20)
20  FORMAT(21X,' (SIEMENS)',20X,' (AMPS)',22X,' (SIEMENS)',20X,' (AMPS)'//)
      GO TO 24
21  WRITE(6,22)
22  FORMAT(//,12X,' IMPEDANCE AT X=0',11X,' VOLTAGE SOURCE AT X=0',
11X,' IMPEDANCE AT X=L',11X,' VOLTAGE SOURCE AT X=L'//)
      WRITE(6,23)
23  FORMAT(20X,' (OHMS)',20X,' (VOLTS)',24X,' (OHMS)',20X,' (VOLTS)'//)
24  WRITE(6,25)
25  FORMAT(' ENTRY',10X,' REAL',11X,' IMAG',11X,' REAL',11X,' IMAG',11X,
1' REAL',11X,' IMAG',11X,' REAL',11X,' IMAG'//)
      DO 27 I=1,N
      READ(5,26) Y0K,Y0L,I0(I),YLF,YL1,IL(I)
26  FORMAT(8(E10.3))
      Y0(I,1)=Y0K+X0*Y0L
      YL(I,1)=YLF+X0*YL1
      WRITE(6,27) I,1,Y0(I,1),I0(I),YL(I,1),IL(I)
27  FORMAT(1X,I2,2X,I2,2(5X,1PE10.3)//)
28  CONTINUE
      IF (OPTION.EQ.11.OR.OPTION.EQ.21) GO TO 32
      IF (N.EQ.1) GO TO 32
      K1=N-1
      DO 31 I=1,K1
      K2=I+1
      DO 31 J=K2,N
      READ(5,29) YCF,YC1,YLR,YL1
29  FORMAT(2(E10.3),2(5X,2(E10.3)))
      Y0(I,J)=YCF+X0*YC1
      YL(I,J)=YLR+X0*YL1
      Y0(J,I)=Y0(I,J)
      YL(J,I)=YL(I,J)
      WRITE(6,30) I,J,Y0(I,J),YL(I,J)
30  FORMAT(1X,I2,2X,I2,2(5X,1PE10.3),2(5X,1PE10.3))
31  CONTINUE
C
C      COMPUTE THE MATRICES TTRAN*Z0*T, TTRAN*ZL*T, TTRAN*Y0, -TTRAN*YL
C      FOR THE THEVENIN EQUIVALENT OR TINV*Y0*TINVTAN, TINV*YL*TINVTRAN,
C      TINV*I0, TINV*IL FOR THE NORTON EQUIVALENT AND STORE IN ARRAYS
C      Y0,YL,I0,IL, RESPECTIVELY.
C
32  IF (OPTION.EQ.12.OR.OPTION.EQ.22) GO TO 35
      DO 34 I=1,N

```

```

FLATP123
FLATP124
FLATP125
FLATP126
FLATP127
FLATP128
FLATP129
FLATP130
FLATP131
FLATP132
FLATP133
FLATP134
FLATP135
FLATP136
FLATP137
FLATP138
FLATP139
FLATP140
FLATP141
FLATP142
FLATP143
FLATP144
FLATP145
FLATP146
FLATP147
FLATP148
FLATP149
FLATP150
FLATP151
FLATP152
FLATP153
FLATP154
FLATP155
FLATP156
FLATP157
FLATP158
FLATP159
FLATP160
FLATP161
FLATP162
FLATP163
FLATP164
FLATP165
FLATP166
FLATP167
FLATP168
FLATP169
FLATP170
FLATP171
FLATP172
FLATP173
FLATP174
FLATP175
FLATP176
FLATP177
FLATP178
FLATP179
FLATP180
FLATP181
FLATP182
FLATP183

```

376

```

SU=ZERUL
SL=ZERUL
DO 33 J=1,N
A(1,J)=YU(1,1)*T1(1,J)
P(1,J)=YL(1,1)*T1(1,J)
SU=SU+T1(J,1)*IC(J)
33 SL=SL+T1(J,1)*IL(J)
F(1)=SU
34 WA(1)=SL
GO TO 34
DO 35 I=1,N
SO=ZERUL
SL=ZERUL
DO 37 J=1,N
SUMU=ZERUL
SUML=ZERUL
DO 36 K=1,N
SUMU=SUMU+YU(I,K)*T1(K,J)
36 SUML=SUML+YL(I,K)*T1(K,J)
A(I,J)=SUMU
P(I,J)=SUML
SO=SO+T1(J,1)*IC(J)
37 SL=SL+T1(J,1)*IL(J)
B(I)=SO
38 WA(I)=SL
DO 39 I=1,N
DO 41 J=1,N
SO=ZERUL
SL=ZERUL
DO 40 K=1,N
SU=SU+T1(K,1)*A(K,J)
40 SL=SL+T1(K,1)*P(K,J)
YU(I,J)=SU
41 YL(I,J)=SL
IC(I)=B(I)
IL(I)=WA(I)
42 IF(OPTION.EQ.1).OR.(OPTION.EQ.12) IL(I)=-IL(I)
C
C *****FREQUENCY DEPENDENT CALCULATIONS*****
C
43 CONTINUE
READ(5,44,END=60) F
44 FORMAT(1E10.3)
OMEGA=TWU*PI*F
C
C COMPUTE THE TERMINAL VOLTAGE
C
C FOR THE EQUATIONS
C
DO 45 I=1,N
W=C(I)
IF(OPTION.EQ.1).OR.(OPTION.EQ.12) W=CF/W
W=C*IG+W*L
C(I,1)=SCLS(W)
45 F(1,1)=A0*SIN(W)
DO 46 I=1,N
SU=ZERUL
DO 47 J=1,N
SL=ZERUL
DO 48 K=1,N
46 SL=SL+YL(I,K)*C(K)+P(K,1)*IC(K)

```

```

FLATP184
FLATP185
FLATP186
FLATP187
FLATP188
FLATP189
FLATP190
FLATP191
FLATP192
FLATP193
FLATP194
FLATP195
FLATP196
FLATP197
FLATP198
FLATP199
FLATP200
FLATP201
FLATP202
FLATP203
FLATP204
FLATP205
FLATP206
FLATP207
FLATP208
FLATP209
FLATP210
FLATP211
FLATP212
FLATP213
FLATP214
FLATP215
FLATP216
FLATP217
FLATP218
FLATP219
FLATP220
FLATP221
FLATP222
FLATP223
FLATP224
FLATP225
FLATP226
FLATP227
FLATP228
FLATP229
FLATP230
FLATP231
FLATP232
FLATP233
FLATP234
FLATP235
FLATP236
FLATP237
FLATP238
FLATP239
FLATP240
FLATP241
FLATP242
FLATP243
FLATP244

```

```

      A(1,J)=SL+YL(1,J)*G(J,J)+YU(1,J)*GU(1,J)
47 SL=SL+YL(1,J)*G(J,J)+P(J,J)*IC(J)
      A(1,1)=A(1,1)+P(1,1)/G(1)
48 B(1)=SU+GU(1,1)*IC(1)+IL(1)
C
C      SOLVE THE EQUATIONS
C
      CALL LEGTIC(A,N,N,B,1,N,G,WA,IER)
      IER=IER-12L
      IF(IER.NE.1) IER=0
      WRITE(6,49) I,IER
49 FORMAT(1H1,' FREQUENCY(HERTZ)= ',1PE11.4,10X,' SOLUTION ERROR= ',
12X,12//)
      WRITE(6,50)
50 FORMAT(10A,' WIRE',5X,' VCM(VOLTS)',5X,' VCA(DEGREES)',5X,
1' VLM(VOLTS)',5X,' VLA(DEGREES)')//)
C
C      COMPUTE AND PRINT THE TERMINAL VOLTAGES
C
      DO 52 I=1,N
      SU=ZEROC
      DO 51 J=1,N
51 SU=SU+YU(1,J)*C(J)
52 W(1)=-G(1)*P(1,1)*IC(1)+GU(1,1)*B(1)+G(1)*P(1,1)*SO
      IF(UP11CN.EQ.21.OR.UP11CN.EQ.22) GO TO 56
      DO 54 I=1,N
      SU=ZEROC
      SL=ZEROC
      DO 53 J=1,N
      SC=SC-YU(1,J)*C(J)
53 SL=SL+YL(1,J)*WA(J)
      A(1,1)=IC(1)+SL
54 P(1,1)=-IL(1)+SL
      DO 55 I=1,N
      U(1)=A(1,1)
55 WA(1)=P(1,1)
56 DO 57 I=1,N
      SU=ZEROC
      SL=ZEROC
      DO 57 J=1,N
      SC=SU+C(1,J)*C(J)
57 SL=SL+C(1,J)*WA(J)
      VC=SU
      VL=SL
      VCM=CDABS(VC)
      VLM=CDABS(VL)
      VCA=UREAL(VC)
      VCI=UIMAG(VC)
      VLA=UREAL(VL)
      VLI=UIMAG(VL)
      IF(VCM.EQ.ZERO.AND.VCI.EQ.ZERO) VCF=ONE
      IF(VLA.EQ.ZERO.AND.VLI.EQ.ZERO) VLF=ONE
      VCA=ATAN2(VCI,VCA)*ONE/PI
      VLA=ATAN2(VLI,VLA)*ONE/PI
      WRITE(6,58) I,VCM,VCA,VLM,VLA
58 FORMAT(17X,12,2X,1PE10.5,5X,1PE10.5,10X,1PE10.5,5X,1PE10.5//)
59 CONTINUE
      GO TO 45
60 STOP
      END

```

```

FLATP245
FLATP246
FLATP247
FLATP248
FLATP249
FLATP250
FLATP251
FLATP252
FLATP253
FLATP254
FLATP255
FLATP256
FLATP257
FLATP258
FLATP259
FLATP260
FLATP261
FLATP262
FLATP263
FLATP264
FLATP265
FLATP266
FLATP267
FLATP268
FLATP269
FLATP270
FLATP271
FLATP272
FLATP273
FLATP274
FLATP275
FLATP276
FLATP277
FLATP278
FLATP279
FLATP280
FLATP281
FLATP282
FLATP283
FLATP284
FLATP285
FLATP286
FLATP287
FLATP288
FLATP289
FLATP290
FLATP291
FLATP292
FLATP293
FLATP294
FLATP295
FLATP296
FLATP297
FLATP298
FLATP299
FLATP300
FLATP301
FLATP302
FLATP303
FLATP304

```

376

TABLE C-1

Changes in FLATPAK to Convert  
to Single Precision Arithmetic

Delete Card 048

<u>Card Number</u>	<u>Double</u>	<u>Single</u>
050	REAL *8	REAL
051	COMPLEX *16	COMPLEX
053	3.141592653D0	3.1415926E0
053	2.997925D8	2.997925E8
054	change all D's to	E's
055	DCMPLX(0.D0,0.D0)	CMPLX(0.E0,0.E0)
056	DCMPLX(1.D0,0.D0)	CMPLX(1.E0,0.E0)
057	DCMPLX(0.D0,1.D0)	CMPLX(0.E0,1.E0)
109	DSQRT	SQRT
113	DSQRT	SQRT
17	DREAL	REAL
237	DCOS	COS
238	DSIN	SIN
289	CDABS	CABS
290	CDABS	CABS
291	DREAL	REAL
292	DIMAG	AIMAG
293	DREAL	REAL
294	DIMAG	AIMAG
297	DATAN2	ATAN2
298	DATAN2	ATAN2

APPENDIX D

FLATPAK2

Program Listing

376





```

CP5/.5107,06150/150.50/
VV=7*V
ZK=DCOMPLX(0.00,0.00)
ZNEC=DCOMPLX(1.00,0.00)
XJ=DCOMPLX(0.00,1.00)
FLATP062
FLATP063
FLATP064
FLATP065
FLATP066
FLATP067
C
C*****FREQUENCY INDEPENDENT CALCULATIONS*****FLATP068
C
C READ AND PRINT INPUT DATA FLATP069
C
C READ(5,1) N,OPTION,C FLATP070
C
C 1 FORMAT(1X,12,2X,12,10.0) FLATP071
C IF(OPTION.EQ.11.OR.OPTION.EQ.12) GO TO 2 FLATP072
C 2 FORMAT(1X,21,2X,12,2X,10.0) GO TO 3 FLATP073
C 3 FLATP074
C 4 FLATP075
C 5 FLATP076
C 6 FLATP077
C 7 FLATP078
C 8 FLATP079
C 9 FLATP080
C 10 FLATP081
C 11 FLATP082
C 12 FLATP083
C 13 FLATP084
C 14 FLATP085
C 15 FLATP086
C 16 FLATP087
C 17 FLATP088
C 18 FLATP089
C 19 FLATP090
C 20 FLATP091
C 21 FLATP092
C 22 FLATP093
C 23 FLATP094
C 24 FLATP095
C 25 FLATP096
C 26 FLATP097
C 27 FLATP098
C 28 FLATP099
C 29 FLATP100
C 30 FLATP101
C 31 FLATP102
C 32 FLATP103
C 33 FLATP104
C 34 FLATP105
C 35 FLATP106
C 36 FLATP107
C 37 FLATP108
C 38 FLATP109
C 39 FLATP110
C 40 FLATP111
C 41 FLATP112
C 42 FLATP113
C 43 FLATP114
C 44 FLATP115
C 45 FLATP116
C 46 FLATP117
C 47 FLATP118
C 48 FLATP119
C 49 FLATP120
C 50 FLATP121
C 51 FLATP122

```

576

```

NEK=NEK-125
IF(KER.NE.0) KER=0
IF(NER.NE.0) NER=0
WRITE(6,11) KER
WRITE(6,11) NER
11 FORMAT(//,' PER-UNIT-LENGTH CAPACITANCE MATRIX INVERSION ERROR= ',
112//)
DO 12 I=1,N
DO 12 J=1,N
C(I,J)=DREAL(T(I,J))
12 C(I,J)=DREAL(P(I,J))/VV
C
READ AND PRINT CHARACTERISTICS OF THE WIRES TO BE USED IN THE SELF
C IMPEDANCE CALCULATIONS
C
READ(5,13) RWS,SIG,NS
13 FORMAT(2(DX,010.5),8X,12)
WRITE(6,14) RWS,SIG,NS
14 FORMAT(/////,' WIRES ARE STRANDED WITH EACH STRAND OF RADIUS= ',
15PE10.5,' MILS'///' CONDUCTIVITY OF WIRE STRANDS= ',
2PE10.5,' SIEMENS PER METER'///' NUMBER OF STRANDS= ',I2////)
RWS=RWS*CMTH
C
READ AND PRINT ENTRIES IN LOAD ADMITTANCE(IMPEDANCE) MATRICES
AND SHORT CIRCUIT CURRENT SOURCE(OPEN CIRCUIT VOLTAGE SOURCE)
C VECTORS
C (SHORT ADMITTANCE(IMPEDANCE) MATRICES AT X=0 IN ARRAY Y0 AND
C THOSE AT X=L IN ARRAY YL. SOURCE SHORT CIRCUIT CURRENT SOURCE
C (OPEN CIRCUIT VOLTAGE SOURCE) VECTORS AT X=0 IN ARRAY I0 AND
C THOSE AT X=L IN ARRAY IL.)
C
IF(OPTION.EQ.11.OR.OPTION.EQ.12) GO TO 17
WRITE(6,15)
15 FORMAT(//,12X,' ADMITTANCE AT X=0',10X,' CURRENT SOURCE AT X=0',
112X,' ADMITTANCE AT X=L',10X,' CURRENT SOURCE AT X=L'//)
WRITE(6,20)
16 FORMAT(21X,' (SIEMENS)',22X,' (AMPS)',22X,' (SIEMENS)',23X,' (AMPS)'//)
GO TO 20
17 WRITE(6,18)
18 FORMAT(//,10X,' IMPEDANCE AT X=0',11X,' VOLTAGE SOURCE AT X=0',
112X,' IMPEDANCE AT X=L',11X,' VOLTAGE SOURCE AT X=L'//)
WRITE(6,19)
19 FORMAT(25X,' (OHMS)',25X,' (VOLTS)',24X,' (OHMS)',23X,' (VOLTS)'//)
20 WRITE(6,21)
21 FORMAT(' 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100 101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117 118 119 120 121 122 123 124 125 126 127 128 129 130 131 132 133 134 135 136 137 138 139 140 141 142 143 144 145 146 147 148 149 150 151 152 153 154 155 156 157 158 159 160 161 162 163 164 165 166 167 168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198 199 200 201 202 203 204 205 206 207 208 209 210 211 212 213 214 215 216 217 218 219 220 221 222 223 224 225 226 227 228 229 230 231 232 233 234 235 236 237 238 239 240 241 242 243 244 245 246 247 248 249 250 251 252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270 271 272 273 274 275 276 277 278 279 280 281 282 283 284 285 286 287 288 289 290 291 292 293 294 295 296 297 298 299 300 301 302 303 304 305 306 307 308 309 310 311 312 313 314 315 316 317 318 319 320 321 322 323 324 325 326 327 328 329 330 331 332 333 334 335 336 337 338 339 340 341 342 343 344 345 346 347 348 349 350 351 352 353 354 355 356 357 358 359 360 361 362 363 364 365 366 367 368 369 370 371 372 373 374 375 376 377 378 379 380 381 382 383 384 385 386 387 388 389 390 391 392 393 394 395 396 397 398 399 400 401 402 403 404 405 406 407 408 409 410 411 412 413 414 415 416 417 418 419 420 421 422 423 424 425 426 427 428 429 430 431 432 433 434 435 436 437 438 439 440 441 442 443 444 445 446 447 448 449 450 451 452 453 454 455 456 457 458 459 460 461 462 463 464 465 466 467 468 469 470 471 472 473 474 475 476 477 478 479 480 481 482 483 484 485 486 487 488 489 490 491 492 493 494 495 496 497 498 499 500 501 502 503 504 505 506 507 508 509 510 511 512 513 514 515 516 517 518 519 520 521 522 523 524 525 526 527 528 529 530 531 532 533 534 535 536 537 538 539 540 541 542 543 544 545 546 547 548 549 550 551 552 553 554 555 556 557 558 559 560 561 562 563 564 565 566 567 568 569 570 571 572 573 574 575 576 577 578 579 580 581 582 583 584 585 586 587 588 589 590 591 592 593 594 595 596 597 598 599 600 601 602 603 604 605 606 607 608 609 610 611 612 613 614 615 616 617 618 619 620 621 622 623 624 625 626 627 628 629 630 631 632 633 634 635 636 637 638 639 640 641 642 643 644 645 646 647 648 649 650 651 652 653 654 655 656 657 658 659 660 661 662 663 664 665 666 667 668 669 670 671 672 673 674 675 676 677 678 679 680 681 682 683 684 685 686 687 688 689 690 691 692 693 694 695 696 697 698 699 700 701 702 703 704 705 706 707 708 709 710 711 712 713 714 715 716 717 718 719 720 721 722 723 724 725 726 727 728 729 730 731 732 733 734 735 736 737 738 739 740 741 742 743 744 745 746 747 748 749 750 751 752 753 754 755 756 757 758 759 760 761 762 763 764 765 766 767 768 769 770 771 772 773 774 775 776 777 778 779 780 781 782 783 784 785 786 787 788 789 790 791 792 793 794 795 796 797 798 799 800 801 802 803 804 805 806 807 808 809 810 811 812 813 814 815 816 817 818 819 820 821 822 823 824 825 826 827 828 829 830 831 832 833 834 835 836 837 838 839 840 841 842 843 844 845 846 847 848 849 850 851 852 853 854 855 856 857 858 859 860 861 862 863 864 865 866 867 868 869 870 871 872 873 874 875 876 877 878 879 880 881 882 883 884 885 886 887 888 889 890 891 892 893 894 895 896 897 898 899 900 901 902 903 904 905 906 907 908 909 910 911 912 913 914 915 916 917 918 919 920 921 922 923 924 925 926 927 928 929 930 931 932 933 934 935 936 937 938 939 940 941 942 943 944 945 946 947 948 949 950 951 952 953 954 955 956 957 958 959 960 961 962 963 964 965 966 967 968 969 970 971 972 973 974 975 976 977 978 979 980 981 982 983 984 985 986 987 988 989 990 991 992 993 994 995 996 997 998 999 1000')
22 Y0(I,1)=Y0R+XJ*Y0I
YL(I,1)=YLR+XJ*YLI
WRITE(6,23) I,Y0(I,1),X0(I),YL(I,1),IL(I)
23 FORMAT(11X,12,2X,12,3(DX,1PE10.5)//)
24 CONTINUE
IF(OPTION.EQ.11.OR.OPTION.EQ.21) GO TO 2F
IF(N.EQ.1) GO TO 2C
K2=1
DO 27 I=1,N1
K2=I+1
DO 27 J=K2,N
READ(5,25) Y0R,Y0I,YLR,YLI

```

25	FORMAT(2(I10.3),20X,2(F10.3))	FLATP184
	Y0(I,J)=Y0I+XJ+Y0I	FLATP185
	YL(I,J)=YLI+XJ*YLI	FLATP186
	Y0(J,I)=Y0(I,J)	FLATP187
	YL(J,I)=YL(I,J)	FLATP188
	WRITE(6,20) I,J,Y0(I,J),YL(I,J)	FLATP189
26	FORMAT(1X,I2,2X,I2,2(5X,1PE10.3),50X,2(5X,1PE10.3))	FLATP190
27	CONTINUE	FLATP191
C		FLATP192
C	COMPUTE AND STORE THE MATRICES AND VECTORS C*70, C*ZL, C*V0, C*VL	FLATP193
C	FOR THE INVERSE EQUIVALENT OF Y0*CINV, YL*CINV, I0, IL FOR THE	FLATP194
C	NORMIN EQUIVALENT IN ARRAYS M1,M2,V1,V2, RESPECTIVELY	FLATP195
		FLATP196
28	IF(OPTION.EQ.11) GO TO 29	FLATP197
	IF(OPTION.EQ.12) GO TO 32	FLATP198
	IF(OPTION.EQ.21) GO TO 30	FLATP199
	IF(OPTION.EQ.22) GO TO 39	FLATP200
29	DO 31 I=1,N	FLATP201
	S0=ZEROC	FLATP202
	SL=ZEROC	FLATP203
	DO 30 J=1,N	FLATP204
	M1(I,J)=C(I,J)*Y0(J,J)	FLATP205
	M2(I,J)=C(I,J)*YL(J,J)	FLATP206
	S0=S0+C(I,J)+I0(J)	FLATP207
30	SL=SL+C(I,J)*IL(J)	FLATP208
	V1(I)=S0	FLATP209
31	VL(I)=SL	FLATP210
	GO TO 43	FLATP211
32	DO 33 I=1,N	FLATP212
	S0=ZEROC	FLATP213
	SL=ZEROC	FLATP214
	DO 34 J=1,N	FLATP215
	SUM0=ZEROC	FLATP216
	SUML=ZEROC	FLATP217
	DO 35 K=1,N	FLATP218
	SUM0=SUM0+C(I,K)*Y0(K,J)	FLATP219
33	SUML=SUML+C(I,K)*YL(K,J)	FLATP220
	S0=S0+C(I,J)+I0(J)	FLATP221
	SL=SL+C(I,J)*IL(J)	FLATP222
	M1(I,J)=SUM0	FLATP223
34	M2(I,J)=SUML	FLATP224
	V1(I)=S0	FLATP225
35	VL(I)=SL	FLATP226
	GO TO 43	FLATP227
36	DO 36 I=1,N	FLATP228
	DO 37 J=1,N	FLATP229
	M1(I,J)=Y0(I,I)+C1(I,J)	FLATP230
37	M2(I,J)=YL(I,I)+C1(I,J)	FLATP231
	V1(I)=I0(I)	FLATP232
38	VL(I)=IL(I)	FLATP233
	GO TO 43	FLATP234
39	DO 42 I=1,N	FLATP235
	DO 41 J=1,N	FLATP236
	SUM0=ZEROC	FLATP237
	SUML=ZEROC	FLATP238
	DO 40 K=1,N	FLATP239
	SUM0=SUM0+Y0(I,K)*C1(K,J)	FLATP240
40	SUML=SUML+YL(I,K)*C1(K,J)	FLATP241
	M1(I,J)=SUM0	FLATP242
41	M2(I,J)=SUML	FLATP243
	V1(I)=I0(I)	FLATP244

```

42 V2(I)=IL(I)
43 CONTINUE
C
C COMPUTE THE MATRIX C*L AND STORE IN ARRAY CO. COMPUTE THE SUMS
C OF ELEMENTS IN EACH ROW OF C AND STORE IN ARRAY V3.
C
DO 46 I=1,N
S=ZLRU
DO 45 J=1,N
S2=ZLRU
DO 44 K=1,N
44 S=S+C(I,K)*CO(K,J)
P(1,J)=S*UNCL
45 S=S+C(I,J)
46 V3(I)=S
DO 47 I=1,N
DO 47 J=1,N
47 CO(I,J)=UNCL(P(I,J))
C
C *****FREQUENTLY DEPENDENT CALCULATIONS*****
C
48 CONTINUE
READ(S,*,END=11) F
49 F=PI*(10.0)
OMEGA=FW*F/PI
JUMEGA=AO*OMEGA
C
C COMPUTE THE WIRE SELF IMPEDANCES
C
LDC=MUD*PI
DELTA=ONE/(FW*PI*DSQRT(SIG+F*MUD*PI))
ALC=ONE/(PI+SIG*AWS*AWS)
IF(AWS*DELTA) GO TO 50
IF(AWS*DELTA) GO TO 51
Z=(M2*(AWS/DELTA+HRC)*RDC+JUMEGA*(JNPT5-PI*AWS/DELTA)*LDC)/NS
GO TO 52
50 Z=(LDC+JUMEGA*LDC)/NS
GO TO 52
51 Z=(M2*AWS*LDC/DELTA+JUMEGA*FW*DELTA*LDC/AWS)/NS
C
C COMPUTE THE EIGENVALUES AND THE EIGENVECTORS OF THE PRODUCT YZ
C (STORE THE EIGENVECTORS AS COLUMNS OF ARRAY T AND THE EIGENVALUES
C IN ARRAY U)
C
52 OMEGA=OMEGA*EMFOW
DO 53 I=1,N
DO 53 J=1,N
53 A(I,J)=OMEGA*(Z*(V3(I)+L(I,J))-OM2*CO(I,J))
CALL FLOCC(A,N,N,N2,N3,N4,N5,N6,N7)
L=LEF-120
IF(L=0) L=1
C
C COMPUTE THE INVERSE OF THE TRANSFORMATION MATRIX, T
C (STORE THE INVERSE IN ARRAY II)
C
DO 54 I=1,N
DO 54 J=1,N
A(I,J)=I(I,J)
54 I2(I,J)=ALCL
55 I2(I,I)=ALCL
CALL FLOCC(A,N,N,N1,N2,N3,N4,N5,N6,N7)

```

```

FLATP245
FLATP246
FLATP247
FLATP248
FLATP249
FLATP250
FLATP251
FLATP252
FLATP253
FLATP254
FLATP255
FLATP256
FLATP257
FLATP258
FLATP259
FLATP260
FLATP261
FLATP262
FLATP263
FLATP264
FLATP265
FLATP266
FLATP267
FLATP268
FLATP269
FLATP270
FLATP271
FLATP272
FLATP273
FLATP274
FLATP275
FLATP276
FLATP277
FLATP278
FLATP279
FLATP280
FLATP281
FLATP282
FLATP283
FLATP284
FLATP285
FLATP286
FLATP287
FLATP288
FLATP289
FLATP290
FLATP291
FLATP292
FLATP293
FLATP294
FLATP295
FLATP296
FLATP297
FLATP298
FLATP299
FLATP300
FLATP301
FLATP302
FLATP303
FLATP304
FLATP305

```

```

      MER=MER-126
      IF(MER.EQ.1) MER=0
      COMPUTE THE TERMINAL VOLTAGES
      FORM THE EQUATIONS
      DO 55 I=1,N
      SU=ZEROD
      SL=ZEROD
      DO 57 J=1,N
      SUMU=ZEROC
      SUML=ZEROC
      DO 56 K=1,N
      SUMU=SUMU+M1(I,K)*T(K,J)
56  SUML=SUML+M2(I,K)*T(K,J)
      SU=SU+T1(I,J)*V1(J)
      SL=SL+T1(I,J)*V2(J)
      A(I,J)=SUMU
57  P(I,J)=SUML
      IO(I)=SU
      IL(I)=SL
      IF(OPTION.EQ.11.OR.OPTION.EQ.12) IL(I)=-IL(I)
      GAM=LOGSURT(D(I))
      EPP=CEXP(GAM*L)*PD
      ENN=CEXP(-GAM*L)*PD
      EP(I)=EPP+ENN
      EN(I)=EPP-ENN
      G(I)=GAM/JLMEGA
      IF(OPTION.EQ.11.OR.OPTION.EQ.12) G(I)=ONFC/G(I)
58  CONTINUE
      DO 60 I=1,N
      DO 60 J=1,N
      SUMU=ZEROC
      SUML=ZEROC
      DO 59 K=1,N
      SUMU=SUMU+T1(I,K)*A(K,J)
59  SUML=SUML+T1(I,K)*P(K,J)
      YU(I,J)=SUMU
60  YL(I,J)=SUML
      DO 61 I=1,N
      SU=ZEROC
      SL=ZEROC
      DO 62 J=1,N
      DO 61 K=1,N
61  SL=SL+YL(I,K)*G(K)*EN(K)*YU(K,J)
      A(I,J)=SL+YL(I,J)*EP(J)+YU(I,J)*P(I)
62  SU=SU+YL(I,J)*G(J)*EN(J)*IO(J)
      W(I,J)=A(I,J)+EN(I)/G(I)
63  C(I)=SU+EP(I)*IO(I)+IL(I)
      SOLVE THE EQUATIONS
      CALL LEWTIC(A,N,N,D,1,N,UM,IA,IB)
      IER=IER-126
      IF(IER.EQ.1) IER=0
      WRITE(6,64) I,IER
64  FORMAT(12X,' FREQUENCY(MER12)= ',IPE11.4,1CX,' SOLUTION ERROR= ',
      12X,12/)
      WRITE(6,65) IER,WK(I)
65  FORMAT(' EIGEN SOLUTION ERROR= ',12X,' EIGEN SOLUTION PRECISION= ',FLATP306
      FLATP307
      FLATP308
      FLATP309
      FLATP310
      FLATP311
      FLATP312
      FLATP313
      FLATP314
      FLATP315
      FLATP316
      FLATP317
      FLATP318
      FLATP319
      FLATP320
      FLATP321
      FLATP322
      FLATP323
      FLATP324
      FLATP325
      FLATP326
      FLATP327
      FLATP328
      FLATP329
      FLATP330
      FLATP331
      FLATP332
      FLATP333
      FLATP334
      FLATP335
      FLATP336
      FLATP337
      FLATP338
      FLATP339
      FLATP340
      FLATP341
      FLATP342
      FLATP343
      FLATP344
      FLATP345
      FLATP346
      FLATP347
      FLATP348
      FLATP349
      FLATP350
      FLATP351
      FLATP352
      FLATP353
      FLATP354
      FLATP355
      FLATP356
      FLATP357
      FLATP358
      FLATP359
      FLATP360
      FLATP361
      FLATP362
      FLATP363
      FLATP364
      FLATP365
      FLATP366

```

```

11PE10.3/)
WRITE(6,66) MEK
66 FORMAT(' TRANSFORMATION MATRIX INVERSION ERROR= ',I2//)
WRITE(6,67)
67 FORMAT(16X,'WIRE',5X,'VUM(VOLTS)',3X,'VOA(DEGREES)',8X,
1'VLM(VOLTS)',5X,'VLA(DEGREES)')//)
C
C
C
COMPUTE AND PRINT THE TERMINAL VOLTAGES
DO 64 I=1,N
SO=ZEROC
DO 68 J=1,N
66 SO=SO+YU(I,J)*B(J)
69 G(I)=-G(I)*CN(I)+I0(I)+EP(I)*B(I)+G(I)*FN(I)*SO
IF(UP1UN.EQ.21.OR.UPT1UN.EQ.22) GO TO 74
DO 71 I=1,N
SL=ZEROC
60 SL=SL+YL(I,J)*G(J)
70 YU(I,I)=I0(I)+SO
71 YL(I,I)=-IL(I)+SL
DO 73 I=1,N
SU=ZEROC
SL=ZEROC
61 SU=SU+I(I,J)*YU(J,J)
72 SL=SL+I(I,J)*YL(J,J)
P(I,I)=0
73 A(I,I)=L
GO TO 77
74 DO 76 I=1,N
SU=ZEROC
SL=ZEROC
DO 75 J=1,N
SU=SU+I(I,J)*B(J)
75 SL=SL+I(I,J)*G(J)
P(I,I)=SO
76 A(I,I)=L
77 DO 80 I=1,N
SU=ZEROC
SL=ZEROC
DO 78 J=1,N
SU=SU+O1(I,J)*P(J,J)
78 SL=SL+O1(I,J)*A(J,J)
VO=SO
VL=SL
VUM=CDABS(VU)
VLA=CDABS(VL)
VCR=UREAL(VU)
VCI=UIMAG(VU)
VLR=UREAL(VL)
VLI=UIMAG(VL)
IF(VCR.EQ.ZERO.AND.VCI.EQ.ZERO) VOR=ONE
IF(VLR.EQ.ZERO.AND.VLI.EQ.ZERO) VLR=ONE
VLA=ATAN2(VCI,VCR)*ONE/PI
VLA=ATAN2(VLI,VLR)*ONE/PI
WRITE(6,77) I,VUM,VOA,VLM,VLA
77 FORMAT(16X,I2,5X,IPE10.3,3X,IPE10.3,10X,IPE10.7,3X,IPE10.3/)
80 CONTINUE

```

```

FLATP367
FLATP368
FLATP369
FLATP370
FLATP371
FLATP372
FLATP373
FLATP374
FLATP375
FLATP376
FLATP377
FLATP378
FLATP379
FLATP380
FLATP381
FLATP382
FLATP383
FLATP384
FLATP385
FLATP386
FLATP387
FLATP388
FLATP389
FLATP390
FLATP391
FLATP392
FLATP393
FLATP394
FLATP395
FLATP396
FLATP397
FLATP398
FLATP399
FLATP400
FLATP401
FLATP402
FLATP403
FLATP404
FLATP405
FLATP406
FLATP407
FLATP408
FLATP409
FLATP410
FLATP411
FLATP412
FLATP413
FLATP414
FLATP415
FLATP416
FLATP417
FLATP418
FLATP419
FLATP420
FLATP421
FLATP422
FLATP423
FLATP424
FLATP425
FLATP426
FLATP427

```

GO TO 4b  
E1 STOP  
END

FLATP428  
FLATP429  
FLATP430

16

TABLE D-1

Changes in FLATPAK2 to Convert  
to Single Precision Arithmetic

Delete Card 051

<u>Card Number</u>	<u>Double</u>	<u>Single</u>
053	REAL *8	REAL
055	COMPLEX *16	COMPLEX
059	3.141592653D0	3.1415926E0
059	2.997925D8	2.997925E8
060-062	change all D's	to E's
064	DCMPLX(0.D0,0.D0)	CMPLX(0.E0,0.E0)
065	DCMPLX(1.D0,0.D0)	CMPLX(1.E0,0.E0)
066	DCMPLX(0.D0,1.D0)	CMPLX(0.E0,1.E0)
132	DREAL	REAL
133	DREAL	REAL
262	DREAL	REAL
275	DSQRT	SQRT
329	CDSQRT	CSQRT
330	CDEXP	CEXP
331	CDEXP	CEXP
415	CDABS	CABS
416	CDABS	CABS
417	DREAL	REAL
418	DIMAG	AIMAG
419	DREAL	REAL
420	DIMAG	AIMAG



Card Number

Double

Single

423

DATAN2

ATAN2

424

DATAN2

ATAN2

6

APPENDIX E

NROOT

Subroutine Listing



6 A(R)-A(R)  
PELUS  
EGL

NK00T062  
NK00T063  
NK00T064

TABLE E-1

Changes in NROOT to Convert  
to Single Precision Arithmetic

<u>Card Number</u>		<u>Double</u>		<u>Single</u>
002		REAL *8		REAL
003	change all	D's	to	E's
016		DSQRT		SQRT
016		DABS		ABS

876

APPENDIX F

EIGEN

Subroutine Listing

```

SUBROUTINE EIGEN(M,N,MM,MA)
DIMENSION A(M,N),Z(M),Y(M),X(M),ETNXZ,CLSX,CLSXZ,
1 FANC=1000-12
IF(M=N) GOTO 2
2 A=0
DO 4 J=1,N
DO 4 I=1,M
A(I,J)=0
4 F(I)=Z(I)
IF(I=1) GOTO 5
5 A(I,I)=A(I,I)+A(I,I)*A(I,I)
6 A(I,I)=A(I,I)+A(I,I)*A(I,I)
7 A(I,I)=A(I,I)+A(I,I)*A(I,I)
8 A(I,I)=A(I,I)+A(I,I)*A(I,I)
9 A(I,I)=A(I,I)+A(I,I)*A(I,I)
10 A(I,I)=A(I,I)+A(I,I)*A(I,I)
11 A(I,I)=A(I,I)+A(I,I)*A(I,I)
12 A(I,I)=A(I,I)+A(I,I)*A(I,I)
13 A(I,I)=A(I,I)+A(I,I)*A(I,I)
14 A(I,I)=A(I,I)+A(I,I)*A(I,I)
15 A(I,I)=A(I,I)+A(I,I)*A(I,I)
16 A(I,I)=A(I,I)+A(I,I)*A(I,I)
17 A(I,I)=A(I,I)+A(I,I)*A(I,I)
18 A(I,I)=A(I,I)+A(I,I)*A(I,I)
19 A(I,I)=A(I,I)+A(I,I)*A(I,I)
20 A(I,I)=A(I,I)+A(I,I)*A(I,I)
21 A(I,I)=A(I,I)+A(I,I)*A(I,I)
22 A(I,I)=A(I,I)+A(I,I)*A(I,I)
23 A(I,I)=A(I,I)+A(I,I)*A(I,I)
24 A(I,I)=A(I,I)+A(I,I)*A(I,I)
25 A(I,I)=A(I,I)+A(I,I)*A(I,I)
26 A(I,I)=A(I,I)+A(I,I)*A(I,I)
27 A(I,I)=A(I,I)+A(I,I)*A(I,I)
28 A(I,I)=A(I,I)+A(I,I)*A(I,I)
29 A(I,I)=A(I,I)+A(I,I)*A(I,I)
30 A(I,I)=A(I,I)+A(I,I)*A(I,I)
31 A(I,I)=A(I,I)+A(I,I)*A(I,I)
32 A(I,I)=A(I,I)+A(I,I)*A(I,I)
33 A(I,I)=A(I,I)+A(I,I)*A(I,I)
34 A(I,I)=A(I,I)+A(I,I)*A(I,I)
35 A(I,I)=A(I,I)+A(I,I)*A(I,I)
36 A(I,I)=A(I,I)+A(I,I)*A(I,I)
37 A(I,I)=A(I,I)+A(I,I)*A(I,I)
38 A(I,I)=A(I,I)+A(I,I)*A(I,I)
39 A(I,I)=A(I,I)+A(I,I)*A(I,I)
40 A(I,I)=A(I,I)+A(I,I)*A(I,I)
41 A(I,I)=A(I,I)+A(I,I)*A(I,I)
42 A(I,I)=A(I,I)+A(I,I)*A(I,I)
43 A(I,I)=A(I,I)+A(I,I)*A(I,I)
44 A(I,I)=A(I,I)+A(I,I)*A(I,I)
45 A(I,I)=A(I,I)+A(I,I)*A(I,I)
46 A(I,I)=A(I,I)+A(I,I)*A(I,I)
47 A(I,I)=A(I,I)+A(I,I)*A(I,I)
48 A(I,I)=A(I,I)+A(I,I)*A(I,I)
49 A(I,I)=A(I,I)+A(I,I)*A(I,I)
50 A(I,I)=A(I,I)+A(I,I)*A(I,I)
51 A(I,I)=A(I,I)+A(I,I)*A(I,I)
52 A(I,I)=A(I,I)+A(I,I)*A(I,I)
53 A(I,I)=A(I,I)+A(I,I)*A(I,I)
54 A(I,I)=A(I,I)+A(I,I)*A(I,I)
55 A(I,I)=A(I,I)+A(I,I)*A(I,I)
56 A(I,I)=A(I,I)+A(I,I)*A(I,I)
57 A(I,I)=A(I,I)+A(I,I)*A(I,I)
58 A(I,I)=A(I,I)+A(I,I)*A(I,I)
59 A(I,I)=A(I,I)+A(I,I)*A(I,I)
60 A(I,I)=A(I,I)+A(I,I)*A(I,I)

```

376





TABLE F-1

Changes in EIGEN to Convert  
to Single Precision Arithmetic

<u>Card Number</u>		<u>Double</u>		<u>Single</u>
002		REAL *8		REAL
004	change all	D's	to	E's
005		1.0D-12		1.0E-6
024		DSQRT		SQRT
024		DSQRT		SQRT
034		DABS		ABS
039		DSQRT		SQRT
042		DSQRT		SQRT
042		DSQRT		SQRT
044		DSQRT		SQRT